Frequentist and Bayesian Statistics Crash Course for Beginners:

Theory and Applications

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Chapter 0: Preface

# Why Learn Statistics?

The fields of Artificial Intelligence, Machine Learning and Data Science are prevailing in many real-world applications. A crucial part of these fields is to deal with huge amount of data which is produced at an unprecedented rate now a days. This data is used to extract useful information for making future predictions on unseen but similar kind of data.

*Statistics* is the filed that lies at the core of Artificial Intelligence, Machine Learning and Data Science. Statistics is concerned with collecting, analyzing and understanding data. It aims to develop models that are able to make decisions in the presence of uncertainty. Numerous techniques of aforementioned fields make use of statistics. Thus, it is essential to gain knowledge of statistics to be able to design intelligent systems.

# The difference between Frequentist and Bayesian Statistics

This book is dedicated to the techniques for frequentist and Bayesian statistics. These two types of statistical techniques interpret the concept of **probability** in different ways.

According to the frequentist approach, the probability of an event is defined for the repeatable events whose outcomes are random. The statistical experiment is run again and again in a long-run to get the probability of the event. Thus, the probability of an event equals to the long-term **frequency** of occurrence of that event.

For example, rolling a six-sided dice can be considered as a repeatable statistical experiment. The outcome of this experiment can be any number from 1 to 6. Since we do not know what will be the outcome in a particular rolling of the dice, we call it a random outcome. According to the frequentist approach, the chance of getting any particular number from 1 to 6 is equally likely. In other words, the probability of any number is 1/6 or 1 out of 6.

As another example, in a pack of 52 cards, we randomly draw a card. We want to check what is the chance of getting a king. To find the probability of our defined event, getting a king, we count the number of favorable outcomes: 4 out of 52 cards. Thus, the probability of getting a king is obtained by dividing the number of favorable outcomes by total number of possible outcomes: 4/52 = 1/13.

The frequentist way of doing statistics makes use of the data from the current experiment. However, contrary to the frequentist approach, the **Bayesian** approach interprets the probability as a ***degree of belief***. For example, it is believed from some previous experiments that a head is twice as likely to occur than a tail. Now, the probability of having a head would be 2/3 as compared to the probability of getting a tail, i.e., 1/3. This belief before running the experiment is our **prior**belief about the experiment of tossing a coin.

The belief can increase, decrease or even remain the same if we run this experiment again and again. This example shows that Bayesian interpretation of probability makes use of previous runs of the experiment to have a degree of belief about any particular experiment. We shall go into the details of these concepts in subsequent chapters of the book.

# What’s in this Book

This book intends to teach beginners the concepts of statistics using the Python programming language. After completing the book, the readers will learn how to collect, sample, manipulate and analyze data. They will also perform experiments to explore and visualize a given dataset. The book aims to introduce to the reader the techniques for estimation and inference of valuable parameters of the statistical models.

The book follows a very simple approach. It is divided into nine chapters.

Chapter 1 reviews the necessary concepts of Python to implement statistical techniques and carry out experiments with the data. It also highlights Python libraries that are helpful for statistical tasks.

Chapter 2 presents the basic concepts behind probability that is closely related to the frequency of occurrence of a certain event. Probability theory serves as a foundation for statistics and data analysis. Moreover, Bayes theorem is discussed that forms the basis for Bayesian statistics.

Chapter 3 covers the topics of random variables and probability distributions to describe statistical events. Several well-known probability distributions are presented in this chapter.

Chapter 4 provides a succinct introduction to the descriptive statistics which are applicable to both frequentist and Bayesian statistics.

Chapter 5 offers several techniques to explore and visualize discrete and continuous data. Exploratory analysis is performed to reveal features and patterns in the statistical data. The data visualization step is important in any statistical experiment, and is almost always performed before any statistical estimation or inference technique can be applied to the data.

Chapter 6 introduces the techniques used for inferring or drawing conclusions from the statistical data on the basis of evidence.

Chapter 7 presents main tasks performed using frequentist or classical view of statistics. Mostly used statistical techniques are consistent with this view of probability.

Chapter 8 discusses topics in Bayesian statistics that interpret the concept of probability as a degree of belief.

Chapter 9 presents two hands-on projects for the understanding of practical tasks that use statistical data.

# Background for Reading the book

This book aims to describe statistical concepts to the beginners using Python functions and libraries. It is intended for those who do not have any previous knowledge of statistics and programming languages. Though programming knowledge is not a pre-requisite for this book. Nevertheless, a basic background of programming languages especially Python would be helpful in a quick understanding of the ideas presented in this book. Chapter 1 of the book consists of a crash course in Python.

The reader of this book requires a computer equipped with the internet connection to effectively learn the material of this book. Another requirement is to have an elementary knowledge of arithmetic operations such as addition, subtraction, multiplication and division to understand calculations for numerous statistical techniques.

# How to use this book

This book presents a number of techniques to understand statistics and the difference between two major types of statistical techniques: frequentist and Bayesian. To facilitate the reading process, occasionally the book presents three types of box-tags in different colors: **Requirements**, **Further Readings,** and **Hands-on Time**. Examples of these boxes are shown below.

|  |
| --- |
| **Requirements** |
| This box lists all requirements needed to be done before proceeding to the next topic. Generally, it works as a checklist to see if everything is ready before a tutorial. |

|  |
| --- |
| **Further Readings** |
| Here, you will be pointed to some external reference or source that will serve as additional content about the specific **Topic** being studied. In general, it consists of packages, documentations, and cheat sheets. |

|  |
| --- |
| **Hands-on Time** |
| Here, you will be pointed to an external file to train and test all the knowledge acquired about a **Tool** that has been studied. Generally, these files are Jupyter notebooks (.ipynb), Python (.py) files or documents (.pdf). |

The box-tag **Requirements** lists the steps required by the reader after reading one or more topics. **Further Readings** provides relevant references for specific topics to get to know the additional content of the topics. **Hands-on Time** points to practical tools to start working on the specified topics. It is recommended to follow the instructions given in the box-tags to get a better understanding of the topics presented in this book.

In each chapter, several techniques have been explained theoretically as well as through practical examples. Each chapter contains exercise questions that can be used to evaluate the understanding of the concepts explained in the chapters. The Python Jupyter Notebooks and the datasets used in the book are provided in the resources.

It is of utmost importance to practice the statistical techniques using Python. To this end, the chapter 1 of the book provides a crash course on Python. After you get sufficient theoretical background presented in each chapter, it is a good practice to write the code yourself instead of just run the source code provided with this book. The example code is surely helpful in case you are stuck. Furthermore, the readers of the book are highly encouraged to complete the exercise questions given at the end of each chapter. The answers to these questions have been provided as well at the end of the book.

# About the Author



M. Wasim Nawaz has a Ph.D. in Computer Engineering from University of Wollongong, Australia. His main areas of research are Machine Learning, Data Science, Computer Vision and Image Processing. Wasim has over eight years of teaching experience in Computer and Electrical Engineering. He has worked with both private and public sector organizations.

Chapter 1: A quick Introduction to Python for Statistics

This chapter presents a crash course on Python to kick start the statistical techniques using Python. First, the complete installation of Anaconda distribution of Python is described for Windows, Mac OS and Linux operating systems. Second, mathematical operators, functions, control statements and Python data structures are explained with practical examples. Finally, mostly used Python libraries for statistics are presented.

# Installation and Setup of Python Environment

This book utilizes Python 3, the latest release of Python. We may download and install Python from the official website *Python Software Foundation*  <https://www.python.org/download>. However, we have to install libraries and packages separately when we follow the aforementioned installation.

One of the convenient ways to get started is to install Python using Anaconda distribution. Anaconda is a free and open-source distribution that comes with its own package manager. Moreover, it includes multiple libraries for Windows, Linux, and macOS operating systems. Since libraries are included in this distribution, we do not need to install them separately.

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Figure 1.1: Anaconda Installers for Windows, MacOS and Linux Individual Edition.

We download Anaconda Individual Edition from<https://www.anaconda.com/products/individual> as shown in Figure 1.1. We select the proper operating system and its version either 32-bit or 64-bit from the aforementioned link. To install Anaconda and setup Python, the following sections give a step-by-step guide for Windows, Mac OS and Linux.

## 1.1.1 Windows

1. Download the graphical Windows installer from<https://www.anaconda.com/products/individual>
2. Double-click the downloaded file and click continue to start the installation.
3. Answer the prompts on the Introduction, Read Me, and License screens.
4. Click the Install button to install Anaconda in a specified directory (C:\Anaconda3\_Python) directory given in the installation.

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Figure 1.2: Installing Anaconda on Windows.

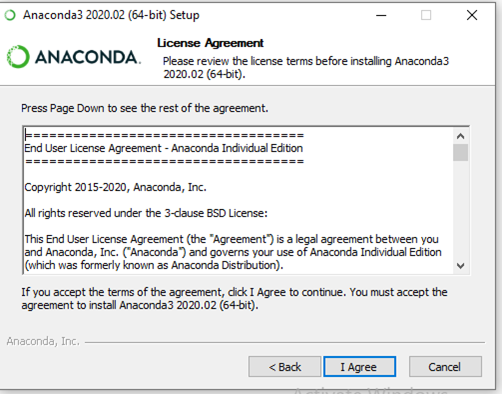
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Figure 1.3: Installing Anaconda on Windows.

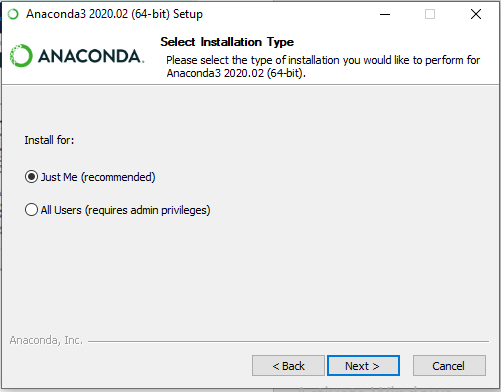
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Figure 1.4: Installing Anaconda on Windows.

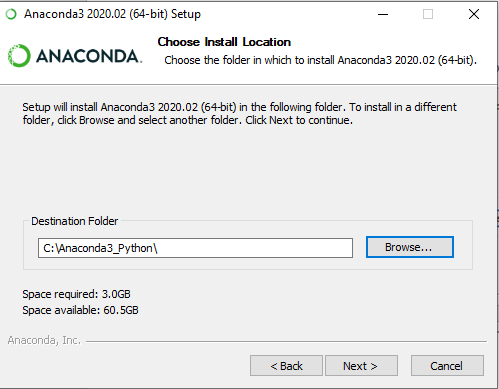
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Figure 1.5: Installing Anaconda on Windows.

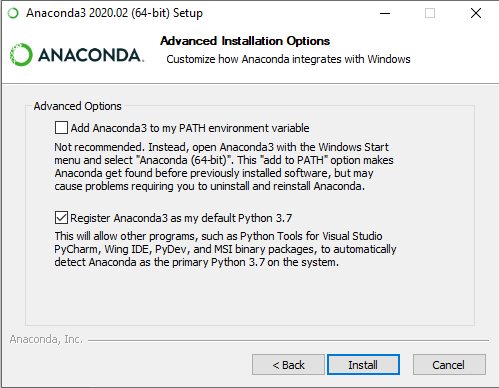
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Figure 1.6: Installing Anaconda on Windows.

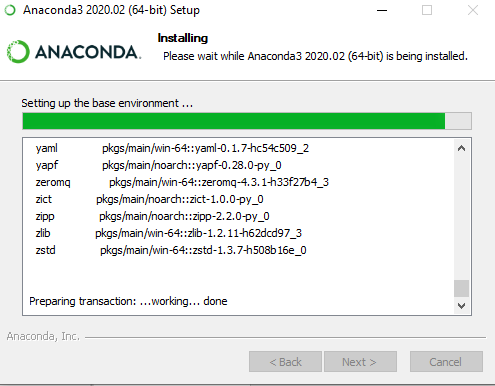
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Figure 1.7: Installing Anaconda on Windows.

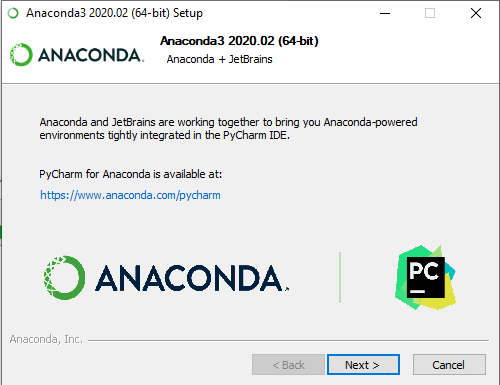
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Figure 1.8: Installing Anaconda on Windows.

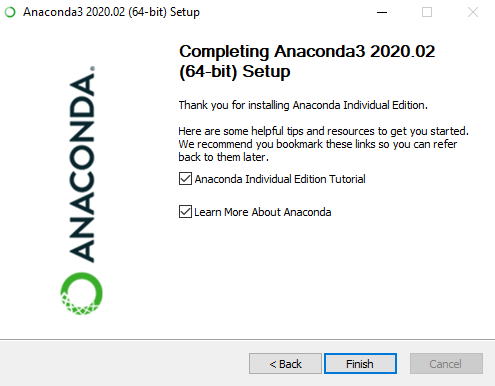
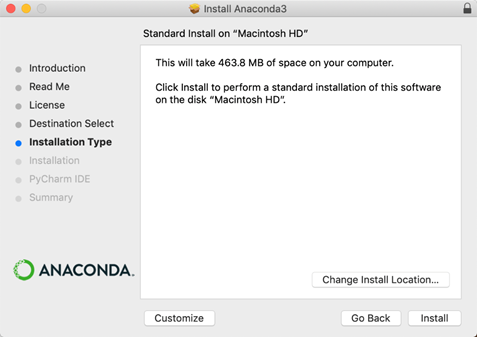
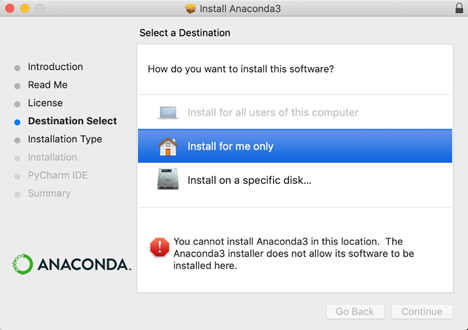
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Figure 1.9: Installing Anaconda on Windows.

## 1.1.2 Apple OS X

1. Download the graphical MacOS installer from<https://www.anaconda.com/products/individual>
2. Double-click the downloaded file and click continue to start the installation.
3. Click the Install button to install Anaconda in the specified directory

****Figure 1.10: Installing Anaconda on Mac OS.

****Figure 1.11: Installing Anaconda on Mac OS.

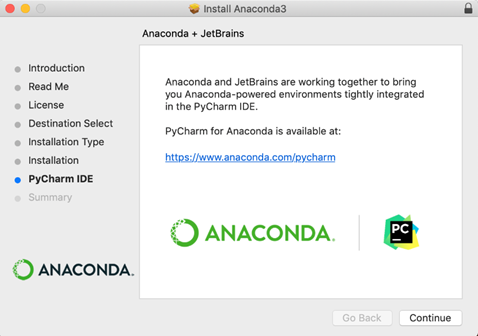
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Figure 1.12: Installing Anaconda on Mac OS.

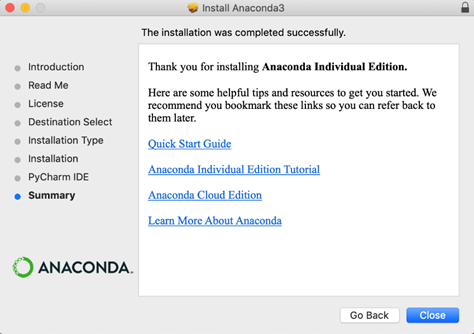
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Figure 1.13: Installing Anaconda on Mac OS.

## 1.1.3 GNU/Linux

Since graphical installation is not available, we use Linux command line to install Anaconda. The copy of the installation file is downloaded from<https://www.anaconda.com/products/individual>

We follow the procedure mentioned below for Anaconda installation on Linux system.

1. Open a copy of Terminal on Linux.
2. Change directories to the downloaded copy of Anaconda on the system.
3. The name of the file normally appears as *Anaconda‐3.7.0‐Linux‐x86.sh* for 32‐bit systems and *Anaconda‐3.7.0‐Linuxx86\_64.sh* for 64‐bit systems. The version number appears in the filename. In our case, the filename refers to version 3.7, which is the version used for this book.
4. Type

bash ~/Downloads/Anaconda3-2020.02-Linux-x86.sh (for the 32‐bit version) or

bash ~/Downloads/Anaconda3-2020.02-Linux-x86\_64.sh (for the 64‐bit version) and press Enter.

1. An installation wizard opens up and asks you to accept the licensing terms for using Anaconda.
2. Accept the terms using the method required for the version of Linux.
3. The wizard asks you to provide an installation location for Anaconda. Choose a location, and click next.
4. The application extraction begins. A completion message pops up once the extraction is complete.

## 1.1.4 Creating and Using Notebooks

Once Python installation is complete, we start exploring its features and writing code to perform tasks. We launch Jupyter Notebook accompanied with Anaconda installation. The Jupyter Notebook is a web application that allows us to create Python code, plots, visualizations and equations. It can be launched by

* the Anaconda Navigator by searching it in *Windows Search Box.* Open Jupyter Notebook as shown in Figure 1.14.
* writing *Jupyter Notebook* in *Windows Search Box* as shown in Figure 1.15.

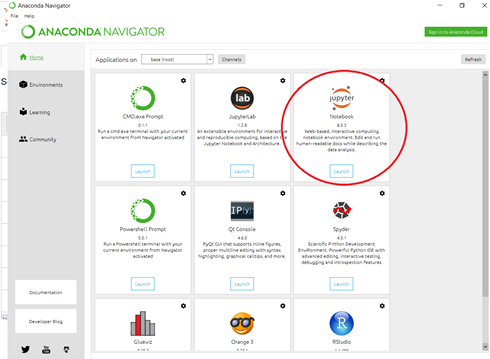
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Figure 1.14: Launching the Jupyter Notebook using Anaconda Navigator.

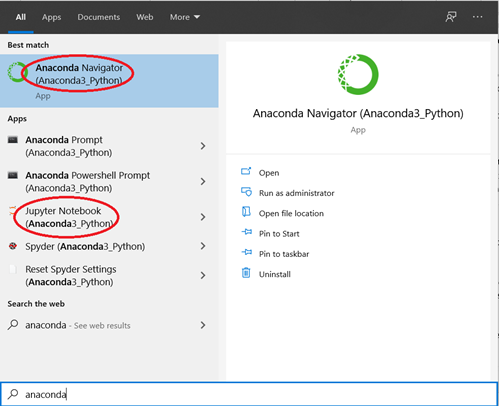
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Figure 1.15: Launching Jupyter Notebook from Windows search box.

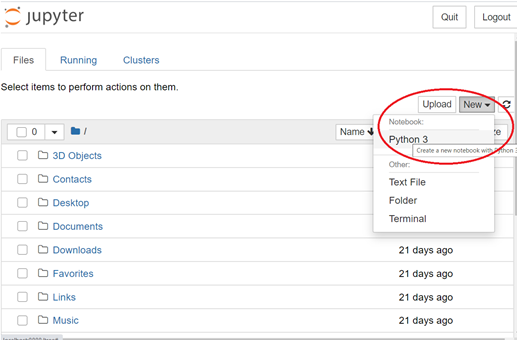
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Figure 1.16: Creating a new Python 3 file in Jupyter Notebook.

Jupyter Notebook opens in a new browser page as shown in Figure 1.16. To create a new notebook, go to New on the top right side of the page and select Python 3.

The box highlighted in the bottom of Figure 1.17 has In [ ]: written next to it. This is the place where we can start typing our Python code. The Notebook can be given a meaningful name by clicking on Untitled1 next to the Jupyter icon in the top left corner of the Notebook. Make sure the highlighted box in the middle of Figure 1.17 is selected to Code.

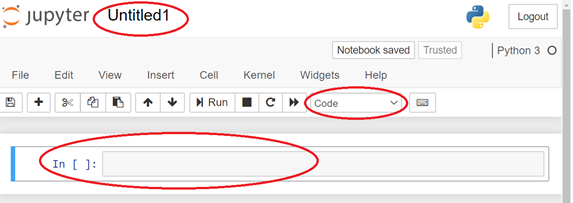
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Figure 1.17: Start working with a Jupyter Notebook.

We are now ready to write our first program. Place the cursor in the cell. Type **print("Hello World")** and click on the Run button on the toolbar. The output of this line of code appears on the next line as shown in Figure 1.18.

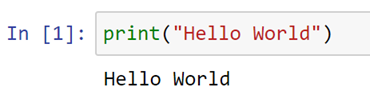
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Figure 1.18: Output of the print statement in Python.

The shortcut to run the code present in a cell is to hit **shift+enter** keys together. Notebook shows the result of running the code right below the cell. A new cell is automatically created for next commands / piece of code to be entered.

Besides code, Jupyter Notebook’s cells can be used to enter text to elaborate the code. For this purpose, we use markdown cells. A markdown cell displays text and mathematical equations formatted using a markdown language. To convert to a markdown cell, we click on cell menu and select Markdown as shown in Figure 1.19. The In [ ] prompt will disappear to signify that the text written in the cell is not an executable Python code.

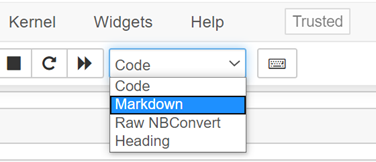


Figure 1.19: A markdown cell

The Python is an interpretable language: The Python code is executed on a Python virtual machine one line at a time. The interpreter acts as a calculator. We can type an expression in the cell and it will return us the output value. The significance of an interpreted language such as Python is that there is abstraction between the code and the platform. This makes Python code portable across different platforms. For example, the same code running on Windows can also run on Linux.

We can download and save a Notebook by clicking on the File drop down menu, selecting Download as and clicking on Notebook (.ipynb) as shown in Figure 1.20. The downloaded files can be used in future by going to the File drop down menu and clicking open.

The code, we generate for the tasks presented in this book resides in a repository on the hard drive of the computer system. A repository is a kind of filing cabinet or folder where we save our code. We can modify and run individual pieces of code within the folder, and add new code to the existing one.

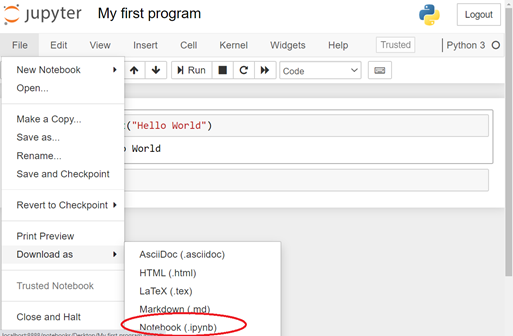
****

Figure 1.20: Saving a Jupyter Notebook for future use.

# Mathematical Operators in Python

Data comes in numerous forms such as numbers, logical values, special symbols and text. Numbers can be integer or floating-point whereas the logical values can be true or false that can be used to make decisions. For example, to find out whether one quantity is greater than another one, we may use logical values.

The arithmetic operators in Python are symbols which are used to perform arithmetic operations for instance addition, subtraction, multiplication and division. Similarly, logical operators are used to perform logical operations. First, we discuss the data types used by Python to represent numbers and logical values. Next, we discuss arithmetic and logical operators.

Python offers numerous data types to represent numbers and logic values; these are given below.

**Integer:** An integer is a whole number without any fractional part. 5 is a whole number; it is an integer. Conversely, 5.0 is not an integer because it has a decimal part. Integers are represented by the data type **int** in Python.

**Float:** A floating-point number contains a decimal part. For example, 3.5 is a floating‐point number. Python stores floating‐point values in the data type **float**.

**Complex:** A complex number comprises of paired numbers: a real number and an imaginary number. The imaginary part of a complex number always appears with a *j*. If we create a complex number with 2 as the real part and 8 as the imaginary part, we make an assignment like this:

|  |
| --- |
| 1. cmplx\_no = 2 + 8j |

**Bool:**Logical arguments require Boolean values represented by data type **bool** in Python. A variable of type bool can either be **True** or **False**. The first letter of both keywords is capital. We can assign a Boolean value to any variable using the keywords True or False as

|  |
| --- |
| 1. x = True 2. type(x) # it returns the type of x as bool. |

Alternatively, to define a bool variable, we create an expression that defines a logical idea. As an example,

|  |  |
| --- | --- |
| 1. bool\_variable = 8 < 4 |  |

returns False because 8 is not smaller than 4.

## 1.2.1 Arithmetic Operators

To perform addition, subtraction, multiplication and division, we use arithmetic operators +, -, \* and /, respectively. Arithmetic operations can be combined using parentheses ( ). To understand the working of these operators, type the following code.

|  |
| --- |
| 1. 3+10-6   **Output:**  7   1. 30-5\*8   **Output:**  -10   1. (30-5\*8)/5   **Output:**  -2   1. 20 / 8  # division returns a floating-point number   **Output:**  2.5 |

The integer numbers, e.g., the number 20 has type int, whereas 2.5 has type float. To get an integer result from division by discarding fractional part, we use the // operator.

|  |
| --- |
| 1. 20 // 6   **Output:**  3 |

To calculate the remainder, we use % operator.

|  |
| --- |
| 1. 20%6   **Output:**  2 |

To calculate powers in Python, we use  \*\* operator.

|  |
| --- |
| 1. 3\*\*4   **Output:**  81 |

Operations involving int and float type operands return the output having the data type float.

|  |
| --- |
| 1. type(5 \* 4.6)   **Output:**  float |

Python supports complex numbers; it uses the suffix j or J to indicate the imaginary part of a complex number. To create a complex number, we type the following command.

|  |
| --- |
| 1. 2+7j   **Output:**  (2+7j) |

## 1.2.2 Bitwise operators

To comprehend bitwise operations, we have to understand how data is stored and processed in computers as binary numbers. A bit is a binary digit 0 or 1. The computer represents every number as a series of 0s and 1s in its memory. For instance, decimal number 5 equals 0000 0101 in binary when we use 8 bits to represent a binary number in a computer.

Negative numbers are represented in computers with a leading 1 on the left side instead of a leading 0. This procedure has two steps:

1. Invert individual bits of the number (this is known as taking 1’s complement of the number). Operator ~ is used to take 1’s complement.
2. Adding a 1 to 1’s complement (this is known as taking 2’s complement of the number).

For example, decimal -4 can be converted to binary by first taking 1’s complement of 4 (0000 0100) that results in 1111 1011 in binary. Now adding a 1 to 1111 1011 results in 1111 1100 that is a binary representation of -4. To take negative of number 4 in Python, we may type.

|  |
| --- |
| 1. # ~4 calculates 1’s complement, 1 is added to it to get 2’s complement or negative of 4. 2. ~4+1   **Output:**  -4 |

Bitwise operators operate on individual bits of the operands. Let the operands be

* x = 3 (0000 0011 in binary) and
* y = 9 (0000 1001 in binary).

We discuss bitwise operators and apply them to the aforementioned operands.

**Bitwise AND** ( & ): It returns 1 if corresponding bits of x and y are 1, otherwise it returns 0.

|  |
| --- |
| 1. x & y   **Output:** 1 |

**Bitwise OR** ( | ): It returns 1 if any of the corresponding bit of x or y is 1, otherwise it returns 0.

|  |
| --- |
| 1. x | y   **Output:**  11 |

**Bitwise NOT** ( ~ ): It returns -(x+1), for a variable x, that is one’s complement of x. In other words, it inverts all the bits of x.

|  |
| --- |
| 1. ~x   **Output:**  -4 |

**Bitwise XOR** ( ^ ): It returns 1 if only one of the corresponding bits of x or y is 1, otherwise it returns 0.

|  |
| --- |
| 1. x ^ y   **Output:**  2 |

**Bitwise right shift** ( >> ): It shifts the bits of the operand towards right by the amount specified in integers on the right side of the operator. Specifying a float on the right side of the operator >>, for example, y>>3.5, gives an error message.

|  |
| --- |
| 1. y >> 2   **Output:**  2 |

**Bitwise left shift** ( << ): It shift the bits of the operand towards left by the amount specified in integers on the left side of the operator. Specifying a float on the right side of the operator <<, for example, y<<3.5, gives an error message.

|  |
| --- |
| 1. x << 2   **Output:**  12 |

## 1.2.3 Assignment Operators

A *variable* is used to store the operands and result of the operations performed on these operands. It can be considered as a container that holds our information. We store our results in a Python Notebook using variables. We make an assignment to a variable to store our data. Various assignment operators supported by Python are given below. The equal sign (=) is used to assign a value to a variable.

|  |
| --- |
| 1. marks1 = 75 2. marks2 = 85 3. marks1 + marks2   **Output:**  160 |

Variable names in Python are case-sensitive. It means that variable name *height* and *Height* are not the same.

If a variable is not assigned any value (not defined), we get an error when we try to use it:

|  |
| --- |
| 1. Marks1   **Output:**  NameError: name 'Marks1' is not defined |

The following code assigns value 10 to my\_var, then adds value 20 to it. Thus, the result stored in my\_var becomes 30.

|  |
| --- |
| 1. my\_var = 10 2. my\_var+=20 3. my\_var   **Output:**  30 |

In the aforementioned code, we have used += as an assignment operator in my\_var+=20 that is equivalent to my\_var=my\_var+20. Other arithmetic operators, such as -, \*, / etc. can be used along with = as assignment operators. For example, try the following code to observe the output.

|  |
| --- |
| 1. my\_var1 = 10 2. my\_var2 = 4 3. my\_var1\*\*=  my\_var2 4. my\_var1   **Output:**  10000 |

## 1.2.4 Logical Operators

Logical operators work on logical operands that can assume one of two values: True and False. The logical operators used in Python are given below.

**Logical** **and**: It returns True only when both the operands are true.

|  |
| --- |
| 1. x=True 2. y=False 3. x **and** y   **Output:**  False |

**Logical** **or**: It returns True if either of the operands is true.

|  |
| --- |
| 1. x=True 2. y=False 3. x **or** y   **Output:**  True |

**Logical** **not:** It complements the operand.

|  |
| --- |
| 1. x=True 2. **not** x   **Output:**  False |

## 1.2.5 Comparison Operators

Comparison operators are used to find relationship between two operands if they are equal or one of the operands is greater than another operand or vice versa. These operators return either True or False, and are extensively employed to make decisions in programming. The details of comparison operators is given below.

Let x = 6 and y = -8 be the operands.

**Equal ==**: It checks if both operands x and y are equal.

|  |
| --- |
| 1. x==y   **Output:**  False |

**Not equal !=**: It checks if both operands x and y are not equal.

|  |
| --- |
| 1. x!=y   **Output:**  True |

**Greater than >:** It checks if one operand is greater than the other operand.

|  |
| --- |
| 1. x > y   **Output:**  True |

**Less than <:** It checks if one operand is smaller than the other operand.

|  |
| --- |
| 1. x < y   **Output:**  False |

**Greater than or equal to >=:** It checks if one operand is greater than or equal to the other operand.

|  |
| --- |
| 1. x >= y   **Output:**  True |

**Less than or equal to <=:** It checks whether one operand is less than or equal to the other operand.

|  |
| --- |
| 1. x <= y   **Output:**  False |

## 1.2.6 Membership Operators

These operators are used to find whether a particular item or set of items are present in a collection or not. The membership operators are **in** and **not in**.

They are used to test whether a value or variable is found in a sequence such as string, list, tuple, set and dictionary. These operators are used in the following example.

|  |
| --- |
| 1. x = 'Hello world' # x is a string of characters 2. **print**('H' **in** x)   # returns True if ‘H’ is in x 3. **print**('Hello' **not** **in** x) # returns True if ‘Hello’ is not present in x   **Output:**  True  False |

# String Operations

Text data includes numbers, alphabets, spaces and special characters such as comma, full stop and colon. Python represents text using *string* data type. It provides us with rich resources to manipulate strings.

Since computers work on binary numbers, they convert string characters into numbers using a standard called *Unicode*. This number is then stored in the memory. For instance, the letter A is converted to its Unicode 65. Type ord("A") in the Jupyter cell, and press Enter to observe 65 as an output. If a decimal number is represented as text, its Unicode value will be different from that number. For example, Unicode for number 9 is 57. In Python, strings are specified either by:

* Enclosing characters in single quotes ('...') or
* Enclosing characters in double quotes ("...")

In Python, a string is an array of bytes representing Unicode characters. A single character is a string with a length of 1. Type the following code to observe the output.

|  |
| --- |
| 'An example string in single quotes.'  **Output:**  'An example string in single quotes.'  "A string in double quotes."  **Output:**  ' A string in double quotes.' |

Multiple strings can be specified and printed using the print statement. A comma is used to separate different strings. Try the following code to print multiple strings.

|  |
| --- |
| **print**( 'Mango', 'and apple', 'are fruits')  **Output:**  Mango and apple are fruits |

We get an error message when we try to print a single quote in a string enclosed in '…'. The same error message is displayed if we try to print a double quote in a string enclosed in “…”.

|  |
| --- |
| **print**('Why don't we visit the museum?')  **Output:**  File "<ipython-input-96-868ddf679a10>", line 1  print(' Why don't we visit the museum?')  ^  SyntaxError: invalid syntax |

To print such characters, we use backslash \, called the escape character.

|  |
| --- |
| 1. **print**('Why don\'t we visit the museum?.')   **Output:**  Why don't we visit the museum? |

The print () function omits the enclosing quotes in the output. Special tasks can be performed using escape characters. For example, \t generates a tab and \n produces a new line within the print statement.

|  |
| --- |
| **print**('Why don\'t we visit \t the museum?')  **Output:**  Why don't we visit the museum?  **print**(' Why don\'t we visit \n the museum?')  **Output:**  Why don't we visit  the museum? |

Suppose we want to display the path of a directory such as *C:\new\_directory* using a print statement. We will get a new line because \n in the directory name produces a new line. To ignore the new line, we use the letter r in the start of directory name as follows:

|  |
| --- |
| **print**(r'c:\new\_directory')  **Output:**  c:\new\_directory |

The operator + can be used to concatenate strings together.

|  |
| --- |
| 1. mystr1 = 'Statistics' 2. mystr2 = ' using' 3. mystr3 = ' Python' 4. mystr1 + mystr2+ mystr3   **Output:**  'Statistics using Python' |

**String Indexing**

The string elements, individual characters or a substring, can be accessed in Python using positive as well as negative indices. Indexing used by Python is shown in Figure 1.21.

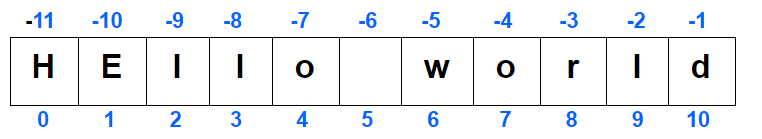


Figure 1.21: Access elements of a string using

positive and negative indices.

Square brackets are used to access string elements. For instance:

|  |
| --- |
| 1. x = "This is a test string" 2. **print**(x[0])   **Output:**  T |

The indices start from 0 in Python. To access last character of the string, we may write

|  |
| --- |
| **print**(x[-1])  **Output:**  g |

A substring can be extracted from a string using indexing. This process is known as **string slicing**. If x is a string, an expression of theform x[i1:i2] returns the x from position i1 to just before i2. A range of indices is specified to access multiple characters of a string.

|  |
| --- |
| 1. **print**(x[0:7])   **Output:**  This is |

The characters of x from index 0 to 6 are returned by the aforementioned statement. The index 7 is not included. To get string characters from a specific index to the last index, we may type the following statement.

|  |
| --- |
| **print**(x[8:len(x)])  **Output:**  a test string |

The string slice begins from the start of the string even if we omit the first index: x[:i2] and x[0:i2] gives the same result.

If we want to get every kth character in the string, we specify a **stride** or a **step** in the string indexing. A stride or a step specifies the size of step between string characters. A stride is set if we add an additional colon in string indexing. For example, to retrieve every second character of the string x starting from index 1 to index 11, we specify a step of 2 as follows:

|  |
| --- |
| 1. x = 'This is a test string' 2. x[1:12:2]   **Output:**  'hsi e' |

If we use a negative stride, we step backward through the string. Negative stride requires the first index to be greater than the second one. To retrieve string characters from the last index to the index 1, we may type the following.

|  |
| --- |
| 1. x = 'This is a test string' 2. x[:0:-2]   **Output:**  'git stas i' |

Note that the first character of string x, T, is not displayed because we have specified a range of indices from end to 1 (index 0 is not included). We get a different output, when we write the following script.

|  |
| --- |
| 1. x = 'This is a test string' 2. x[::-2]   **Output:**  'git stas iT' |

To replicate a string multiple times, we use the operator \*. To generates five copies of the string ‘Hello’, type.

|  |
| --- |
| 1. str = 'Hello  ' \* 5 2. str   **Output:**  'Hello Hello Hello Hello Hello ' |

In Python, strings can be manipulated using numerous built-in methods (functions). The method **strip()** eradicates any whitespace from the beginning or the end of a string.

|  |
| --- |
| 1. str1 = "    This is a text string    " 2. **print**(str1.strip())   **Output:**  This is a text string |

To convert a string to lower case, we use the method **lower().**

|  |
| --- |
| 1. str2 = "This is a text string" 2. **print**(str2.lower())   **Output:**  this is a text string |

To convert a string to upper case, we use the method **upper().**

|  |
| --- |
| 1. str3 = "This is a text string" 2. **print**(str3.upper())   **Output:**  THIS IS A TEXT STRING |

To replace characters of a sting, we use the method **replace()**.

|  |
| --- |
| 1. str4 = "I ate a banana" 2. **print**(str4.replace("banana", "mango"))   **Output:**  I ate a mango |

To break a sting into smaller strings, we use the method **split()** along with a specified separator.

|  |
| --- |
| 1. str5 = 'Hi mate, how do you do?' 2. **print**(str5.split(","))   **Output:**  ['Hi mate', ' how do you do?'] |

In the aforementioned code, we have used a comma as a separator. Other characters can also be specified to serve as separators.

# Conditional Statements and Iterations

Conditional statements are used when we need to make decisions in our program. A block of code is executed only if a certain condition is satisfied, and a different piece of code is run otherwise. Conditional statements provided by Python are:

1. if,
2. elif and
3. else.

**If** statement can be used standalone, but **elif** and **else** are always accompanied by a corresponding **if** statement. We give the details and usage of these statements in the following sections.

## 1.4.1 If, elif and else Statements

If statement is the simplest conditional statement. The syntax, proper arrangement of symbols and keywords to constitute a correct programming command, of an if statement is:

if(condition):

      Statement1

Note that the line following the if(condition): is indented. We may specify more indented statements after the Statement1. Statements indented the same amount after the colon (:) are part of if statement. These statements run when the condition of if statement is True. In case this condition is False, Statement1 and other indented statements will not be executed. Figure 1.22 shows the flowchart of an if statement.

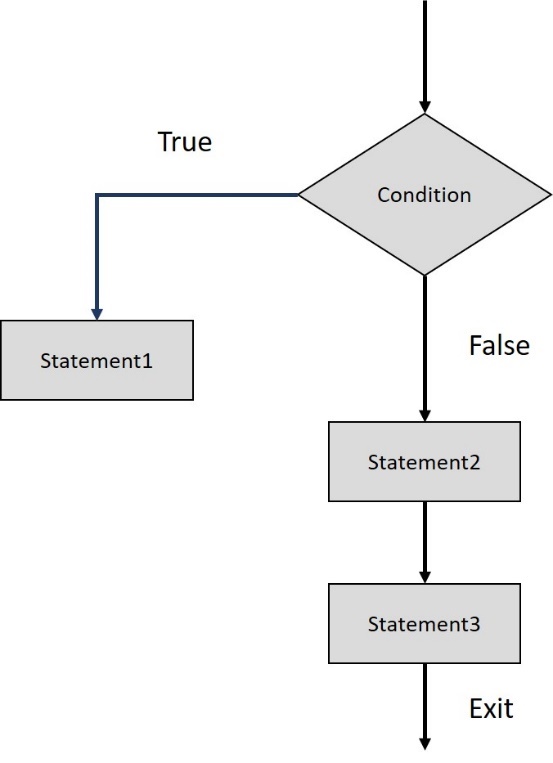
****

Figure 1.22: Flow chart of an if statement.

For instance, we want to record and display the marks of a students obtained in a particular subject. The total marks obtained should not exceed 100. The program should display an error or warning when marks are greater than 100. Python script incorporating an if statement would be as follows.

|  |
| --- |
| 1. student\_marks = 90 2. if(student\_marks > 100): 3. print("Marks exceed 100.") |

The colon (:) after if(student\_marks>100) is important because it separates the condition from the statements. The condition inside if(condition) is evaluated; it returns True if the condition is fulfilled, and False otherwise. Arithmetic, logical and conditional operators can be employed to design a condition.

An input from a user can also be used to form a condition. For instance, a user of the program can be asked to enter student\_marks that can be used inside an if statement.

|  |
| --- |
| 1. print('Enter marks obtained by a student') 2. student\_marks = int(input()) 3. if(student\_marks > 100): 4. print("Marks exceed 100.") |

Note that the input() function gets the input from the user; it saves the input as a string. We use int(input()) to get an integer from the string. If we execute the aforementioned program, and input marks greater than 100, we get a warning "Marks exceed 100". If the entered marks are 100 or less, no warning message is displayed.

**else Statement**

The statement **else** is always accompanied by an accompanying if statement, i.e., **if-else**. The syntax of if-else is given below.

if(condition):

Indented statement(s) when condition is True

else:

Indented statement(s) when condition is False

In our previous examples on student marks, let us display the message “Outstanding”, if student\_marks are 80 or greater.  A message “Not outstanding” is displayed otherwise.

|  |
| --- |
| 1. print('Input marks of a student') 2. student\_marks = int(input()) 3. if(student\_marks >= 80): 4. print("Outstanding") 5. else: 6. print("Not outstanding ") |

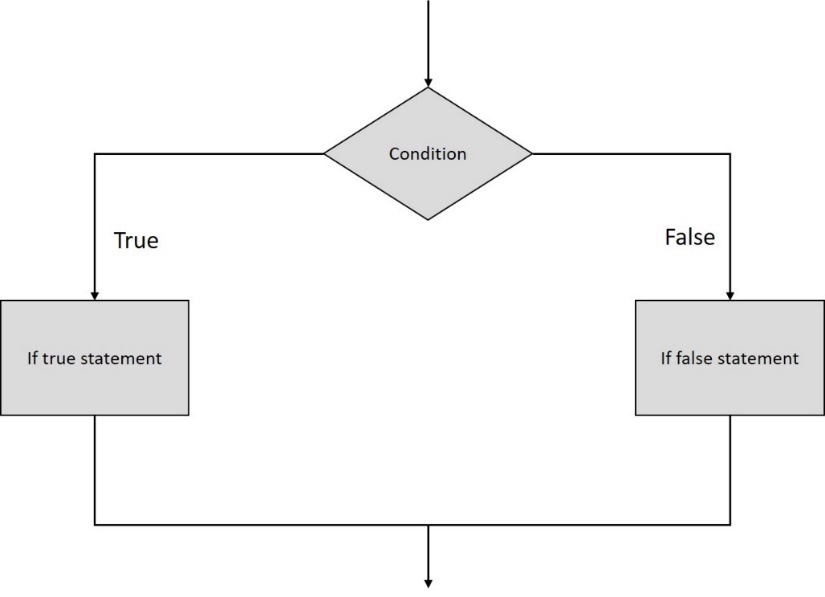


Figure 1.23: Flow chart of an if-else statement.

Figure 1.23 presents the flowchart of an if-else statement. It can be observed that one of two blocks of code will be executed based upon the condition to be evaluated.

**Nested Decisions**

To take decisions under multiple conditions, Python allows us to perform nested decisions. The **if-elif-else** statements are employed to accomplish nested decisions. Continuing with the example of student marks, if the marks of a student are greater than 100 or less than 0, a waring should be displayed. Additionally, if obtained marks are 80 or greater, *Outstanding* should be displayed. Otherwise, *Not outstanding* should be displayed.

|  |
| --- |
| 1. print('Enter marks of a student') 2. student\_marks = int(input()) 3. if(student\_marks > 100 or student\_marks < 0): 4. print("Invalid marks.") 5. elif(student\_marks >= 80): 6. print("Outstanding") 7. else: 8. print("Not outstanding") |

Note that we have a used a logical operator or to combine two conditions together inside the if statement.

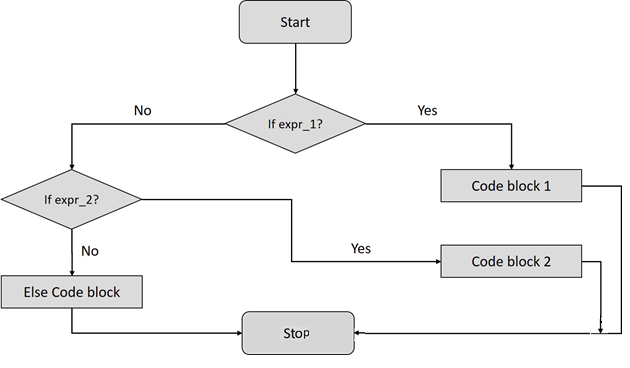


Figure 1.24: Flow chart of an if-elif-else statement.

Figure 1.24 shows the flowchart of an if-elif-else statement. It can be observed that one block of code will be executed based upon the condition to be evaluated.

|  |
| --- |
| **Further Readings** |
| More information about conditional statements can be found at  https://www.techbeamers.com/python-if-else/ |

## 1.4.2 For Loop

Iteration statements provided to us by Python allows to

perform a task more than once. To iterate a task fixed number of times, a for loop is used. For loop has a definite beginning and end. We provide a sequence or a variable to the loop as an input that causes the loop to execute a fixed number of times. The syntax of a for loop is given as.

for loop\_variable in sequence:

Statement(s) to be executed in the for loop

The flow chart of a for loop is given in Figure 1.25.

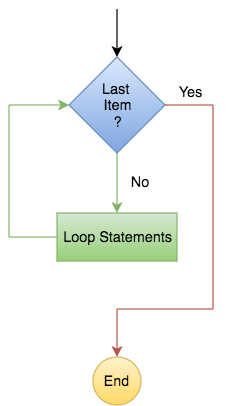
****

Figure 1.25: Flow chart of a for loop.

Note the Statement(s) to be executed in the body of the for loop are indented. The loop\_variable is used inside the for loop, and the number of times the for loop runs depends upon the length of the sequence. To implement the for loop, type the following code.

|  |
| --- |
| 1. subjects = ["Probability", "Statistics", "Machine Learning", "Data Science", "Artificial Intelligence"] 2. for k in subjects: 3. print(k)   Output:  Probability  Statistics  Machine Learning  Data Science  Artificial Intelligence |

In this example, “subjects” is a variable containing 5 items. This is used to decide number of iterations of a for loop. The loop runs 5 times because the number of items in the variable subjects is 5.

The function range() is normally used in a for loop to generate a sequence of numbers. For example, range(5) generates numbers from 0 to 4 (5 numbers). The following code generates the first 5 numbers.

|  |
| --- |
| 1. for k in range(5): 2. print(k)   Output:  0  1  2  3  4 |

We can also specify a step size other than 1 within the range () function as follows.

|  |
| --- |
| 1. for x in range(3, 12, 3): 2. print(x)   Output:  3  6  9 |

In range(3, 12, 3), 3 is the step size. The statements **break** and **continue**are sometimes used inside the loops. The break statement discontinues the execution of the loop. The continue statement skips all the statements of the for loop following the continue statement. The usage of both statements is illustrated in the following example.

|  |
| --- |
| 1. students = ["Adam", "Alice", "Bob", "Emma","Julia"] 3. for k in students: 4. if k == "Bob": 5. continue 6. print(k) 7. if k == "Emma": 8. break   Output:  Adam  Alice  Emma |

The name Bob is not printed in the output because the continue statement is executed when the value of k equals Bob. Note that print(k) statement is not indented with the if statement; thus, it is not part of the if statement. Moreover, the code breaks right after it has printed the name Emma.

## 1.4.3 While Loop

The while loop iteratively runs certain statements until its condition is fulfilled. The syntax of the while loop is given below.

while (condition):

Statement(s) to be executed in the while loop

For instance, to add natural numbers up-to the number input by a user, we use a while loop as follows.

|  |
| --- |
| 1. # This program finds sum of first n natural numbers, where the value of n is input by the user. 3. n = int(input("Input an integer = ")) 5. # initialize variables sum and j (counter) 6. sum = 0 7. j = 1 8. while j <= n: 9. sum = sum + j 10. j = j+1    # update the counter variable 11. print("First", n, "natural numbers add up to ", sum) |

The user of this program is asked to input a natural number upon execution of this program. A sum of 10 is obtained if the number 4 is entered, and a sum of 55 is returned upon entering the number 10. The while loop allows us to use break, continue and else statements inside a while loop like a for loop. Figure 1.26 presents the flow chart of a while loop.

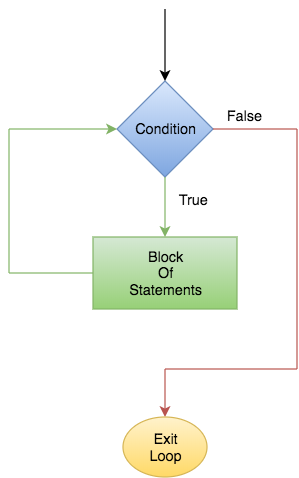
****

Figure 1.26: Flow chart of a while loop.

**Nested Loops**

A loop, either for or while, can be used inside another loop. This is known as nested loops that can be used when we work with the data in 2-dimensions. The following program uses two for loops, one nested inside another, to print all the combinations of two variables.

|  |
| --- |
| 1. attributes = ["heavy", "wooden", "fast"] 2. objects = ["chair", "table", "computer"] 3. for j in attributes: 4. for k in objects: 5. print(j, k)   Output:  heavy chair  heavy table  heavy computer  wooden chair  wooden table  wooden computer  fast chair  fast table  fast computer |

|  |
| --- |
| **Further Readings** |
| More information about iteration statements can be found at  <http://www.lastnightstudy.com/Show?id=84/Python-3-Iteration-Statements>  <https://www.w3schools.com/python/default.asp> |

# Functions in Python

A function is a piece of code that performs a specific task. Functions execute when they are called by their names. Python permits us to define/create functions using the keyword def. For instance, to define a function named as my\_function1, we write the following code.

|  |
| --- |
| 1. **def** my\_function1(): 2. **print**("This is a test function") |

To run this function, we type its name.

|  |
| --- |
| 1. my\_function1()   **Output:**  This is a test function |

A function can accept one or more inputs by passing parameters or arguments inside the braces ( ). For instance, the following function accepts a string as its input.

|  |
| --- |
| 1. **def** my\_function2(str\_in): 2. **print**("This function prints its input that is " + str\_in) 4. my\_function2("computer") 5. my\_function2("table") 6. my\_function2("chair")   **Output:**  This function prints its input that is computer  This function prints its input that is table  This function prints its input that is chair |

If a \* is added before the parameter name while defining the function, an input of variable size can be passed as input / argument to the function. Thus, the function is able to receive multiple inputs. The following function elaborates this idea.

|  |
| --- |
| 1. **def** my\_function3(\*myfruits): 2. **print**(myfruits[2], "is my favorite fruit.") 3. my\_function3("Mango", "Apple", "Orange") # 3 inputs.   **Output:**  Orange is my favorite fruit.   1. my\_function3("Mango", "Orange","Apricot","Apple" ) # 4 inputs.   **Output:**  Apricot is my favorite fruit. |

Data can be returned from a function when we use the return statement as follows.

|  |
| --- |
| 1. **def** mult\_by\_10(k): 2. **return** 10 \* k 3. **print**(mult\_by\_10(2)) 4. **print**(mult\_by\_10(-8)) 5. **print**(mult\_by\_10(100))   **Output:**  20  -80  1000 |

Python allows us to define a function without any name. This is called a **lambda function** (anonymous function) which can receive multiple input arguments, but has only one statement. To define a lambda function, we use

lambda *arguments* : *statement*

To illustrate the creation and use of a lambda function, we may type the following code.

|  |
| --- |
| 1. x = **lambda** input\_number : input\_number - 10 2. **print**(x(10)) 3. **print**(x(-10)) 4. **print**(x(20))     **Output:**  0  -20  10 |

The aforementioned lambda function subtracts 10 from each input number.

# Data Structures

In addition to commonly used data types int, float and str, Python offers data types to store a collection of multiple entries from numbers, alphabets, alphanumeric, strings and special characters. The four commonly used collection data types provided by Python are as follows.

* **List** is a mutable and ordered collection that allows duplicate entries.
* **Tuple** is an immutable and ordered collection that also allows duplicate entries.
* **Set** is an unordered and unindexed collection that, like real sets, prohibits duplicate entries.
* **Dictionary** is a mutable, unordered and indexed collection of entries that prohibits duplicate entries.

The following sections discuss these data types and their usages.

## 1.6.1 Lists

A list is a mutable and ordered collection of elements. Lists are specified using square brackets in Python. For instance, to create a list named item\_list, type the following code.

|  |
| --- |
| 1. item\_list = ["backpack", "laptop", "ball point", "sun glasses"] 2. **print**(item\_list)   **Output:**  ['backpack', 'laptop', 'ball point', 'sun glasses'] |

To access any particular element / item of a list, we refer its index number. For instance, to print the third item of the list, we type the following code.

|  |
| --- |
| 1. **print**(item\_list[2])   **Output:**  ball point |

Since Python permits negative indexing, we can use them to access elements of a list. As an example, the following piece of code prints the third last item of the list.

|  |
| --- |
| 1. item\_list = ["backpack", "laptop", "ball point", "sun glasses"] 2. **print**(item\_list[-3])   **Output:**  laptop |

To return the second and the third list items, we type the following code.

|  |
| --- |
| **print**(item\_list[1:3])    # Elements at index 1 and 2 but not the one at 3.  **Output:**  ['laptop', 'ball point'] |

Try the following, and observe the output

|  |
| --- |
| 1. **print**(item\_list[:3])     # returns list elements from the start to "ball point" 2. **print**(item\_list[2:])     # returns elements from "ball point" to the last element 3. **print**(item\_list[-3:-1])  # returns elements from index -3 to -1 |

The index of a specific element can be used to change the value of that element. For instance, to change the second element of the item\_list, type the following

|  |
| --- |
| 1. item\_list[1] = "computer" 2. **print**(item\_list)   **Output**:  ['backpack', 'computer', 'ball point', 'sun glasses'] |

Conditional statements can be used with a list. The elements of a list can be checked using an if statement and the keyword **in** as follows.

|  |
| --- |
| 1. **if** "sun glasses" **in** item\_list: 2. **print**("sun glasses is present in the list") 3. **else**: 4. **print**("sun glasses is not present in the list")   **Output**:  sun glasses is present in the list |

## 1.6.2 Tuples

A tuple is immutable and ordered collection of items. In Python, tuples are specified using round brackets (). The following code creates a tuple.

|  |
| --- |
| 1. py\_stat = ("Python", "for", "statistics") 2. print(py\_stat)   Output:  ('Python', 'for', 'statistics') |

Elements of a tuple can be accessed using [ ]. For instance:

|  |
| --- |
| 1. print(py\_stat[2])   Output:  statistics |

Similar to lists, we can use negative indexing and a range of indexing. Since tuples are immutable, the values present in a tuple are not changed once it is created. However, we can use loops to go through elements of a tuple. The keyword in can be used to determine if a specified element is present in a tuple. The method len() finds out the number of items present in a tuple. The + operator can be employed to join two or more tuples together. Finally, to delete a tuple, use the statement **del py\_stat.**

The tuple method **count()** returns the number of times a particular value appears in a tuple.

|  |
| --- |
| 1. py\_stat2 = ('Python', 'has support for', 'statistics') 2. print(py\_stat2.count('stat')) 3. print(py\_stat2.count('statistics'))   Output:  0  1 |

The tuple method **index()** is used to search the tuple for a particular value. It returns the position where the specified value is found. For example, type the following code.

|  |
| --- |
| 1. print(py\_stat2.index('Python')) 2. print(py\_stat2.index('probability'))   Output:  2  ValueError: tuple.index(x): x not in tuple |

A ValueError is printed if the value to be indexed for does not exist in the tuple.

## 1.6.3 Sets

A set is an unindexed and unordered collection of items. Python specifies sets using curly brackets { }. For example, type the following code.

|  |
| --- |
| 1. my\_animals = {"cat", "dog", "tiger", "fox"} 2. **print**(my\_animals)   **Output:**  {'dog', 'tiger', 'cat', 'fox'} |

No index is linked to set items because sets are unordered. Nevertheless, a loop can be used to go through the set elements.

|  |
| --- |
| 1. my\_animals = {"cat", "dog", "tiger", "fox"} 2. **for** x **in** my\_animals: 3. **print**(x)     **Output:**  dog  cat  tiger  fox |

The printed output follows no order. The keyword in is used to check if a particular value is present in a set.

|  |
| --- |
| 1. **print**("tiger" **in** my\_animals) 2. **print**("lion" **in** my\_animals)   **Output:**  True  False |

Once a set is created, its elements cannot be changed. But, new elements can be added. The method **add()**  adds a single element to a set.

|  |
| --- |
| 1. my\_animals = {"cat", "dog", "tiger", "fox"} 2. my\_animals.add("lion") 3. **print**(my\_animals)   **Output:**  {'lion', 'cat', 'tiger', 'dog', 'fox'} |

The output of the aforementioned program displays items without any order. The method **update()** adds multiple elements to a set.

|  |
| --- |
| 1. my\_animals = {"cat", "dog", "tiger", "fox"} 2. my\_animals.update(["sheep", "goat", "sheep"]) 3. **print**(my\_animals)   **Output:**  {'cat', 'tiger', 'dog', 'goat', 'sheep', 'fox'} |

The item 'sheep' appears once in the output because sets do not allow duplicate entries. To find the number of elements of a set, we use the method **len(my\_animals)**.

To remove an element in a set, we use either the method **remove()** or the method **discard().** For instance, we remove "tiger" as follows.

|  |
| --- |
| 1. my\_animals = {"cat", "dog", "tiger", "fox"} 2. my\_animals.remove("tiger") 3. **print**(my\_animals)   **Output:**  {'dog', 'cat', 'fox'} |

Two or more sets can be joined together using the method **union().** Alternatively, the method **update()** can be used to insert elements from one set into another. Let us try the following code.

|  |
| --- |
| 1. myset1 = {"X", "Y" , "Z"} 2. myset2 = {4, 5, 6} 3. myset3 = myset1.union(myset2) 4. **print**(myset3)   **Output:**  {4, 5, 6, 'Y', 'X', 'Z'} |

Moreover, the method **pop( )** removes the last item from a set. The method **clear ( )** empties the set, and the keyword **del** before the name of the set deletes the set completely.

## 1.6.4 Dictionaries

A dictionary is a mutable, unordered and indexed collection of items. A dictionary in Python has a key:value pair for each of its elements. Dictionaries retrieve values when the keys are known. To create a dictionary, we use curly braces { }, and put key:value elements inside these braces where each pair is separated from others by commas. For example, the following piece of code creates a dictionary named py\_stat\_dict.

|  |
| --- |
| 1. py\_stat\_dict = { 2. "name": "Python", 3. "purpose": "Statistics", 4. "year": 2020 5. } 6. **print**(py\_stat\_dict)   **Output:**  {'name': 'Python', 'purpose': Statistics', 'year': 2020} |

The dictionaries require the keys to be unique and immutable string, number or tuple. The values, on the other hand, can be of any data type and can repeat. Square brackets are used to refer to a key name to access a specified value of a dictionary.

|  |
| --- |
| 1. **print**(py\_stat\_dict['name'])    # accesses value for key 'name' 2. **print**(py\_stat\_dict.get('purpose'))  # accesses value for key 'purpose'   **Output:**  Python  Statistics |

A message: *None* is displayed if we try to access a non-existent key.

|  |
| --- |
| **print**(py\_stat\_dict.get('address'))  **Output:**  None |

We get the error: **KeyError: 'address'** to indicates that the key 'address' does not exist, when we run print(py\_stat\_dict['address']). The value of an element can be changed by referring to its key as shown below.

|  |
| --- |
| 1. py\_stat\_dict["year"] = 2019 2. py\_stat\_dict   **Output:**  {'name': 'Python', 'purpose': 'Statistics', 'year': 2019} |

A for loop can be used to go through a dictionary; it returns *keys* of the dictionary.

|  |
| --- |
| 1. **for** k **in** py\_stat\_dict: 2. **print**(k)   **Output:**  name  purpose  year |

The values can be returned as well.

|  |
| --- |
| 1. **for** k **in** py\_stat\_dict: 2. print(py\_stat\_dict[k])   **Output:**  Python  Statistics  2019 |

The same output is obtained when we use the following.

|  |
| --- |
| 1. **for** k **in** py\_stat\_dict.values(): 2. print(k) |

To access both keys and values together, we use the method **items()** as follows.

|  |
| --- |
| 1. **for** x, y **in** py\_stat\_dict.items(): 2. print(x, y)   **Output:**  name Python  purpose Statistics  year 2019 |

To check if a key exists within a dictionary, we employ a conditional if statement.

|  |
| --- |
| 1. **if** "year" **in** py\_stat\_dict: 2. **print**("'year' is one of the valid keys")   **Output:**  'year' is one of the valid keys |

To add a new element to a dictionary, a new key is used and a value is assigned to this key as given below.

|  |
| --- |
| 1. py\_stat\_dict["pages"] = 300 2. **print**(py\_stat\_dict)   **Output:**  {'name': 'Python', 'purpose': 'Statistics', 'year': 2019, 'pages': 300} |

To remove a specific element, the method **pop()** can be used.

|  |
| --- |
| 1. py\_stat\_dict.pop("year")  # del py\_stat\_dict["year"] does the same job. 2. **print**(py\_stat\_dict)   **Output:**  {'name': 'Python', 'purpose': 'Data science', 'pages': 300} |

The keyword del removes the whole dictionary when we use **del py\_stat\_dict**. The method **clear()** deletes all elements of a dictionary.

|  |
| --- |
| 1. py\_stat\_dict.clear() 2. py\_stat\_dict   **Output:**  { } |

The method **len(dictionay\_name)** is used to print the number of key:value pairs present in the dictionary.

|  |
| --- |
| 1. py\_stat\_dict = { 2. "name": "Python", 3. "purpose": "Statistics", 4. "year": 2020 5. } 6. **print**(len(py\_stat\_dict))   **Output:**  3 |

A dictionary cannot be copied by a simple assignment such as **py\_stat\_dict2 = py\_stat\_dict.** It is because py\_stat\_dict2 is just a reference to the original dictionary py\_stat\_dict. Whatever changes are made to py\_stat\_dict, are automatically made to py\_stat\_dict2 as well. To copy the elements of a dictionary, we use the method **copy()** as follows.

|  |
| --- |
| 1. py\_stat\_dict2 = py\_stat\_dict.copy() 2. **print**(py\_stat\_dict) 3. **print**(py\_stat\_dict2)   **Output:**  {'name': 'Python', 'purpose': 'Data science', 'year': 2020}  {'name': 'Python', 'purpose': 'Data science', 'year': 2020} |

|  |
| --- |
| Further Reading |
| A detailed tutorial on Python is given in <https://docs.python.org/3/tutorial/>  <https://www.w3schools.com/python/default.asp> |

# 1.7 Python Libraries for Statistics

The Anaconda distribution of Python includes suitable packages and libraries that can readily be used for statistical tasks. The following libraries will be used throughout this book.

1. NumPy for mathematical functions,
2. Pandas for data processing,
3. Statistics: Python’s built-in module for Statistical functions ,
4. Matplotlib for visualization and plotting
5. SciPy.stats module for basic and advanced statistical functions,
6. Statsmodels for statistical models ,
7. PyMC for Bayesian modeling and inference.

All except PyMC library are pre-installed in Anaconda distribution. We shall discuss the installation of the PyMC in Section 1.7.7. The details of these libraries are given in the following sections.

## 1.7.1 NumPy for Mathematical Functions

NumPy, or Numerical Python, is a Python library that supports multi-dimensional arrays and matrices. It provides a sizable collection of fast numeric functions to work with these arrays and to perform operations of linear algebra on them.

In most programming languages including Python *arrays* are used to store multiple values in a variable. An array is a variable that is able to hold several values. Arrays are commonly used to store statistical data. In standard Python, lists are used as arrays; however, lists are slow to work with. In case, speed is an important factor, we use NumPy’s array object, also called **ndarray,** that is significantly faster than a list.

To create and use ndarrays, we first need to import the NumPy library. Often, we use alias to refer to the name of different libraries. NumPy is usually replaced with its defined alias np. To create NumPy arrays, we type the following code.

|  |
| --- |
| 1. **import** numpy as np 2. my\_arr0 = np.array(20) 3. my\_arr1 = np.array([10, 20, 30, 40, 50]) 4. print(my\_arr0) 5. print(my\_arr1)   **Output:**  20  [10 20 30 40 50] |

The scalar values are considered as 0-dimensional arrays. An array of scalar or 0-dimensional values is called as a 1-dimensional array. The variable my\_arr0 in the aforementioned program is a 0-dimensional array, whereas variable my\_arr1 is a 1-dimensional array.

We can create a 2-dimensional array by placing 1-dimensional arrays as elements of another array. A 2-dimensional array is used to store and process matrices.

|  |
| --- |
| 1. **import** numpy as np 2. my\_arr2 = np.array([[10, 20, 30, 40], [90, 80, 70, 60]]) 3. print(my\_arr2)   **Output:**  [[10 20 30 40]  [90 80 70 60]] |

In the above-mentioned example, a matrix of 2 rows and 4 columns is created. We can also create 3 or higher dimensional NumPy arrays as follows:

|  |
| --- |
| 1. import numpy as np 2. my\_arr3 = np.array([[[10, 20, 30], [40, 50, 60]], [[70, 80, 90], [100, 110, 120]]]) 3. print(my\_arr3)   **Output:**  [[[ 10 20 30]  [ 40 50 60]]  [[ 70 80 90]  [100 110 120]]] |

This code generates two matrices of 2 rows and 3 columns each. The following program uses a few of the NumPy mathematical functions on arrays.

|  |
| --- |
| 1. **import** numpy as np 3. a = np.array([1,2,3]) 4. b= np.array([4,5,6]) 6. **print**("Addition of a and b :",np.add(a,b)) 8. **print**("Multiplication of a and b :",np.multiply(a,b)) 10. **print**("Subtraction of a and b :",np.subtract(a,b)) 12. **print**("division of a and b :",np.divide(a,b)) 14. **print**("a raised to b is:",np.power(a,b)) 16. **print**("mod of a and b :",np.mod(a,b)) 18. **print**("remainders when a/b :",np.remainder(a,b)) 20. a = np.array([3.33,4.55,5.25]) 22. rounded\_a = np.round\_(a,2) 23. **print**("Rounded array is: ",rounded\_a) 25. floor\_a = np.floor(a) 26. **print**("Floor of the array is: ",floor\_a) 28. **print**("Square root of the array is: ",np.sqrt(a))   **Output:**  Addition of a and b : [5 7 9]  Multiplication of a and b : [ 4 10 18]  Subtraction of a and b : [-3 -3 -3]  division of a and b : [0.25 0.4 0.5 ]  a raised to b is: [ 1 32 729]  mod of a and b : [1 2 3]  remainders when a/b : [1 2 3]  Rounded array is: [3.33 4.55 5.25]  Floor of the array is: [3. 4. 5.]  Square root of the array is: [1.82482876 2.1330729 2.29128785] |

## 1.7.2 Pandas for Data Processing

Statistical data acquired from different sources is in a raw form that has to be cleaned and prepared for further analysis. Pandas is a library for data preparation and cleaning. Pandas uses mainly two data structures:

1. **Series**, which is like a list of items and
2. **DataFrames**, which acts like a table or a matrix with multiple columns.

Pandas allows data cleaning features such as replacing missing values, joining and merging data from different sources. We import Pandas and use pd as its alias.

|  |
| --- |
| **import** pandas as pd |

**Series:** Similar to a 1-dimensional NumPy array, the Series data structure is able to handle 1-dimensional data. However, unlike NumPy arrays, it offers extra features to pre-process data. The constructor Series () is used to create a series object.

|  |
| --- |
| 1. myseries = pd.Series([-2, -1, 0, 1, 2]) # note capital S in Series  2. myseries  **Output:**  0  -2  1  −1  2   0  3   1  4 2  dtype: int64 |

The last line of the output, dtype: int64, indicates that the type of values of myseries is integer of 64 bits.

A series object contains two arrays: index and value, that are linked to each other. The first array on the left of the output of the previous program saves the index of the data, while the second array on the right contains the actual values of the series.

Series objects can be generated using NumPy arrays. Instead of default numeric indices, descriptive indices can be assigned to the values. The following program shows how to use a NumPy array to generate a series object.

|  |
| --- |
| 1. **import** pandas as pd 2. **import** numpy as np 4. series\_list = pd.Series([1,2,3,4,5,6,7,8,9]) 5. series\_np = pd.Series(np.array([10,20,30,40,50,60,70,80,90])) 7. **print**("A Pandas series list:\n",series\_list) 8. **print**("\nA Pandas series using numpy array:\n",series\_np) 10. series\_index = pd.Series( 11. np.array([10,20,30,40,50]), 12. index=['a', 'b', 'c', 'd', 'e'] 13. ) 15. **print**("\nA Pandas series with indexing in letters:\n",series\_index)   **Output:**  A Pandas series list:  0 1  1 2  2 3  3 4  4 5  5 6  6 7  7 8  8 9  dtype: int64  A Pandas series using a NumPy array:  0 10  1 20  2 30  3 40  4 50  5 60  6 70  7 80  8 90  dtype: int32  A Pandas series with indexing in letters:  a 10  b 20  c 30  d 40  e 50  dtype: int32 |

Line 12 uses index option in pd.Series () constructor to assign letters as indices to the values.

**DataFrame:** The second data structure used by Pandas, the DataFrame, is similar to a 2-dimensional NumPy array. The DataFrame contains an ordered group of columns. Every column contains values of numeric, string, or Boolean, etc. types.

To create a DataFrame, we pass a dictionary to the constructor DataFrame(). This dictionary comprises of keys with corresponding values. In the Python script given below, a dictionary namely d is created. This dictionary is used as an input to the DataFrame () constructor to create a dataframe.

|  |
| --- |
| 1. d = {'one': pd.Series([1.2, 2.3, 3.4], index=['a', 'b', 'c']), 2. 'two': pd.Series([1.5, 2.4, 3.2, 4.1], index=['a', 'b', 'c', 'd'])} 4. df = pd.DataFrame(d) 5. **print**("Dataframe from a dict of series is:\n" ,df) 7. df1 = pd.DataFrame(d, index=['d', 'b', 'a']) 8. **print**("Dataframe from a dict of series with custom indexes is:\n" ,df1)   **Output:**  Dataframe from a dict of series is:  one two  a 1.2 1.5  b 2.3 2.4  c 3.4 3.2  d NaN 4.1  Dataframe from a dict of series with custom indexes is:  one two  d NaN 4.1  b 2.3 2.4  a 1.2 1.5 |

The following Python script makes use of dictionary object to create a dataframe namely df. The program also shows how to get data from the dataframe.

|  |
| --- |
| 1. my\_dict = { 2. 'name' : ["a", "b", "c", "c", "e"], 3. 'age' : [10,20, 30, 40, 50] 4. } 6. df = pd.DataFrame( my\_dict, 7. index = [ 8. "First", 9. "Second", 10. "Third", 11. "Fourth", 12. "Fifth"]) 14. **print**("\nThe dataframe is:\n",df) 16. series\_name = df.name 17. **print**("\nThe name series is:\n",series\_name)  20. series\_age = df.age 21. #Getting the mean of a Series 22. **print**("\nGetting mean value from a series: ",series\_age.mean()) 24. # Getting the size of the Series 25. **print**("\nGetting size of a series: ",series\_age.size) 27. # Getting all unique items in a series 28. **print**("\nGetting unique values of a series: ",series\_name.unique()) 30. # Getting a python list out of a Series 31. **print**("\nGetting a list of a series: ",series\_name.tolist())   **Output:**  The dataframe is:  name age  First a 10  Second b 20  Third c 30  Fourth c 40  Fifth e 50  The name series is:  First a  Second b  Third c  Fourth c  Fifth e  Name: name, dtype: object  Getting mean value from a series: 30.0  Getting size of a series: 5  Getting unique values of a series: ['a' 'b' 'c' 'e']  Getting a list of a series: ['a', 'b', 'c', 'c', 'e'] |

## 1.7.3 Statistics: Python’s Built-in Module

Python provides a built-in module with a rich variety of

functions to calculate statistics of real valued data. A brief list of functions provided by this module are given in Table 1.1.

Table 1.1: Statistical functions provided by Statistics module.

|  |  |
| --- | --- |
| **Function Name** | **Description** |
| [mean()](https://docs.python.org/3/library/statistics.html#statistics.mean) | It calculates the average or arithmetic mean of the data. |
| [median()](https://docs.python.org/3/library/statistics.html#statistics.median) | It is used to calculate median or middle value of the data. |
| [mode()](https://docs.python.org/3/library/statistics.html#statistics.mode) | It calculates the single mode (most common value) of discrete or nominal data. |
| [quantiles()](https://docs.python.org/3/library/statistics.html#statistics.quantiles) | It divides data into intervals with equal probability. |
| [pstdev()](https://docs.python.org/3/library/statistics.html#statistics.pstdev) | It calculates standard deviation of the whole population. |
| [pvariance()](https://docs.python.org/3/library/statistics.html#statistics.pvariance) | It calculates variance of the whole population. The variance is the square root of the standard deviation. |
| [stdev()](https://docs.python.org/3/library/statistics.html#statistics.stdev) | It calculates standard deviation of a sample taken from the population. |
| [variance()](https://docs.python.org/3/library/statistics.html#statistics.variance) | It calculates variance of a sample taken from the population. |

There is a slight difference between the standard deviation / variance of a sample and that of the whole population. In the calculation of statistics for a sample, we divide by (*N*-1) where *N* represents number of data points. However, in case of population variance and standard deviation, we divide by (*N*). Therefore, we get slightly different results. This is illustrated along with other statistics in the following Python script.

|  |
| --- |
| 1. **import** numpy as np 2. **import** statistics as st 4. raindata = [2, 5, 4, 4, 0, 2, 7, 8, 8, 8, 1, 3] 6. # Mean 7. **print**("mean = ", st.mean(raindata)) 9. # Median 10. **print**("median = ",st.median(raindata)) 12. # Mode 13. **print**("mode = ",st.mode(raindata)) 15. # population variance 16. **print**("pvariance = ", st.pvariance(raindata)) 18. # population standard deviation 19. **print**("pstdev = ", st.pstdev(raindata)) 21. # variance 22. **print**("variance = ", st.variance(raindata)) 24. # standard deviation 25. **print**("stdev = ", st.stdev(raindata))   **Output:**  mean = 4.333333333333333  median = 4.0  mode = 8  pvariance = 7.555555555555555  pstdev = 2.748737083745107  variance = 8.242424242424242  stdev = 2.8709622502610936 |

Note that we get pstdev = 2.75 and stdev = 2.87. The function st.mode () gives the data point that occurs the most in the dataset. This function gives error in case there is no unique mode.

## 1.7.4 Matplotlib for Visualization and Plotting

It is often desirable to plot the datasets and its important statistics to get a better understanding of the distribution of the data. Matplotlib is the Python library that provides us with a variety of interactive tools to plot the data. The following example plots a given dataset along with its mean, median and mode.

|  |
| --- |
| 1. **import** matplotlib.pyplot as plt 2. **import** statistics as st 4. month\_names = ['Jan', 'Feb', 'Mar', 'Apr', 'May', 'Jun', 'Jul', 'Aug', 'Sep', 'Oct', 'Nov', 'Dec'] 5. months = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12] 7. fig, ax = plt.subplots(nrows=1, ncols =1) 9. ax.set\_title("Measures of Center") 10. ax.set\_xlabel("Month") 11. ax.set\_ylabel("Number of times it rained") 13. ax.scatter([1,2,3,4,5,6,7,8,9,10,11,12],raindata) 15. plt.xticks(np.arange(12)+1, month\_names, color = 'black') 17. # draw points for mean, median, mode 18. ax.plot([st.mean(raindata)], [st.mean(raindata)], color='r', marker="o", markersize=15) 19. ax.plot([st.median(raindata)], [st.median(raindata)], color='g', marker="o", markersize=15) 20. ax.plot([st.mode(raindata)], [st.mode(raindata)], color='k', marker="o", markersize=15) 22. # Annotation 23. plt.annotate("Mean",  (st.mean(raindata), st.mean(raindata)+0.3),color="r") 24. plt.annotate("Median", (st.median(raindata), st.median(raindata)-0.7),color="g") 25. plt.annotate("Mode", (st.mode(raindata), st.mode(raindata)-0.7),color="k") 27. plt.show()   **Output:** |

## 1.7.5 SciPy.stats Module for Statistical Functions

SciPy.stats is a Python module that contains several probability distributions in addition to a large number of statistical functions. To generate summary statistics, we first import scipy.stats. The following script prints numerous statistics.

|  |
| --- |
| 1. **import** scipy.stats as stats 2. **import** numpy as np 3. # Statistical functions applied on an array of data 5. c = np.array([5, 2, 5, 6, 3, 4, 2, 8, 7]) 7. all = stats.describe(c) 8. gmean = stats.gmean(c) 9. hmean = stats.hmean(c) 10. mode = stats.mode(c) 11. skewness = stats.skew(c) 12. iqr = stats.iqr(c) 13. zscore = stats.zscore(c) 15. **print**("\nDescribe\n",all) 16. **print**("\nGeometric mean\n",gmean) 17. **print**("\nharmonic mean\n",hmean) 18. **print**("\nMode\n",mode) 19. **print**("\nSkewness\n",skewness) 20. **print**("\nInter Quantile Range\n",iqr) 21. **print**("\nZ Score\n",zscore)   **Output:**  Describe  DescribeResult(nobs=9, minmax=(2, 8), mean=4.666666666666667, variance=4.5, skewness=0.12962962962962918, kurtosis=-1.1574074074074074)  Geometric mean  4.196001296532889  harmonic mean  3.722304283604136  Mode  ModeResult(mode=array([2]), count=array([2]))  Skewness  0.12962962962962918  Inter Quantile Range  3.0  Z Score  [ 0.16666667 -1.33333333 0.16666667 0.66666667 -0.83333333 -0.33333333  -1.33333333 1.66666667 1.16666667] |

Scipy.stats provides us a large number of random variables and discrete as well as continuous probability distributions.

|  |
| --- |
| 1. **import** scipy.stats as stats 2. **from** scipy.stats **import** norm 3. **from** scipy.stats **import** uniform 5. # Generation of random variables 6. a = norm.rvs(size = 5) 7. **print** (a) 8. b = uniform.cdf([0, 1, 2, 3, 4, 5], loc = 1, scale = 4) 9. **print** (b)   **Output:**  [-0.58508956 1.96115496 1.04615577 -0.0938734 0.91089162]  [0. 0. 0.25 0.5 0.75 1. ] |

We shall go into the detail of random variables and probability distributions in Chapter 3.

## 1.7.6 Statsmodels for Statistical models

The Python module statsmodels offers numerous statistical functions to create statistical models and assess their performances. This module also provides a range of statistical tests to explore a given dataset.

In statsmodels, we can specify the details of the statistical model using formulas or array objects. The following is an example to generate a regression model using ordinary least squares (OLS).

|  |
| --- |
| 1. **import** numpy as np 2. **import** statsmodels.api as sm 4. # Generate artificial data (2 regressors + constant) 5. nobs = 100 7. X = np.random.random((nobs, 2)) 8. X = sm.add\_constant(X) 10. beta = [1, .1, .5] 12. e = np.random.random(nobs) 13. # Dot product of two arrays 14. y = np.dot(X, beta) + e 16. # Fit regression model 17. results = sm.OLS(y, X).fit() 19. # Inspect the results 20. **print**(results.summary())   **Output:**  OLS Regression Results  ==============================================================================  Dep. Variable: y R-squared: 0.079  Model: OLS Adj. R-squared: 0.060  Method: Least Squares F-statistic: 4.155  Date: Fri, 04 Sep 2020 Prob (F-statistic): 0.0186  Time: 22:18:38 Log-Likelihood: -25.991  No. Observations: 100 AIC: 57.98  Df Residuals: 97 BIC: 65.80  Df Model: 2  Covariance Type: nonrobust  ==============================================================================  coef std err t P>|t| [0.025 0.975]  ------------------------------------------------------------------------------  const 1.6532 0.088 18.781 0.000 1.478 1.828  x1 0.0062 0.120 0.052 0.959 -0.233 0.245  x2 0.3266 0.114 2.856 0.005 0.100 0.553  ==============================================================================  Omnibus: 71.909 Durbin-Watson: 2.124  Prob(Omnibus): 0.000 Jarque-Bera (JB): 7.872  Skew: -0.133 Prob(JB): 0.0195  Kurtosis: 1.651 Cond. No. 5.72  =============================================================================  Warnings:  [1] Standard Errors assume that the covariance matrix of the errors is correctly specified. |

The output of the code describes a number of statistics related to the regression model. The reader may not be familiar with a lot of terms in the output. However, at this stage it is not very important to understand the minute details of the statistical models. We shall get back to these concepts in the later chapters of the book. However, it is important to realize the powerful features of the statsmodels library.

## 1.7.7 PyMC for Bayesian Modeling

PyMC3 is a Python package specifically designed for Bayesian statistical modeling and machine learning. This package makes use of Markov chain Monte Carlo (MCMC) and variational algorithms to create / train the statistical models which are hard to create otherwise.

To perform differentiation as frequently required in Bayesian statistics and for computational optimization, PyMC3 depends upon Theano, another Python library.

PyMC is not part of Anaconda distribution. Thus, we have to install it manually. To install, PyMC to Anaconda distribution, we open the Anaconda prompt from Windows start menu. In the prompt, we type the following command.

conda install m2w64-toolchain

Once the toolchain is installed, we get a message “done”. Next, we type the following command to install the pymc3, the latest release of the package.

conda install -c conda-forge pymc3

We also have to install another Python library, theano, which has dependencies on pymc3.

conda install theano pygpu

Depending upon the internet speed, it will take a while to install this package.

If the installed PyMC package does not work, we may need to install the xarray dependency by typing the following command.

pip install xarray==0.16.0

An essential step to build Bayesian models is the description of a probability model. In this process, we assign statistical distributions, that can be described by some parameters, to unknown quantities in the model. Therefore, PyMC3 provides wide-ranging pre-defined probability distributions which are used to build Bayesian models. For instance, to define a variable having Normal or Gaussian probability, we specify it as an instance of the Normal.

|  |
| --- |
| 1. **import** pymc3 as pm 2. with pm.Model(): 4. x = pm.Normal('x', mu=0, sigma=1) |

Details of PyMC3 functionality is beyond the scope of this chapter. We go into the details of Bayesian modeling in Chapter 8.

|  |
| --- |
| Further Reading |
| More information about Python and its commonly used functions can be found at  <https://docs.python.org/3/tutorial/index.html> |

|  |
| --- |
| **Hands-on Time** |
| To test your understanding of the concepts presented in this chapter, complete the following exercise. |

# 1.8 Exercise Questions

**Question 1:**

Which statement is usually used when we have to make a decision based upon only one condition?

A If Statement

B else Statement

C For Loop

D Both A and B

**Question 2:**

Which statement is usually used when we need to iteratively execute a code fixed number of times?

A If Statement

B else Statement

C For Loop

D Both A and B

**Question 3:**

What will be the output if we type 19 / 3?

A 6

B 6.333333333333333

C 1

D Not given

**Question 4:**

What will be the output if we type 17 // 4?

A 4

B 1

C 4.25

D 68

**Question 5:**

What will be the output if we type 45 % 7?

A 6

B 3

C 6.428571428571429

D Not given

**Question 6:**

What will be the output if we type the following code?

word = 'Python'

word[1]

A 'P'

B 'p'

C 'y'

D 'Y'

**Question 7:**

What will be the output if we type the following code?

word = 'Python'

word[-2]

A 'n'

B 'o'

C 'h'

D 'P'

**Question 8:**

What will be the output if we enter 80 as student marks when we run the following code?

|  |
| --- |
| 1. **print**('Input marks of a student') 2. student\_marks = int(input()) 3. **if**(student\_marks > 100 **or** student\_marks < 0): 4. **print**("Marks exceed 100.") 5. **elif**(student\_marks >= 80): 6. **print**("Excellent") 7. **else**: 8. **print**("Not excellent") |

A Nothing will be printed

B Not excellent

C Excellent

D Marks exceed 100.

**Question 9:**

Suppose we have run the following piece of code.

|  |
| --- |
| 1. mybirds =  ["Parrot", "Sparrow", "Crow", "Eagle"] 2. mybirds.insert(1,'Crow') 3. mybirds |

What would be the result?

A ['Parrot', 'Sparrow', 'Crow', 'Eagle']

B ['Parrot', 'Sparrow', 'Crow', 'Crow', 'Eagle']

C ['Parrot', 'Crow', 'Sparrow', 'Crow', 'Eagle']

D ['Crow', 'Parrot', 'Sparrow', 'Crow', 'Eagle']

**Question 10:**

What would be the result if we have run the following piece of code?

|  |
| --- |
| 1. mybirds =  ["Parrot", "Sparrow", "Crow", "Eagle"] 2. mybirds.remove("Pigeon") 3. mybirds |

A ['Parrot', 'Sparrow', 'Crow', 'Eagle']

B ['Parrot', 'Sparrow', 'Crow', 'Eagle', 'Pigeon' ]

C An error message will be displayed

D Not given

Chapter 2: Starting with Probability

# 2.1 Definition of Probability

Statistical processes and measurements are usually uncertain because the outcomes cannot be precisely predicted. In the process of collecting statistical data, we generally assume that there is a true value which lies within the measurements we make. This means there is uncertainty in collecting the data. Generally, our goal is to find the best estimate of our measured data under uncertainty.

To measure the uncertainty of statistical processes and events, we resort to the probability theory that is often used to describe uncertain quantities. We explain the concept of probability in the subsequent sections of this chapter.

In numerous situations, we have to describe an event in term of its chances of occurrence. For example, weather forecasts tell us chances of rain on any particular day. In sports analysis, the probability of winning a team is given before or during the actual game.

The definition of probability is a subject of philosophical debate. The probability is a single number that varies from 0 to 1. A high value of the probability of an event indicates more likeliness that the event will occur.

In repeatable experiments whose outputs are random such as tossing a coin or drawing a card from a deck, the probability of happening of a desirable event can be defined as the number of desired outcomes divided by the total number of outcomes from all the repetitions of the experiment.

For instance, when we toss an unbiased coin, either of the two outcomes: heads or tails can occur. The chances of getting heads is equal to that of tails. We say that the probability of heads and tails is 0.5 each.

In another experiment where a coin is tossed thrice, we may get one out of eight possible outcomes: HHH, HHT, HTH, HTT, THH, THT, TTH, TTT. Here, H and T represent heads and tails, respectively. The probability of getting a particular outcome, for example, all heads HHH, is 1 out of 8 outcomes. Numerically, we report the probability as 1/8 or 0.125. When such an experiment is performed, the chances of occurrence of a particular outcome may not be as per the calculations.

There are two opposing factions that interpret the concept of probability differently. One of the groups is known as **frequentist**, that interprets the probability as **relative frequency** of happening of a certain outcome provided the experiment is repeated again and again. This is somewhat objective view of probability because the fundamental assumption is repetition of the experiment. The computation of the probability in the aforementioned experiments follows the frequentist approach.

The second major group, also known as **Bayesian**, interprets the probability as a **degree of belief** in an event. This degree of belief is usually based on expert knowledge of the event which is obtained from the results of previous experiments, and is represented by a **prior** probability distribution. The combination of the prior with a **likelihood** function results in a **posterior** probability distribution that incorporates all the information to get the probability of an event as a degree of belief. This understanding of the probability is rather subjective and it is different from the frequentist interpretation. We shall go into the details of the Bayesian interpretation when we discuss Bayes theorem in the same chapter.

# 2.2 Some Important Definitions

In statistical studies or experiments, the quantities to be measured are named as **random variables**. An observation is a specific outcome of the experiment. Numerous observations collected from the study constitute the **data**, and an assortment of all possible outcomes of the experiment are called the **population**.

Practically, we cannot observe the whole **population**. As an alternate, we take a **sample** that is a small portion of the population. We try to get the sample from the population in such a way that it should represent the whole population. Thus, we take a random sample in which all members of the population are equally likely to be included in the sample.

For instance, if we are going to conduct a survey on the amount of time people spend online, we shall select and observe some individuals. This subset of people might provide us a biased sample of the population, and the results obtained from such a survey would not generalize to the whole population. Thus, it is important to collect a sample of considerable size that is representative of the whole population.

# 2.3 Samples Spaces and Events

The outcomes of statistical experiments are generally random. The probability theory is employed to study the random behavior of statistical experiments. The set

of all possible outcomes of an experiment forms the **sample space** specific to the experiment. We usually denote the sample space by *S*. An element that is an outcome of *S* is represented by *s*. The sample space is selected to get one outcome from one run of the experiment. The sample space can be finite or infinite.

For example, if we roll a dice, we get one of the numbers from 1 to 6. The sample space of this experiment is given as

*S = {1, 2, 3, 4, 5, 6}.*

As another example, tossing a coin twice will constitute the following sample space.

*S = {HH, HT, TH, TT}.*

We can view the aforementioned experiment in a slightly different way. For example, when we are interested in number of heads, the sample space would be given as

S = {0, 1, 2}.

All of the above-mentioned sample spaces are **countably finite**.

The time from a specified point to the occurrence of a particular event is known as survival time. For example, the survival time, in hours, from birth of a honeybee has the following sample space

*S* = {0, 1, 2, 3, 4, …}

Practically, there is an upper limit to this survival time, but we do not know it in advance. Therefore, we include all non-negative integers in the sample space. This is an example of a **countably infinite** sample space. Finally, the lifetime of a light bulb can be any positive real number with the sample space

S = [0, ¥),

where [ includes 0 in the set, and ) excludes the infinity ¥ from the set. This is an example of an **uncountably infinite** sample space because the time a light bulb may survive can take on any positive real number.

An **event** is a sub-set of a sample space. An empty sub-set of the sample space is known as the null event. The whole sample space is another type of event. An event that contains a single element of the sample space is called as an elementary event, whereas an event that is constituted of multiple outcomes of the sample space is called a compound event.

In the example of tossing a coin twice, we define an event that no head occurs:

*E* = {0}.

This forms an elementary event. On the other hand, defining an event that at most 1 head occurs constitutes a compound event with the following sample space.

*E* = {0, 1}.

The events can be combined together the way we combine different sets. For example, in rolling a dice, event 1, *E*1, can be defined as getting an odd number, and event 2, *E*2, can be defined as getting a number less than 4.

*E*1 = {1, 3, 5}.

*E*2 = {1, 2, 3}.

The **intersection** of events *E*1 and *E*2 is another event *E*3 that would be an odd number less than 4.

*E*3 = *E*1 ∩ *E*2 = {1, 3}

Moreover, the **union** of the events can also be defined. For instance, we define *E*4 as an event that the outcome is either odd or less than 4.

*E*4 = *E*1 ∪ *E*2 = {1, 2, 3, 5}.

The laws applicable to set theory are also equally applicable to events. These laws include commutative, associative and distributive laws.

The relationship between different events is usually depicted graphically as a logic or set diagram known as a **Venn diagram**. The events are shown as regions represented by closed curves such as circles.

The points inside a circle signify elements of the event, whereas the points outside the circle denote elements of the sample space not present in the event. For instance, the set of all elements that are members of both events *E*1 and *E*2, i.e., the intersection of *E*1 and *E*2, is shown as the overlapped area in the Venn diagram. Figure 2.1 shows the intersection of two events as the area highlighted in brown color.

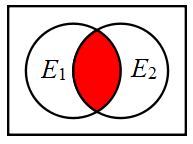


Figure 2.1: A Venn diagram showing intersection of two events *E*1 ∩ *E*2.

Figure 2.2. depicts the union of two events as the highlighted area.

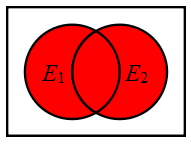


Figure 2.2: A Venn diagram showing union of two events *E*1 ∪ *E*2.

In general, when there is an overlap between two events, we calculate the probability of the union of both events as

*P*(*E*1 ∪ *E*2) = *P*(*E*1) + *P*(*E*2) - *P*(*E*1 ∩ *E*2).

The term *P*(*E*1 ∩ *E*2) or the probability of the intersection is subtracted from *P*(*E*1) + *P*(*E*2) because the sum of *P*(*E*1) and *P*(*E*2) includes the common area twice.

The disjoint or mutually exclusive events do not have any common element from the sample space. Figure 2.3 shows two disjoint events as a Venn diagram.

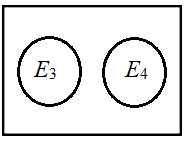


Figure 2.3: A Venn diagram showing two disjoint or mutually exclusive events that do not have any common elements of the sample space.

# 

# 2.4 Axioms of Probability

Generally, we use sets to understand the events drawn from a sample space. The set theory can also be used to understand the probability theory. Based on the set theory, some propositions about probability can be deduced. These propositions are known as probability axioms where an axiom is a proposition whose truth is self-evident. These axioms are given as:

1. *P*(*S*) = 1.

The probability that at least one of all the possible outcomes of the sample space *S* will occur is 1. Alternatively, when an experiment is performed, some event of the sample space of this experiment will always occur.

1. *P*(*E*)≥0

If *E* is an event (a sub-set of *S*)*,* its probability is equal to or greater than zero.

1. *P*(*E*1 ∪ *E*2 ) = P(*E*1) + P(*E*2) for mutually exclusive or disjoint events *E*1 and *E*2.

The symbol ∪ stands for the set union. We can redefine this as: If *E*1 and *E*2 have nothing in common, i.e., these are mutually exclusive, the probability of either *E*1 or *E*2 equals the probability of occurrence of *E*1 plus the probability of occurrence of *E*2.

# 2.5 Calculating Probability by Counting

Statistical experiments and the data used by them usually have an element of randomness. We employ probability theory as a foundation to understand this random behavior.

The frequentist statistics interprets the probability as relative frequency. In this interpretation, the probability is defined for those events from experiments which can be repeated again and again under similar conditions.

The frequentist approach defines the probability of an event as the ratio of number of times the event occurs to the total number of times the experiment is run provided the experiment is run numerous times under identical conditions. The probability can also be defined as a long-run proportion, that is the ratio of the occurrence of the event to the total large number of runs of the experiment.

In this case, we count the occurrence of the event whose probability is to be found. Mathematically, the probability *p* of the event *E* is defined as



where *m* is the number of times the event *E* occurs in *n* repeated trials of the experiment. The frequentist interpretation of the probability is generally well-accepted by most statisticians. However, the problem with this interpretation is that it assumes the experiment is repeatable. In many real-world natural events that happen only once, such as the occurrence of rain in a particular geographic area tomorrow, this interpretation fails.

To calculate the probability by counting, let us consider an experiment. Suppose that a fair coin is thrown twice. The sample space of this experiment is

*S = {HH, HT, TH, TT}*

Each outcome has a probability of ¼ under the assumption of equally likely outcomes. We define event *A* as getting both tails, and event *B* as head on the second toss as follows:

*A* = {TT} and

*B* = {HH, TH}.

The probability of both events can be given as

*P*(*A*) = Number of times *A* occurs / total number of outcomes

*P*(*A*) = 1/4

*P*(*B*) = Number of times *B* occurs / total number of outcomes

*P*(*B*) = 2/4

In another example, a statistical experiment is conducted numerous times. The data obtained from the experiment is summarized in the table given below. From this collected sample data, what is a reasonable estimate of the probability that the outcome of the next run of the experiment will be 5?

|  |  |  |
| --- | --- | --- |
| **Outcome** | **Frequency** | **Relative Frequency** |
| 1 | 200 | 0.0513 |
| 2 | 100 | 0.0256 |
| 3 | 900 | 0.2307 |
| 4 | 500 | 0.1282 |
| 5 | 1200 | 0.3077 |
| 6 | 500 | 0.1282 |
| 7 | 200 | 0.0513 |
| 8 | 300 | 0.0769 |

The frequentist approach calculates the probability of an event by computing the relative frequency which is obtained when we divide frequency of occurrence of an event by the total number of runs of the experiment.

Though the data given in the above-mentioned table is limited, we can still estimate the probability of occurrence of 5. The relative frequency of the outcome 5 is number 1200 divided by the total number of runs of the experiment, i.e., 3900. Thus, our estimate of the probability for outcome 5 is approximately 1200/3900≈0.30. In Python, type the following code.

|  |
| --- |
| 1. ## Calculating probability of events 3. # Sample Space 4. num\_cards = 52 6. # Favorable Outcomes 7. num\_aces = 4 9. num\_hearts = 13 10. num\_diamonds = 13 12. # Divide favorable outcomes by the total number of elements in the sample space 13. prob\_ace = num\_aces / num\_cards 15. prob\_red\_card = (num\_hearts+ num\_diamonds) / num\_cards  18. # Print probability rounded to two decimal places 19. **print**('The probability of getting an ace =', round(prob\_ace, 3)) 20. **print**('The probability of getting a red card =', round(prob\_red\_card, 3)) 22. # to print the probability in percentage 23. prob\_ace\_percent = prob\_ace \* 100 24. prob\_red\_percent = prob\_red\_card \* 100 26. **print**('\nThe probability of getting an ace in percentage =', str(round(prob\_ace\_percent, 1)) + '%') 27. **print**('The probability of getting a red card in percentage =', str(round(prob\_red\_percent, 1)) + '%')   **Output:**  The probability of getting an ace = 0.077  The probability of getting a red card = 0.5  The probability of getting an ace in percentage = 7.7%  The probability of getting a red card in percentage = 50.0% |

# 2.6 Combining Probabilities of More than One Events

Let us define events A and B:

* **Event A:** It is raining outside. Let there be a 40% chance of raining today. The probability of event A is P(A) = 0.4.
* **Event B:** A person needs to go outside. Let there be a 30% chance of the person going outside. The probability of B would be P(B) = 0.3.

**Joint probability**: Let the probability that both events happen simultaneously is 0.2 or 20%. It is written as P(A and B) or P(A⋂B), and is known as the  joint probability of A and B. The symbol ⋂ is for the intersection of the events.

# 2.7 Conditional Probability and Independent Events

Suppose we are interested to know the probability or chances of occurrence of rain given the person has gone outside. The probability of rain given the person has gone outside is the **conditional probability** denoted as *P(A|B).*

The conditional probability can be understood by thinking of a reduced sample space when one of the events, i.e., *B* in our case, has already occurred. Since we are certain that *B* has occurred, we do not need to look for the whole sample space for calculating the conditional probability *P(A|B).* Thus, we find the probability of intersection of *A* and *B* under the condition that *B* has occurred. Mathematically, it can be given as,

*P(A|B) = P(A*⋂*B) / P(B)*

*= 0.2 / 0.3 = 0.66= 66.6%.*

Some events depend upon other events. For example, let event *A* be “buying a lottery ticket” and event *B* be “winning the lottery”. The events *B* is dependent upon event *A* because we cannot win without buying a ticket.

Conversely, two events are said to be **independent** if the occurrence of one does not affect the occurrence of the other event. For instance, rolling a dice and tossing a coin are two independent events since these events can occur in any order, and the occurrence of one does not affect the occurrence of the other event.

Therefore, for any two independent events *A* and *B,* the probability of event *A* given the event *B* has occurred before is given as *P (A|B):*

*P (A|B) = P(A)*

The probability of event *B* given the event *A* has occurred before is given as *P (A|B):*

*P (B|A) = P(B)*

*P(A ∩ B) = P(A|B) P(B) = P(A) P(B)*

It is obvious from this last expression that for independent events the joint probability of both events equals the product of individual probabilities of the events.

To find out if the events are dependent or independent, we perform certain simple tests.

* If the order of happening of two events matter, one of the events is dependent upon the other event. For instance, parking a car and getting the parking ticket are dependent events.
* If the order of events does not matter, we check if the occurrence of one event impacts the outcome of the second event. If yes, the events are dependent, otherwise the events are independent.

Drawing a card from a deck of 52 cards, replacing it to the deck, and then drawing another card from the same deck constitutes two independent events as two draws from the deck. Since we replace the card, we do not change anything. The probability of drawing first card is 1/52, and the probability of drawing the second card is also 1/52.

However, if we draw a card, then draw another card **without replacing** the first card, we have 1/52 probability of drawing the first card, and 1/51 probability of drawing the second card because the second draw is from 51 cards instead of 52 cards. This is an example of dependent events.

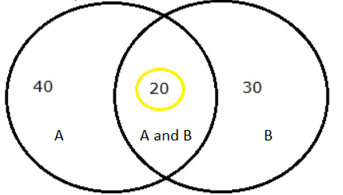


Figure 2.4: Explanation of the joint and conditional probability.

We implement these concepts in Python as follows.

|  |
| --- |
| 1. ## Probability of Independent and dependent Events  4. # Sample Space 5. total\_cards = 52 6. cards\_drawn = 1 7. # remaining cards when the card drawn in the first place is not replaced 8. rem\_cards = total\_cards - cards\_drawn 10. # Calculate the joint probability of drawing a king after drawing a queen in the first draw with replacement 11. num\_queens = 4 12. num\_kings = 4 13. prob\_king1 = num\_kings / total\_cards 14. prob\_queen1 = num\_queens / total\_cards 16. # probability of intersection of events 17. prob\_king\_and\_queen1 = prob\_king1 \* prob\_queen1 19. # Determine the joint probability of drawing a king after drawing a queen in the first draw without replacement 21. prob\_king2 = num\_kings / rem\_cards 22. prob\_queen2 = num\_queens / total\_cards 24. # probability of intersection of events 25. prob\_king\_and\_queen2 = prob\_king2 \* prob\_queen2  28. # Print each probability 29. **print**('The product of probability of getting a king and the probability of drawing a queen = ', round(prob\_king1 \* prob\_queen1,5)) 30. **print**('The probability of getting a king after drawing a queen in the first draw with replacement = ', round(prob\_king\_and\_queen1,5)) 31. **print**('The probability of getting a king after drawing a queen in the first draw without replacement = ', round(prob\_king\_and\_queen2,5))   **Output:**  The product of probability of getting a king and the probability of drawing a queen = 0.00592  The probability of getting a king after drawing a queen in the first draw with replacement = 0.00592  The probability of getting a king after drawing a queen in the first draw without replacement = 0.00603 |

The aforementioned example shows that if the first card drawn is replaced, and another card is drawn from the deck, both events become independent of each other. The product of both probabilities equals the probability of getting a king after drawing a queen in the first draw with replacement. The last line of the output shows a different value of the probability because the first card is not replaced.

# 2.8 Bayes’ Theorem

Besides *P(A|B)*, there is another conditional probability related to the event: probability of occurrence of event *B* given *A* has already occurred, i.e., *P(B|A)*. **Bayes’ theorem** converts one conditional probability to the other conditional probability. Since

*P(A⋂B) = P(A|B)  P(B)*

and

*P(A⋂B) = P(B|A)  P(A).*

Equating these two equations, we get

*P(B|A)=  [ P(A|B)  P(B) ] / (P(A).*

For the events A and B defined in Section 2.7

*P(B|A)=* (0.66)(0.3)/0.4

= 0.495 = 49.5%.

Recall that we have calculated *P(A|B) = 0.66= 66.6%* in Section 2.8. It is evident from this example that generally *P(A|B)* is not equal to *P(B|A)*.

The Bayes’ theorem is usually used when we have access to the data, and we want to find out some unknown parameters from the data. Suppose event *A* represents the data, and event *B* represents some unknown parameter to be estimated from the data. We can interpret the probabilities used in the Bayes’ theorem as follows.

* **P(B):** the probability of the event *B* (sometimes referred to as an unknown parameter or a hypothesis) regardless of the data. This is known as the **prior** probability of *B* or the unconditional probability.
* **P(A):** the probability of the data, regardless of the event *B*. This is known as the **evidence**.
* **P(A|B):** the probability of data *A* given that the hypothesis or the assumed parameter *B* is true. This is known as the **likelihood** of data *A* conditional on the hypothesis *B*.
* **P(B|A):** the probability of event *B* given the data *A*. This is known as **posterior** probability. Usually we are interested to find this probability.

It is important to realize that if one of the conditional probabilities is used as a likelihood function, the other conditional probability will be the posterior. Using *P(B|A)* as the likelihood will make *P(A|B)* a posterior.

# 2.9 Calculating Probability as Degree of Belief

The probability is calculated as a degree of belief in the Bayesian interpretation of the probability. Suppose, in a rainy season, it rains most of the days of the month in some geographical area. The natives of that area believe that the chances of having a rainy-day is 80% or 0.8. This becomes the prior probability that is based on the degree of belief of the natives. We write

*P*(rainy-day = true) = 0.8,

where a degree of belief of 80% that a randomly chosen day receives rain is the prior probability of having a rainy-day in the absence of any other evidence or the data.

It is important to point out that the degree of belief denotes the probability of happening of a particular event before we make actual observation of the event. Obviously, the priors of the events can change when we observe the actual outcomes or events. In other words, the presence of an evidence may cause our degree of belief of the event to change. It means that the calculation of posterior probability from prior, likelihood and evidence change our belief which may be used in later experiments of the similar type.

As a practical example, we might want to calculate the probability that a patient has a heart disease given they are obese.

* We define event *A* as “patient has a heart disease”. From previous experience and the data collected from different hospitals, it is believed that 15% of patients have a heart disease, i.e., *P*(*A*) = 0.15.
* We define event *B* as “patient is obese”. From the past collected data, we believe that 10% of the patients are obese, i.e., *P*(*B*) = 0.1.
* Suppose that we know from the hospital tests data that 20% of the patients diagnosed with a heart disease are obese, i.e., *P*(*B|A*) = 0.2. The probability that a patient is obese given that they have a heart disease is 20%. *P*(*B|A*) is referred to as a likelihood function.
* Now we are interested to find out the probability that a patient has a heart disease if they are obese, i.e., *P*(*A|B*). This new probability in the presence of evidence, obesity, is called as posterior probability. It is calculated using the Bayes’ theorem as follows:

*P*(*A|B*) = *P*(*B*|*A*) x *P*(*A*) / *P*(*B*)

*P*(*A|B*) = *0.2 x 0.15 / 0.1 = 0.3.*

This implies that if a patient is obese, their chances of having a heart disease is 0.3 or 30% in contrast to 15% chances in the absence of the evidence as suggested by the past collected data. Thus, the presence of evidence of one event alters the posterior probability of the other event.

|  |
| --- |
| 1. # calculating the probability as a degree of belief 2. # calculating the probability of heart disease when patient is obese 4. # defining a function to find out P(A|B) given P(A), P(B), P(B|A) 5. **def** bayes\_rule(p\_a, p\_b, p\_b\_over\_a): 6. # calculate P(A|B) 7. p\_a\_over\_b = (p\_b\_over\_a \* p\_a) / p\_b 8. **return** p\_a\_over\_b  11. ### testing of the funciton that employs Bayes rule to get posterior from prior 12. p\_a = 0.15 13. p\_b\_over\_a = 0.2 14. p\_b= 0.1 16. # calculating the posterior P(A|B) 17. p\_a\_over\_b = bayes\_rule(p\_a, p\_b, p\_b\_over\_a) 18. # summarize 19. **print**('The posterior probability P(A|B) = %.1f%%' % (p\_a\_over\_b \* 100))   **Output:**  The posterior probability P(A|B) = 30.0% |

In line 5 to 8, we define a function namely bayes\_rule () that takes the given probabilities *P(A), P(B)* and *P (B|A)* as inputs, and produces *P(A|B)* as the output. Lines 12 to 19 test our function. We define arbitrary values of *P(A), P(B)* and *P (B|A)* and call the function bayes\_rule () within the print statement. Note that we have used string formatting operator % as %.1f%% that specifies the format of the floating-point number to be printed. This formatting is applied to the floating-point number returned by (p\_a\_over\_b \* 100) to give result to one decimal place as specified by .1f.

|  |
| --- |
| **Requirements** |
| The Python scripts presented in this chapter have been executed using the Jupyter notebook. Thus, to implement the Python scripts, you should have the Jupyter notebook installed. Since Jupyter notebook has built-in libraries, we do not need to install them separately. |

|  |
| --- |
| **Further Readings** |
| For the practice of questions related to probability theory, please visit the following links:  <https://www.universalclass.com/articles/math/what-is-probability-in-statistics.htm>  For details and applications of Bayes theorem, visit  <https://www.analyticsvidhya.com/blog/2019/06/introduction-powerful-bayes-theorem-data-science/> |

|  |
| --- |
| **Hands-on Time** – **Source Codes** |
| The Jupyter notebook containing the source code given in this chapter can be found in Resources/Chapter 2.ipynb. We suggest that the reader writes all the code given in this chapter to verify the outputs mentioned in this chapter. |

# 2.10 Exercise Questions

**Question 1:**

In an experiment, two coins are flipped together, what is the probability that both coins lands heads?

A 1/2

B 1/4

C 1/8

D 1

**Question 2:**

Suppose that we draw a card randomly from a deck of 52 cards, what is the probability that the drawn card is of black color?

A 1/2

B 1/4

C 1/8

D 1

**Question 3:**

Suppose that we draw a card randomly from a deck of 52 cards, what is the probability that the drawn card is a king of spades?

A 1/13

B 1/4

C 1/52

D 4/52

**Question 4:**

Which one of the following is not an example of independent events?

A Rolling a dice, then tossing a coin

B Buying a new car, then buying a pair of shoes

C Drawing a card from a deck, then drawing another card without replacing the first card

D Drawing a card from a deck, then drawing another

card after replacing the first card

**Question 5:**

If the probability of an event *P*(*E*) = 0.4, *P*(not *E*) will be

A 0.4

B 0.5

C 0.6

D 1

**Question 6:**

The probability of drawing an ace from a deck of 52 cards is:

A 1/52

B 1/26

C 4/13

D 1/13

**Question 7:**

A dice is rolled, find out the probability of getting either 2 or 3?

A 1/6

B 2/6

C 1/3

D 1/2

**Question 8:**

If a card is chosen from a deck of 52 cards, what is the probability of getting a one or a two?

A 4/52

B 1/26

C 8/52

D 1/169

**Question 9:**

**A footballer scores at least one goal in 6 matches out of 30 matches. Find the probability of the matches in which he did not score any goal?**

A 1/5

B 2/5

C 3/5

D 4/5

**Question 10:**

What is the probability of getting a sum of 10 from two rolls of a dice?

A 1/36

B 2/36

C 3/36

D 4/36

Chapter 3: Random Variables & Probability Distributions

# 3.1 Random Variables: Numerical Description of Uncertainty

A basic concept when dealing with uncertainty is that of a *random variable* (RV). Randomly picking up a student from a university class and measuring their height or weight is a random process. We are uncertain about the outcome of this process beforehand. The measured height can be considered a RV. Thus, we may define a RV as “*a real valued function of a sample space*”. The sample space is the set of all possible outcomes of an experiment. For instance, the set of numbers from 1 to 6 is the sample space for rolling a dice once. In this case, the random variable can take on any value from 1 to 6.

As another example, the time it takes for a bus to get from station A to station B is a random variable. If the maximum time between two consecutive buses is *T*, the sample space for this experiment would be the interval [0, *T*] = {*t: 0 ≤ t ≤ T*}. This means that the random variable, *t*, can assume any length of time in the interval [0, *T*]. In this case, the sample space is continuous in contrast to the discrete sample space of the experiment involving the dice.

Generally, the definition of the word “random” by looking it up in a dictionary would be “Lacking any definite plan or order or purpose”, or “Having no specific pattern or objective". Statistically, this is not the correct definition.The word random in statistics implies a process or variable whose output is not determined in advance or its value is not deterministic. The output of a random process can be given by a probability distribution.

Additionally, it is possible for a random process to give more chances of occurrence to certain outcomes over other outcomes. In this case, the chances of happening of the outcomes would differ from one another. As an instance, if we toss an unfair coin biased in the favor of heads again and again, we will have more frequency of occurrence of heads than tails. Even in this case, we consider tossing the biased coin as a random process.

Random variables can be either **qualitative** or **quantitative**.

* The qualitative variables are not measured or counted. These have non-numeric outcomes without any order. For instance, the names of animals, types of cars and the gender are all qualitative variables.
* The quantitative variables are measurable or countable. The outcome of these variables is numeric. For example, height, weight, amount of time, age and number of goals in a football game are all quantitative variables. There are two main categories of the quantitative variables: **discrete and continuous** random variables.
  + Discrete random variables have countable number of possible outcomes. For instance, number of wins in a tournament and number of defective items in a lot consisting of 10 items are discrete random variables.
  + Continuous random variables can assume any valid value over a continuous scale. For example, weight, height, age and time are continuous random variables.

# 3.2 Generation of Random Numbers and Random Variables

In this Section, we work with random numbers using Python. Generation of random numbers forms the basis for producing random variables. To generate a random integer from 0 to 50, and a random floating-point number from 0 to 1, type the following code.

|  |
| --- |
| 1. **from** numpy **import** random 3. # Generate a random integer from 0 to 100 4. x = random.randint(50) 5. **print**(x, '\n') 7. #Generate a random floating point number from 0 to 1: 8. y = random.rand() 10. **print**('%0.2f' %y)   **Output:**  39  0.55 |

The module random is imported from NumPy library in line 1 of the program. The function randint (50) is used to generate a random integer in the range 0 to 50. Furthermore, in line no. 8 of the code, the function rand () is used to generate a random floating-point number in the range 0 to 1.

We can also generate arrays of random numbers. The following program depicts this concept.

|  |
| --- |
| 1. # Generating a 1-D array containing 10 random integers in the range 0 to 50 2. **from** numpy **import** random 4. x1d=random.randint(50, size=(10)) 6. **print**(x1d) 8. # Generating a 2-D array containing 4x3 random integers in the range 0 to 50 9. x2d = random.randint(50, size=(4, 3)) 11. **print**('\n\n',x2d)   **Output:**  [ 1 43 27 30 37 14 19 20 20 31]  [[43 20 36]  [41 48 24]  [28 48 3]  [35 25 2]] |

In line 4 of the code, the function randint (50, size=(10)) generates a 10-element array of random integers in the range 0 to 50. In line no. 9, randint(50, size=(4, 3)) generates a matrix of random numbers in the range 0 to 50. The size of the matrix is specified by the option size=(4, 3).

It is also possible to generate a multi-dimensional array of random floating-point numbers by specifying the size of the array in random.rand(xsize, ysize). For example xsize = 5 and ysize = 6 will generate a 2-dimensional array of floating point numbers having a total of 5x6 = 30 elements.

Having discussed the generation of random numbers using NumPy module random, this is the time to generate random variables using Python. There are different types of random variables as discussed in the subsequent sections of this chapter. Here, we generate one common type of continuous random variable: uniform random variable.

Auniform random variable is defined for the continuous data. It can assume any value in a certain range [a,b] with equal probability. The Python function random.uniform(a, b) is used to generate a random variable.

|  |
| --- |
| 1. #### Generation of uniform random variable 2. **Import** numpy as np 3. **from** numpy **import** random 4. b = 20 5. a = 10 6. uni\_rv = np.zeros(10) 7. **for** i **in** np.arange(10): 8. uni\_rv[i] = random.uniform(a,b) 10. uni\_rv   **Output:**  array([16.56806644, 19.4409342 , 19.16584349, 12.66223275, 16.05819612, 16.92521575, 11.31674717, 10.34496818, 17.61196685, 14.86797476]) |

The program given above uses np.zeros(10) to initialize an array uni\_rv that is used to hold 10 values of uniform random variable. The program uses a for loop to save values of uniform random variable at different indices of the arary uni\_rv.

# 3.3 Probability Mass Function (PMF)

As discussed earlier, a random variable can be discrete or continuous. A discrete random variable assumes each of its values with some probability. For instance, if we toss a coin twice, we can have one out of four outcomes: *S* = {*HH, HT, TH, TT*}.

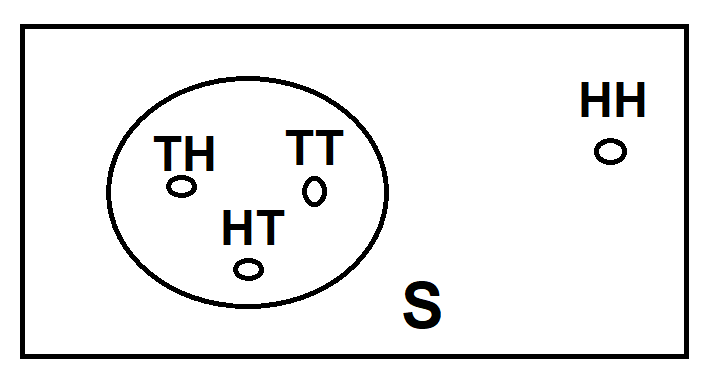


Figure 3. 1: The Venn diagram showing the sample space of the experiment in which a coin is tossed twice.

Thus, the sample space contains 4 elements. The random variable *X* describing the number of tails assumes the value 0 with the probability ¼ because there is one outcome, *HH*, in which no tails occur. The variable *X* assumes the value 1 with the probability ½ because there are two outcomes that have exactly one tail: *HT* and *TH.* Finally, the outcome *TT* has 2 tails, that results in a probability of ¼ for *P*(*X*=2). This can be summarized in the following table.

|  |  |  |  |
| --- | --- | --- | --- |
| *X* | 0 | 1 | 2 |
| *P(X=x)* | 1/4 | 2/4 | 1/4 |

Note that the value of random variable *X* can assume any possible value of the number of tails from the elements of sample space. Hence, the sum of probabilities of all the values of the random variable will always be 1. If these values do not sum up to 1, we have to look for a possible mistake in the calculation of probabilities.

Since the random variable given above can assume **discrete** values only, the set of pairs of all values (*X*,*P*(*X=x*)) is called as a **probability mass function** or **probability distribution** of a discrete random variable. Thus, describing the probability of each possible outcome of a random variable is known as a probability distribution. In the aforementioned example of tossing of coins, (0,1/4), (1, 2/4) and (2, 1/4) constitute a probability mass function. The probability mass function (PMF) of this experiment is given below in Figure 3. 2.

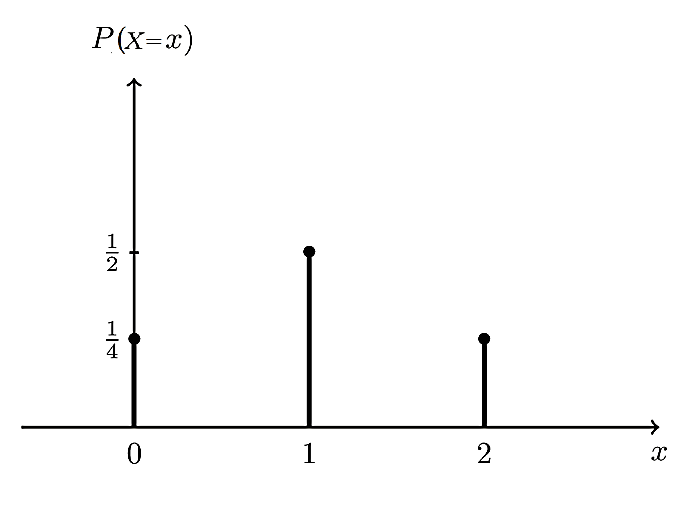


Figure 3. 2: The probability mass function (PMF) of the random variable representing number of tails when a coin is tossed twice.

The following Python script shows how we can run a statistical experiment, compute the probabilities and the probability mass function of a discrete random variable and plot the results.

|  |
| --- |
| 1. ### Computing and Plotting probability mass function of a discrete random variable 3. **import** numpy as np 4. **import** matplotlib.pyplot as plt 6. # inline magic function makes the plots to be stored in the notebook document 7. %matplotlib inline  10. # We repeat the experiment multiple times to get a better result of probabilities 11. num\_rep\_exp = 100 13. # variable num\_tails\_rep saves the number of tails got from each run of the experiment 14. num\_tails\_rep = np.zeros(num\_rep\_exp) 16. **for** i **in** range(num\_rep\_exp): 17. # 18. outcome1 = np.random.choice(['H', 'T']) 19. outcome2 = np.random.choice(['H', 'T']) 21. ### counting the number of tails from outcome1 and outcome2 22. **if** outcome1 == 'H' **and** outcome2 == 'H': 23. num\_tails = 0 24. **elif** outcome1 == 'H' **and** outcome2 == 'T': 25. num\_tails = 1 26. **elif** outcome1 == 'T' **and** outcome2 == 'H': 27. num\_tails = 1 28. **else**: 29. num\_tails = 2 31. # Saving the number of tails from each experiment at different indices of num\_tails\_rep. 32. num\_tails\_rep[i] = num\_tails  35. outcome\_value, outcome\_count = np.unique(num\_tails\_rep, return\_counts=True) 36. prob\_count = outcome\_count / len(num\_tails\_rep) 38. # Now that we have tossed the coin twice for 1000 times, we plot the results 39. plt.bar(outcome\_value, prob\_count) 40. plt.ylabel("Probability") 41. plt.xlabel("Outcome") 42. plt.title("Probability Mass Function") 43. plt.show()   **Output:** |

The program integrates multiple concepts together. After importing libraries in line 3 and 4, we use inline function of Matplotlib in line 7 that allows the plots generated by the program to be stored along with the notebook.

We repeat our experiment multiple times to plot the probability mass function after repeated trials of the experiment. Line number 14 initializes the value of the variable num\_tails\_rep that is used to save the result, number of tails, in each repetition of the experiment. We use a for loop to run the experiment repeatedly. The function choice () from the random module of NumPy library is utilized in lines 18 and 19 to choose from the specified outcomes (['H', 'T']) randomly. The variables outcome1 and outcome2 save the values either H or T after each iteration of the for loop. Lines 22 to 29 are then used to count the number of tails resulting from the output of lines 18 and 19. The output num\_tails is stored in num\_tails\_rep[i] until the for loop finishes its execution. Note that the for loop starts at line 16 and ends at line 32.

The variable num\_tails\_rep holds 100 outcomes from 100 runs of the experiment. We use the function unique () that gives us the unique values, i.e., 0, 1 and 2 in variable outcome\_value along with the number of occurrences of each value in variable outcome\_count. We calculate the probability of each outcome in line 36. Finally, lines 39 to 43 use the bar function of the Matplotlib library to plot the probability mass function of our experiment.

Note that if the experiment is run say 10 times, we may not get the shape of the PMF as we have got in the output of the code. In this case, the reason is that we are not following the basic assumption behind the frequentist interpretation of the probability which demands us to run the experiment a large number of times. As an instance if the experiment is run only 2 times, we may get 1 tail in the first run and 0 tail in the second run. Thus, the computed probabilities would be P(X=0)=1/2 P(X=1)=1/2 and P(X=2)=0, which do not correspond to the true PMF of the experiment.

# 3.4 Probability Density Function (PDF)

Similar to a continuous function, a continuous random variable has infinite number of points. Getting the chances of occurrence of exactly one value would result in a 0 probability. Thus, unlike a PMF, we are unable to describe the distribution of a continuous random variable in tabular form. The probability distribution of a continuous random variable is a continuous function which is also known as a probability density function (PDF).

An example of a continuous random variable is the variable that describes the height of university students. The height is usually measured in meters or centimeters. So, there would be infinite number of real values between any two heights, say 170 and 171 centimeters. Even between 170.28 and 170.29 centimeters, there are an infinite number of values of heights. Thus, the probability of selecting a student at random who is exactly 170.284 centimeters tall would be extremely low because there would be many points near to the height of interest, i.e., 170.284 centimeters.

Since there are infinite number of heights in our sample space, we assign a probability of 0 to the event of getting a height measurement of 170.284 centimeter. In this type of cases, instead of selecting a single value, we are generally interested in a range of values. For example, we may be interested in selecting a person whose height is between 165 and 175 centimeters.

Thus, for continuous random variables, we deal with the intervals instead of a single point. To generate a continuous random variable, we can either use NumPy library or SciPy.Stats. Here, we use the latter to generate the PDF for a normally distributed continuous random variable.

|  |
| --- |
| 1. **from** scipy.stats **import** norm 2. # generate random numbers from a normal probability density function (PDF) with zero mean and a standard deviation of 1: N(0,1) 3. norm\_pdf = norm.rvs(size=10000,loc=0,scale=1) 4. plt.hist(norm\_pdf, bins=100, density=1) 5. plt.xlabel('Random variable value') 6. plt.ylabel('Relative Frequency') 7. plt.title('Probability Density Function (PDF) for a Normal Random Variable') 8. plt.show()   **Output:** |

After we import necessary package norm, we use norm.rvs() in line 3 of the code to generate a Normally distributed continuous random variable. The options loc=0 and scale=1 specify the centre and the spread of the density function, respectively. The line 4 of the code uses hist () function from Matplotlib.pyplot module to generate **histogram** of the generated random variable. A histogram is a plot of the data using bars, where the height of the bar represents the frequency or relative frequency of a group of data points. In a histogram, taller bars indicate that a large amount of the data falls in that range. A histogram is used to display the shape, centre and spread of continuous random variables. The option **bins** specify the number of bars or groups of the data. In this example, we have used 100 bins or 100 bars to group the overall range of the values that our normal random variable can assume.

The following code uses NumPy to generate the PDF of a continuous random variable. Try to observe the change in the output of the following code by changing the value of number\_of\_data in line 4 of the code. Moreover, changing the value of bins in line 8 of the code will also change the shape of the output. The reader is encouraged to play around these values in the following code to observe changes in the output.

|  |
| --- |
| 1. **import** numpy as np 2. **import** matplotlib.pyplot as plt 3. number\_of\_data = 10000 4. random\_data\_set = np.random.randn(number\_of\_data) 6. ## plotting the shape of the generated data as a histogram 7. plt.hist(random\_data\_set, bins=100) 8. plt.show() |

|  |
| --- |
| **Further Readings** |
| The Python module SciPy.Stats offers a variety of continuous and discrete random variables along with useful functions to work with these distributions. For a detail of SciPy.Stats functions, visit  <https://docs.scipy.org/doc/scipy/reference/stats.html> |

# 3.5 Expectation of a Random Variable

A **statistic** is a numerical value that summarizes our dataset or a part of the dataset. The expected value, average or mean value of some data points or a random variable is one of the mostly used statistic.

[The expected or the mean value, mathematical expectation](https://www.geeksforgeeks.org/linearity-of-expectation/)or simply the expectation of a random variable is the long-run average value of repetitions of the experiment which this random variable belongs to. The expectation is also known as the first moment.

For instance, the sample space for tossing one fair coin twice is

*S = {HH, HT, TH, TT}.*

All four possible outcomes are equally likely. For a random variable *X* representing the number of tails in both tosses, It follows that

*P*(*X* = 0) = *P*(*HH*) = ¼,

*P*(*X* = 1) = *P*(*TH*) + *P*(*HT*) = ½ and

*P*(*X* = 2) = *P*(*TT*) = ¼.

The outcome HH represents that head occurred in both tosses, whereas HT means head occurred in the first toss and tails occurred in the second toss. The probabilities are the relative frequencies in the long run. Thus, to find the expected value denoted as μ, we take the average of all possible outcomes as follows:

μ= *E*(*X*) = Σ*x.P*(*X=x*)

μ= *E*(*X*) = (0) (1/4) + (1) (1/2) + (2) (1/4) = 1*.*

The expected value of rolling a six-sided dice can be computed as follows.

μ= *E*(*X*) = (1) (1/6) + (2) (1/6) + (3) (1/6) +(4) (1/6) + (5) (1/6) + (6) (1/6) = 3.5*.*

To calculate the expected value of a random variable, we type the following code.

|  |
| --- |
| 1. **import** numpy as np 2. sample\_space = np.arange(6)+1 3. **print**("\nArray of numbers representing a sample space", sample\_space) 4. **print**("The mean of the random variable is", np.mean(sample\_space)) 5. **print**("The average of the random variable is", np.average(sample\_space))   **Output:**  Array of numbers representing a sample space [1 2 3 4 5 6]  The mean of the random variable is 3.5  The average of the random variable is 3.5 |

# 3.6 Probability Distributions

A probability distribution gives the probabilities of occurrence of different values present in the dataset. Since a random variable can be discrete or continuous, we have corresponding discrete and continuous distributions. As mentioned earlier, the probability distribution of the discrete random variable is called as PMF, whereas the continuous random variable’s distribution is called as PDF.

There are numerous continuous and discrete valued distributions. In this Section, we give details of some of the distributions commonly encountered and used by statisticians and data scientists.

## 3.6.1 Bernoulli and Binomial Distribution

A Bernoulli distribution is a discrete probability distribution that can take only two possible values, outputs or outcomes: 1 for success with a probability *p* and 0 for failure with a probability *q*=(1-*p*). This distribution assumes only one trial of the experiment that generates 0 or 1. Thus, the Bernoulli random variable assumes either value 1 (success) or 0 (failure).

The probability of success = *p* and

The probability of failure= *q* or 1-*p*.

A Bernoulli RV can be completely specified by its parameter *p.* Mathematically, the probability function for a Bernoulli RV is given as



A single experiment with 2 possible outcomes is called a Bernoulli trial whereas a sequence of outcomes is called a Bernoulli process.

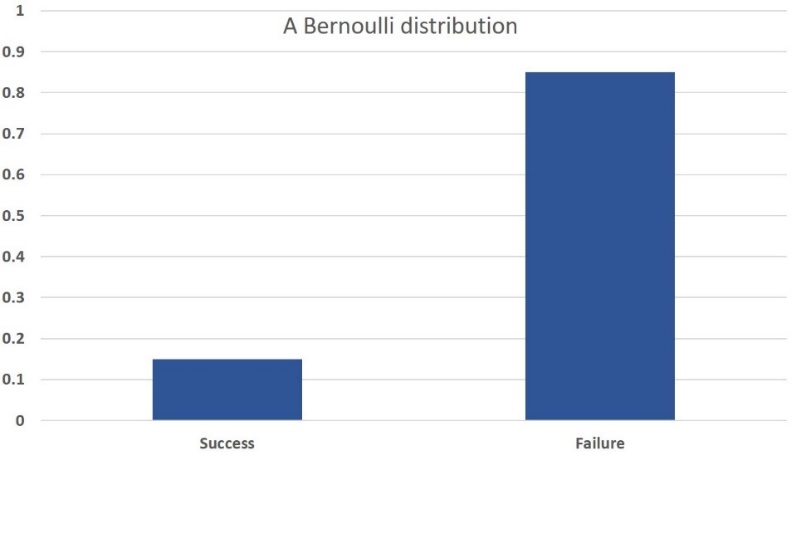


Figure 3.3: A Bernoulli distribution.

In Figure 3.3, the probability of success *p*= 0.15 and probability of failure *q*= 0.85. The expected value is the mean of all the data values in the distribution. The expected value of a Bernoulli RV equal *p*

*E(X) = xp(X=x)*

*=0(*1*-p) +* 1*(p) = p*

To implement and visualize the results for Bernoulli distributions for a fair and an unfair coin, write down the following Python program.

|  |
| --- |
| 1. **from** scipy.stats **import** bernoulli 2. **from** matplotlib **import** pyplot as plt  5. num\_tosses = 1000 6. # p=0.5 is for fair coin, any other value of p results in unfair coin 7. fair\_coin = bernoulli.rvs(p=0.5,size=num\_tosses) 8. plt.hist(fair\_coin) 10. plt.title('Bernouli Distribution for a fair coin') 11. plt.xlabel('Value of Bernouli RV') 12. plt.ylabel('Frequency of occurrence') 13. plt.show() 15. # plotting distribution for an unfair coin 16. unfair\_coin = bernoulli.rvs(p=0.2,size=num\_tosses) 17. plt.hist(unfair\_coin) 19. plt.title('Bernouli Distribution for an unfair coin') 20. plt.xlabel('Value of Bernouli RV') 21. plt.ylabel('Frequency of occurrence') 22. plt.show()   **Output:** |

We run our experiment 1000 times as mentioned in line 5 of the program. A probability value *p =* 0.5 in line 7 of the code specifies a fair coin with equal probability of occurrence of tails and heads. However, *p*= 0.2 in line 16 specifies an unfair coin biased towards one of the outcomes. The plots in the output of the program verify our results.

**The binomial distribution** can be considered as an extension of a single experiment to multiple experiments. For a single trial, i.e., *n* = 1, the binomial distribution is a Bernoulli distribution. The binomial distribution is the basis for the popular binomial test of statistical significance.

This distribution aims to find the probability of success of an event that can assume one of two possible outcomes in a series of experiments. For example, we always get a head or a tail when we toss a coin. For instance, to find the probability of exactly 10 heads in an experiment where a coin is repeatedly tossed 20 times, we use the binomial distribution. Here we assume that occurrence of heads corresponds to the successful event. Mathematically, the binomial distribution is given as



where *n* represents number of runs of the experiment, *k* is the parameter to represent number of successes. The expression



is similar to that of Bernoulli’s. To find out total number of successes *k* in *n* runs, we find the number of successful combinations using



where *n*! means factorial of the number *n*.

*n! = n (n-*1*) (n-*2*) …* 3.2.1.

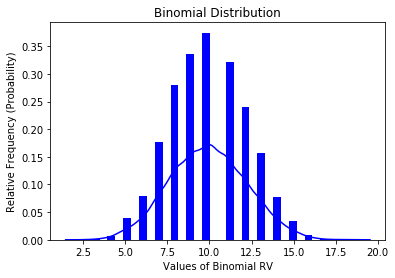
For instance, the factorial of number 5 is 5.4.3.2.1 = 120.

In the following Python example, we utilize SciPy.Stats package to create a binomial distribution. Though hist () function from Matplotlib library can be used to visualize probability distributions, here we import **seaborn** library that is based upon Matplotlib library for advanced in-built visualization functions to generate probability distribution graphs.

|  |
| --- |
| 1. ## Binomial Random variable 2. **import** numpy as np 3. **import** seaborn as sns 4. **from** scipy.stats **import** binom 6. ## n corresponds to number of trials in each experiment, size refers to total runs of the experiment, p is probability of success. 7. binom\_rv = binom.rvs(n=20,p=0.5,loc=0,size=100) 9. **print**('Number of successes in each trial having 20 coin tosses =', binom\_rv) 11. ## distplot from seaborn library is used to visualize probability distributions 12. ax = sns.distplot(binom\_rv, color='blue', hist\_kws={"linewidth": 10,'alpha':1}) 13. # hist\_kws specifies keywords to be used with histogram, linewidth specifies the width of bars and alpha is used to adjust the color strength 14. ax.set(xlabel='Values of Binomial RV', ylabel='Relative Frequency (Probability)', title ='Binomial Distribution')   **Output:**  Number of successes in each trial having 20 coin tosses = [10 13 9 9 16 7 6 9 11 10 9 13 11 10 10 8 10 13 11 7 12 10 9 12 9 12 10 13 9 8 13 6 10 8 8 11 10 11 11 6 13 11 10 7 8 7 8 14 10 10 10 7 8 11 10 10 17 8 6 10 10 14 11 10 10 10 13 11 11 12 5 10  8 11 9 10 9 7 9 10 11 7 10 5 15 10 11 9 7 14 12 9 12 10 7 11 10 6 10 9]  [Text(0, 0.5, 'Relative Frequency (Probability)'),  Text(0.5, 0, 'Values of Binomial RV'),  Text(0.5, 1.0, 'Binomial Distribution')] |

In this code, we specify *n* = 20 that corresponds to number of trials in each experiment, the option size = 100 in line 7 refers to total runs of the experiment and the value of *p,* the probability of success, is set to 0.5. From the output, we can observe that the probability of getting 10 heads from 20 tosses of a coin is about 0.30. Note that this value may change, if we run the experiment again because out of 20 trials, we randomly get the outcomes. Thus, the event of getting exactly 10 heads in 20 trials will vary if we run the same program again. Therefore, it is important to run the experiment large number of times to get a reliable estimate of the probability distribution of the binomial random variable.

In line 12, we use sns.distplot to plot the distribution of the random variable. Here, the option hist\_kws specifies keywords to be used with histogram, linewidth specifies the width of bars and alpha is used to adjust the color strength. If we run the same code for a size of 2000 times, we get the following output.



We observe that the binomial distribution for sufficiently large number of runs of the experiment approximates to a bell-shaped curve. The continuous Normal or Gaussian random variable, discussed later in this chapter, also have a bell-shaped curve.

## 3.6.2 Uniform Distribution

Auniform distribution is for the continuous valued data. It has a single value, 1/(b-a) which occurs in a certain range [a,b], whereas everything is zero outside that range. We can think of it as an indication of a categorical variable with 2 categories: 0 or the value. The categorical variable may have multiple values in a continuous range between some numbers a and b.



Figure 3.4: A Uniform distribution.

Mathematically, the uniform distribution is given as



To implement the uniform distribution, and visualize the results, we use the following Python script.

|  |
| --- |
| 1. **from** scipy.stats **import** uniform 2. **from** matplotlib **import** pyplot as plt 4. ### generaring 100 samples of a uniform RV 5. uniform\_rv1 = uniform.rvs(size = 100) 6. plt.hist(uniform\_rv1, bins = 10, density = 1) 7. plt.title('Uniform Distribution') 8. plt.xlabel('Value of Uniform RV') 9. plt.ylabel('Relative Frequency of occurrence') 10. plt.show() 12. ### generaring 1000 samples of a uniform RV 13. uniform\_rv2 = uniform.rvs(size = 1000) 14. plt.hist(uniform\_rv2, bins = 50, density=1) 15. plt.title('Uniform Distribution') 16. plt.xlabel('Value of Uniform RV') 17. plt.ylabel('Relative Frequency of occurrence') 18. plt.show()  21. ### generaring 100000 samples of a uniform RV 22. uniform\_rv3 = uniform.rvs(size = 100000) 23. plt.hist(uniform\_rv3, bins = 100, density=1) 24. plt.title('Uniform Distribution') 25. plt.xlabel('Value of Uniform RV') 26. plt.ylabel('Relative Frequency of occurrence') 27. plt.show()   **Output:** |

In lines 6, 14 and 23, the option density = 1 normalizes the frequency of occurrence of each outcome to give us relative frequency of the occurrence instead of the frequency. The option bins specify the number of groups of the data.

The first output image shows a rough approximation of the ideal uniform distribution due to insufficient number of samples of the random variable, i.e., 100. Some of the bins / groups show a value of relative frequency more than 1, others show a relative frequency less than 1. However, the area under the curve of any probability distribution is always equal to 1.

It can be observed that when the size of RV increases, we get a better approximation of ideal uniform distribution as given in the last output where we use 100,000 samples of the random variable.

## 3.6.3 Normal (Gaussian) Distribution

A Normal or Gaussian Distribution is defined by its mean and standard deviation. The data values are spread around the mean value, and the standard deviation controls the spread. A Gaussian distribution has most data values around the mean or center value. A smaller value of standard deviation indicates that data is highly concentrated and vice versa.

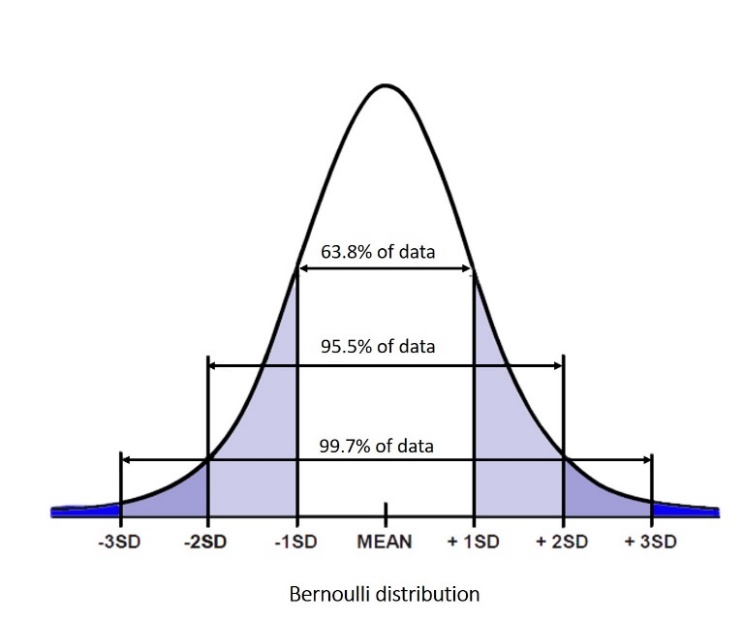
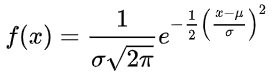
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Figure 3.5: A Gaussian (Normal) distribution. The value of Gaussian RV is on x-axis, whereas the y-axis represents the probability density.

In Figure 3.5, a Normal or Gaussian distribution is shown that is centered at MEAN. Note that 68.3% of the samples of Normally distributed data lies within 1 standard deviation, -1SD to +1SD, on either side of the MEAN. Moreover, 95.5% of the samples of Normally distributed data lies within 2 standard deviations, -2SD to +2SD, on either side of the MEAN. Mathematically, the Gaussian distribution is given as



where e, π, μ and σ are exponential Euler’s number (e = 2.718...), Pi = 3.14159…, the mean and the standard deviation respectively. If we plot this function, we get a bell-curve as shown in Figure 3.5. If a Normal distribution is centered around the value 0 and it has a standard deviation of 1, it is called as a **standard Normal distribution.**

To implement Gaussian random variable and its distribution, type the following Python code.

|  |
| --- |
| 1. **from** scipy.stats **import** norm 2. **import** matplotlib.pyplot as plt 3. **import** numpy as np 5. # generting a Gaussian random vaiable having 50 samples 6. norm\_rv1 = norm.rvs(size=50) 7. **print**(norm\_rv1) 8. **print**('The mean of Normal RV1 is = %0.3f' % np.mean(norm\_rv1)) 9. **print**('The standard deviation of Normal RV2 is = %0.3f' %np.std(norm\_rv1)) 11. # plotting the probability distribution of the generated random variable 12. plt.hist(norm\_rv1) 13. plt.title('Normal (Gaussian) Distribution') 14. plt.xlabel('Value of Gaussian RV') 15. plt.ylabel('Frequency of occurrence') 16. plt.show() 18. # generting a Gaussian random vaiable having 5000 samples 19. norm\_rv2 = norm.rvs(loc= 10, scale = 5, size=5000) 20. #print(norm\_rv2) 21. **print**('The mean of Normal RV2 is = %0.3f' %np.mean(norm\_rv2)) 22. **print**('The standard deviation of Normal RV2 is = %0.3f' %np.std(norm\_rv2)) 24. # plotting the probability distribution of the generated random variable 25. plt.hist(norm\_rv2, bins=100) 26. plt.title('Normal (Gaussian) Distribution') 27. plt.xlabel('Value of Gaussian RV') 28. plt.ylabel('Frequency of occurrence') 29. plt.show()   **Output:**  [ 0.37376069 -0.93269653 1.79103153 -0.17525239 0.7234985 0.4447245  0.58314568 0.06923583 1.76857662 0.02561472 -0.4693774 -0.87189776  0.46097479 0.46539548 0.53569866 -1.94335259 0.18735439 0.08020707  0.61002039 -0.03137532 0.51216684 -0.34661192 -0.67804504 1.17631318  -0.29321776 -0.78823176 -1.65098939 1.38928274 0.24679901 0.06046885  -0.18963214 -0.21655229 0.44973762 -0.5473701 0.17112014 -0.53245687  -0.92840228 -0.53733909 -0.55721695 1.30647944 -0.46756945 -0.2043573  1.55485863 -0.3008035 0.22704038 0.58550703 0.18858938 0.83405865  0.73521948 -0.93849856]  The mean of Normal RV1 is = 0.082  The standard deviation of Normal RV2 is = 1.041    The mean of Normal RV2 is = 9.999  The standard deviation of Normal RV2 is = 4.950 |

We generate a Gaussian RV of 50 samples in line 6 of the code. These values are printed as an array of numbers using the print command given in line 7. Lines 8 and 9 are used to calculate the mean and the standard deviation of the generated random variable. The code to generate the distribution is given in lines 12 to 16. Since the number of points are limited, we get a rough approximation of the ideal normal distribution.

We generate another Normal RV with 5000 samples in line 19 of the code. Its center and spread are specified using the options loc and scale, respectively. The mean and the standard deviation of this RV are 9.99 and 4.95, respectively, which are closed to the ideal values 10 and 5. The second plot in the output shows a reasonably good approximation of the ideal normal distribution.

## 3.6.4 Poisson Distribution

A Poisson distributionis a discrete distribution. Its shape is similar to the continuous Normal distribution but with some *skewness*. A Poisson distribution has relatively uniform spread in all directions just like the Normal distribution; however, the spread becomes non-uniform for increasing values of skewness.

A Poisson distribution with a low mean is highly skewed. The tail of the data extends to the right. However, if the mean is larger, the distribution spreads out, tends to be more symmetric and becomes more like the Gaussian distribution. Mathematically, the probability mass function (PMF) of a Poisson distribution is given as



where the parameters μ and *k* represent the expected (average) rate of occurrence and the number of occurrences of an event, respectively, whereas e is the Euler's number (e = 2.718...) and *k*! is the factorial of *k*.

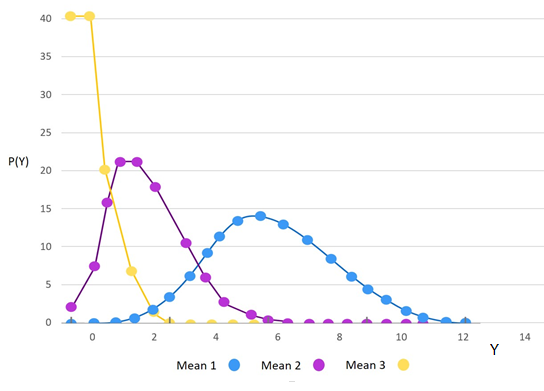
****

Figure 3.6: Poisson distributions with different values of mean.

A Poisson distribution is used to estimate number of times an event can occur within some specified time. It is used for independent events that occur at a constant rate within a given time interval.

To find out the probability of observing *k* events in an interval is given by the aforementioned equation. For instance, the number of users visiting a website in a given interval can be thought of a Poisson process. The number of cars passing a specific portion of a road in a given interval of time is another example of a Poisson process. If the number of cars passing in one hour is 1000, the average number of cars passing per minute, is μ =1000/60. To find the probability that not more than 10 cars pass in a minute is the sum of the probabilities for 0, 1, 2, 3, …, 10 cars.

Type the following Python script to simulate a Poisson distribution.

|  |
| --- |
| 1. **from** scipy.stats **import** poisson 2. **import** matplotlib.pyplot as plt 4. poisson\_rv1 = poisson.rvs(mu=2, size=10000) 5. plt.hist(poisson\_rv1,bins=100, density = 1) 6. plt.title('Poisson Distribution') 7. plt.xlabel('Value of Poisson RV') 8. plt.ylabel('Frequency of occurrence') 9. plt.show()  12. poisson\_rv2 = poisson.rvs(mu=10, size=10000) 13. plt.hist(poisson\_rv2,bins=100, density = 1) 14. plt.title('Poisson Distribution') 15. plt.xlabel('Value of Poisson RV') 16. plt.ylabel('Frequency of occurrence') 17. plt.show()   **Output:** |

It can be observed from the first plot in the output that as the average rate, the mean of the Poisson RV is decreased, it results in a skewed distribution. The first plot is a rough approximation to the Poisson distribution due to limited number of observations. The second plot shows a distribution that is less skewed than the first because it uses an average rate of 10 instead of 2.

|  |
| --- |
| Further Reading |
| More information about functions provided by SciPy.Stats and the probability distributions using Python can be found at  <https://docs.scipy.org/doc/scipy/reference/stats.html>  <https://www.datacamp.com/community/tutorials/probability-distributions-python> |

# 3.7 Exercise Questions

**Question 1:**

The median and mode of the numbers 15, 11, 9, 5, 15, 13, 17 are, respectively:

A.13, 6  
B. 13, 18  
C. 13, 15D. 15, 16

**Question 2:**

A coin is tossed three times. The random variable that describes the number of heads has a probability of \_\_\_\_\_\_\_ for 0 heads.

A. 1/8

B. 2/8

C. 3/8

D. 0

**Question 3:**

Which of the following distributions are used for discrete Random Variables?

A. Gaussian Distribution

B. Poisson Distribution

C. Uniform Distribution

D. None of the mentioned.

**Question 4:**

When we show all possible values of a discrete random variable along with their matching probabilities is called as  
A. Probability Density Function (PDF)

B. Probability Mass Function (PMF)  
C. Cumulative distribution function  
D. All of the above.

**Question 5:**

The expectation or the mean value of a discrete random variable *X* can be given as

A. P(X)  
B. ∑ P(X)  
C. ∑ X P(X)  
D. 1

**Question 6:**

If the expectation of *X* is *E(X)* = 10 and the expectation of *Y* is *E(Y)* = -2, then *E(X –Y)* =?

A. 8  
B. -12  
C. 12D. Cannot be determined.

**Question 7:**

If a random variable assumes all negative values, it will result in \_\_\_\_\_\_\_\_\_

A. Positive probability  
B. Negative probability  
C. Negative as well as positive probabilities  
D. All of the above-mentioned options are possible,

**Question 8:**

If for a random variable X, Σ *P(X)* = *N*2 – 15 then, the value of N will be.  
A. 1  
B. 0  
C. 4  
d) Cannot be determined.

**Question 9:**

If the probability of a random variable *X* is *P(X=0)* = 0.9, and the random variable assumes either value 0 or 1. then the expectation of *X*, *E(X)* would be?

A. 1

B. 0.1

C. 4

D. 0

**Question 10:**

A Normal distribution is symmetric about?

A. Variance  
B. Mean  
C. X-axis  
D. Covariance

**Question 11:**

For a standard Normal random variable, the value of its mean is?

A. Infinity  
B. 0  
C. 1

D. Insufficient data

**Question 12:**

The spread of the normal distribution curve depends upon its.

A. Mean   
B. Standard deviation  
C. Correlation

D. Not given.

Chapter 4: Descriptive Statistics: Measure of Central Tendency and Spread

Descriptive statistics describe the elementary features present in the sample data or the measured / observed values in a statistical experiment. Combined with the visualization tools, descriptive statistics provide the quantitative summary of the data.

Descriptive statistics, as opposed to inferential statistics, describe what is present in the data. It is not used to reach at conclusions based upon the observed data. Inferential statistic, that is the topic of chapter 6 onwards, is used to make decisions after drawing conclusions from the data.

Through the use of descriptive statistics such as a simple average or mean of the data, we can summarize large amounts of observed data in a meaningful way. However, when the data is summarized, we risk losing the details present in the data.

# 4.1 Measuring the Central Tendency of Data

The central tendency of statistical data or a probability distribution gives us an estimate of the middle (center) of our data or a probability distribution. There are three major types of statistics for central tendency:

* The mean,
* The median,
* The mode.

We describe them in the following subsections.

## 

## 4.1.1 The Mean

The mean or the average value of given statistical data is computed by summing up all the values then dividing by total number of values. For a list of numbers: [3, 8, 1, 3, 6, 21, -4],

Mean = [3, 8, 1, 3, 6, 21, -4]/7 = 5.43.

We can also compute the mean or the expected value of a random variable by using the formula for expectation as described in Chapter 3. We take the average of all possible outcomes of a random variable to find the expected value μ as follows:

μ= *E*(*X*) = Σ*x.P*(*X=x*)

μ= *E*(*X*) = (0) (1/4) + (1) (1/2) + (2) (1/4) = 1*.*

The expected value or the mean of rolling a six-sided dice can be computed as follows.

μ= *E*(*X*) = (1) (1/6) + (2) (1/6) + (3) (1/6) +(4) (1/6) + (5) (1/6) + (6) (1/6) = 3.5.

## 4.1.2 The Median

The median is the statistic for central tendency that describes the middle value. To find the median of numeric data, we sort the numbers from smallest to largest. When we have an odd number of data points, the median is found as **(number of data points // 2) +1**, where // represents the floor division. Thus, out of 7 sorted values, the median would be the 4th value.

Median [-4, 1 , 3, 3, 6, 8, 21]=3

If there are an even number of values, there is no middle number. In this case, the median of the list will be the mean of the middle two values within the list.

Median [10, 12, 14, 18, 20, 24, 28, 40]

= (18+20)/2 = 19

## 

## 4.1.3 The Mode

The mode is the value that occurs the most in the observed data. If no number in the list is repeated, then there is no mode for the list.

Mode [-4, 1 , 3, 3, 6, 8, 21]= 3

To find the statistics for central tendency of the data, we may write the following Python script.

|  |
| --- |
| 1. **import** statistics as st 3. raindata = [2, 5, 4, 4, 0, 2, 7, 8, 8, 8, 1, 3] 5. # Printing the Mean, Median and the Mode of the data 6. **print**("mean = %0.3f" %st.mean(raindata)) 7. **print**("median = %0.3f" %st.median(raindata)) 8. **print**("mode = %0.3f" %st.mode(raindata))   **Output:**  mean = 4.333  median = 4.000  mode = 8.000 |

The NumPy library also has functions to compute mean and median, i.e., np.mean() and np.median(). Their usage will also give the same results as st.mean() and st.median(). However, the NumPy library does not have a function to find out the mode of the data.

# 4.2 Measuring the Spread of Data

Spread or dispersion of the statistical data measures the variation of the data around the central tendency such as the mean. There are three common measures of the spread of the data:

* The range,
* The variance,
* The standard deviation.

## 4.2.1 The Range

The range is simple descriptive statistic to measure the spread of the data. It can be found by subtracting the minimum value present in the data from the maximum value. For instance, if the highest value in the data is 80 and the lowest is 25, the range of the given data is 80 - 25 = 55.

## 4.2.2 The InterQuartile Range (IQR)

InterQuartile Range (IQR) gives us a better picture of the underlying data as compared to the simple range. In IQR, we divide our data into 4 quarters after we sort it in ascending order. A popular plot that shows these quartiles is known as a Box and Whisker plot shown in Figure 4.1.

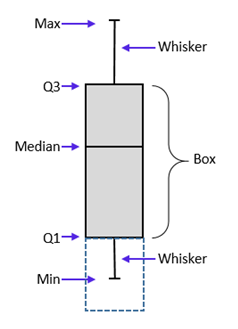


Figure 4.1: A Box and Whisker plot. The length of the box represents IQR.

The IQR is simply the difference between third and the first quartiles or the length of the box in the plot:

IQR = Q3 – Q1

To calculate IQR, we can enter the following script.

|  |
| --- |
| 1. ### InterQuartile Range 3. **import** pandas as pd 4. student\_frame = pd.DataFrame({'Student Name': ['A','B','C', 'D','E','F','G'], 5. 'Sex':['M','F','M','F','F','M','M'], 6. 'Age': [10, 14, 18, 15, 16, 15, 11], 7. 'School': ['Primary','High', 'High', 'High', 'High','High','Primary']}) 9. # 25% or quartile 1 (Q1) 10. Q1 = student\_frame.quantile(0.25) 11. # 75% or quartile 3 (Q3) 12. Q3 = student\_frame.quantile(0.75) 13. # InterQuartile Range (IQR) 14. IQR = Q3 - Q1 15. **print**('The Q1 = %.3f, Q3 = %.3f and the InterQuartile Range (IQR) = %0.3f' %(Q1, Q3, IQR))   **Output:**  The Q1 = 12.500, Q3 = 15.500 and the InterQuartile Range (IQR) = 3.000 |

The only numeric variable in our data is ‘Age’, whose IQR is found using the quantile () function of the Pandas library. We store our data in a Pandas DataFrame in lines 4 to 7.

Specifying any quantile such as 0.25 (25%), 0.5 (50%) and 0.75 (75%) as an argument to the quantile () function (lines 10 and 12 ) give the 25th percentile (the first quartile - Q1), the 50th percentile (the median - Q2) and the 75th percentile (the third quartile - Q3) of the values. The difference Q3 – Q1 in line 14 of the code gives us IQR.

## 4.2.3 The Variance

Suppose we are measuring the heights of a group of people. Most measurements lie within an acceptable range. However, due to some problem with the measuring scale or a human error, one measurement is recorded as 300cm. If the minimum height in the data is 150cm. The range would be 300-150 = 150cm, which is incorrect in this case. A very small or very large unacceptable value in the collected data is called as an **outlier.** The range is highly susceptible to outliers in the data, and the range is significantly exaggerated.

A better and detailed descriptive statistic to measure the spread of the data under possible outliers is the variance. The variance shows the relationship of every observed value present in the data to the mean of the data. The variance σ2 is a measure of the variability within the data around the mean value. The variance of a random variable *X* can be computed as follows.



where *E* represents the mean or the expected value, μ is the mean of the data points and *f*(*x*) represents the probability distribution.

For instance, we have the following probability distribution of a random variable:

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| *x* | 0 | 1 | 2 | 3 | 4 |
| *f(x)* | 0.2 | 0.1 | 0.3 | 0.3 | 0.1 |

To compute the variance of a random variable, we:

1. compute its mean,
2. find the squared deviation of all the possible values of the random variable form the mean,
3. calculate the expectation or the mean of the squared differences from 2.

The mean μ = Σ x *f*(*x*)

= (0)(0.2) + (1)(0.1) + (2)(0.3) + (3)(0.3) + (4)(0.1) = 2.0.

*E* [(*X-* μ)2] = Σ (x - μ)*2* f(x)

= (0 − 2)2(0.2) + (1 − 2)2(0.1) + (2 − 2)2(0.3) + (3 − 2)2(0.3) + (4 − 2)2(0.1) = 1.6.

For a continuous random variable or a continuous range of data, we cannot sum up infinite number of values. In this case, we replace the summation with integration to find out the mean or the variance.

As mentioned in Section 2.3 that in statistical studies or experiments, numerous observations collected from the study constitute the data, and an assortment of all possible outcomes of the experiment are called the **population**. Since we cannot observe the whole population, we take a **sample** that is a small portion of the population.

There is a slight difference between the variance of a sample and that of the whole population. In the calculation of population variance, we divide by *N*. However, in case of sample variance, we divide by (*N*-1), where *N* represents number of data points. Therefore, we get slightly different results. To find out the variance of population, we use the following formula:



For the sample variance, we use the formula given below:



The reason why we divide by (*N*-1) instead of *N* is that a sample taken from the population does not provide us with the complete information of the population. We can just estimate the variance of the population based on the sample data. Thus, the research in statistics suggests that subtracting one from the total number of data points, i.e., (*N*-1) gives a better estimate of the population variance as compared to the case when we divide by *N*.

## 

## 4.2.4 The Standard Deviation

The standard deviation is just the square root of the variance.

STD = √σ2 = σ

To find range, variance and standard deviation of the quantities, we may write the following Python script.

|  |
| --- |
| 1. **import** statistics as st 3. raindata = [2, 5, 4, 4, 0, 2, 7, 8, 8, 8, 1, 3] 5. data\_range = max(raindata)- min(raindata) 6. # Range of the data 7. **print**("The range of the data is = %0.3f"  % data\_range) 9. # population variance 10. **print**("population variance = %0.3f"  %st.pvariance(raindata)) 11. # population standard deviation 12. **print**("population standard deviation = %0.3f" %st.pstdev(raindata)) 14. # sample variance 15. **print**("variance = %0.3f" %st.variance(raindata)) 16. # sample standard deviation 17. **print**("standard deviation = %0.3f" %st.stdev(raindata))   **Output:**  The range of the data is = 8.000  population variance = 7.556  population standard deviation = 2.749  variance = 8.242  standard deviation = 2.871 |

If the statistical data contains multiple attributes / features, we can still compute variance and standard deviation of each feature. For example, we have been given the names, age and the grades of multiple students. We create a Pandas DataFrame to store multiple features of the data together. Pandas built-in statistical functions are then used to compute simple descriptive statistics of the data. The following Python script illustrates this concept.

|  |
| --- |
| 1. **import** pandas as pd 2. #Create a Dictionary of series 3. mydata = {'Name':pd.Series(['Liam',   'Olivia', 'Noah',   'Emma',     'Oliver', 'Ava', 4. 'William','Sophia', 'Elijah', 'Isabella', 'James',  'Charlotte']), 5. 'Age':pd.Series([20,24,21,23,32,25,23,31,30,32,26,22]), 6. 'Grades':pd.Series([3.23,3.24,3.98,2.56,3.20,3.6,3.8,3.7,2.98,3.8, 3.10,3.65])} 7. #Creating a Pandas DataFrame 8. my\_df = pd.DataFrame(mydata) 10. # Calculating the variance and the standard deviation of the data 11. **print**('The variance of the data is', my\_df.var()) 13. **print**('\nThe standard deviation of the data is', my\_df.std())   **Output:**  The variance of the data is Age 19.295455  Grades 0.174115  dtype: float64  The standard deviation of the data is Age 4.392659  Grades 0.417271  dtype: float64 |

In lines 3 to 6, we specify the features of the data as Pandas Series objects. Line 8 creates Pandas DataFrame from multiple Series objects. Finally, lines 11 and 13 compute the sample variance and the sample standard deviation of each numeric feature present in the data. Note that the descriptive statistics such as variance and standard deviation are not defined for non-numeric data such as names of the students.

# 4.3 Covariance and Correlation

Up to this point in this chapter, we have provided simple descriptive statistics for univariate data. This means that we have discussed measures of central tendency of the data such as mean, median and mode, and measures of spread of the data such as range, standard deviation and variance. These statistics are applied to *single variable / feature/ attribute* of the data; hence, the name univariate descriptive statistics.

Suppose we want to know the relationship between two variables present in the data such as student age and the grades they have obtained. In this case, we resort to *Bivariate Descriptive Statistics.* The most common bivariate statistics are

1. The covariance,
2. The correlation.

**The covariance** is used to find the relationship / dependency between two variables. It is defined as



where x and y are two features present in the data, μx and μy are the means or expected values of x and y, and *E* represents the expectation operator. The covariance between two features can be positive or negative.

The terms (x- μx) and (y- μy) are computed for each data point. These are multiplied together, and finally mean or average of all the products is calculated to find a single number as the covariance between features x and y.

Consider the case when most of data points result in a positive result for both terms (x- μx) and (y- μy). In this case, the product (x- μx) (y- μy) would be positive. Moreover, if most of data points result in a negative result for the terms (x- μx) and (y- μy) are also negative. In this case, the product (x- μx) (y- μy) would again be positive. We shall get a positive value for the covariance. We say that there is a positive relationship between features.

Conversely, if positive (x- μx) values have corresponding negative (y- μy) values and vice versa, the product (x- μx) (y- μy) would be negative. Hence, the covariance would be negative. We say that there is a negative relationship between features when we get a negative result after the computation of the covariance.

**The correlation** or the correlation coefficient is obtained by normalizing the covariance. It is obtained when we divide the covariance by the product of individual standard deviations of the variables.



While the covariance can result in any arbitrary positive or negative real number, the correlation is always between -1 to 1 due to the normalization by the individual standard deviations. Thus, the correlation is used mostly to identify the strength of the relationship between two features.

To find the covariance and the correlation between two different features, we may use the following code.

|  |
| --- |
| 1. **import** numpy as np 2. mycov = np.cov([1, 2, 3], [1.0, 2.5, 7.5]) 3. **print**('The covariance between x and y is \n') 4. mycov   **Output:**  array([[ 1.    ,    3.25 ],           [ 3.25   , 11.58333333]])     1. mycorr = np.corrcoef([1, 2, 3], [1.0, 2.5, 7.5]) 2. **print**('The correlation between x and y is \n') 3. mycorr   **Output:**  array([[1.    ,    0.95491911],        [0.95491911,    1. ]]) |

The output of this code shows 4 values instead of a single value for the covariance and the correlation. The reason is that the NumPy functions cov () and corrcoef () gives us variances and the normalized variances on diagonal entries, and the covariance and the correlation coefficient on off-diagonal entries, respectively. We see same values on off-diagonal entries because the covariance and the correlation coefficient between x and y is the same as that of between y and x.

|  |
| --- |
| Further Reading |
| More information about descriptive statistics and Python code to implement these statistics can be found at  <https://realpython.com/python-statistics/>  <https://www.tutorialspoint.com/python_pandas/python_pandas_descriptive_statistics.htm>  <https://www.dataquest.io/blog/basic-statistics-with-python-descriptive-statistics/> |

# 4.4 Exercise Questions

**Question 1:**

An outlier can be defined as:

* 1. A variable that cannot be observed
  2. A variable that is hard to quantify
  3. A missing data value
  4. An extreme value

**Question 2:**

Variance of the data is calculated from

A. The mode

B. The Mean

C. The Median

D. None of the mentioned

**Question 3:**

Variance and standard deviation of the data

A. can be negative

B. are always positive

C. can be both negative and positive

D. can never be zero.

**Question 4:**

Covariance and correlation between two features of the data

A. can be negative

B. are always positive

C. can be negative or positive

D. can never be zero.

**Question 5:**

The median of the data [5, -9, 7, 6, -20, 20] is

A. 5

B. 6

C. 5.5

D. Not given

**Question 6:**

The mode of the data [18, 11, 10, 12, 14, 4, 5, 11, 5, 8, 6, 3, 12, 11, 5]

A. 11

B. 5

C. 0

D. No unique mode

**Question 7:**

The range of the data [21, 18, 9, 12, 8, 14, 23] is

A. 23

B. 8

C. 15

D. 7

**Question 8**

If the sample variance of the data [21, 18, 23] is 2.51, the population variance would be

A. less than the sample variance

B. more than the sample variance

C. equal to the sample variance

D. cannot be determined.

Chapter 5: Exploratory Analysis: Data Visualization

# 5.1 Introduction

In the previous chapter, we have seen that descriptive statistics provides useful summary by exploring the underlying statistical data. In this chapter, we perform further exploration using plots and visualization tools.

The purpose of exploratory analysis is to get familiarization with the structure and important features of the data. In exploratory analysis, we employ numerous techniques to reveal the structure of the data. These include:

* **Univariate visualization** is used to generate summary statistics for each numeric variable of the data. We summarize our dataset through descriptive statistics that uses a variety of statistical measurements to better understand the dataset. Visualization tools such as bar plots and histograms are used for univariate visualization.
* **Bivariate visualization** is used to find the relationship between two variables of the data. It uses correlations, scatter and line plots to reveal relationship between two variables of the data.
* **Multivariate visualization** is performed to understand relations between multiple variables of the data. It uses line plots, scatter plots and matrices with multiple colors.

Visualization tools help us reveal the structure of variables, discover data patterns, spot anomalies such as missing values and outliers, and check assumptions about the data.

In the following sections, we present different type of visualization tools and explain the process of exploratory analysis along with practical Python examples.

# 5.2 Bar (Column) Charts

If we have categorical or discrete data that can take on a small set of values, we use bar charts to show the categories as rectangular bars whose lengths are proportional to the values belonging to these categories. Bar charts are sometimes referred to as column charts.

As an instance, to display the number of students studying different subjects as a bar chart, type the following Python script.

|  |
| --- |
| 1. **import** matplotlib.pyplot as plt 3. fig = plt.figure() 4. ax = fig.add\_axes([0,0,1,1]) 6. name\_of\_class = ['Python', 'Statistics', 'Machine Learning', 'Data Science', 'Big Data'] 7. students = [33,27,25,39,32] 9. ax.bar(name\_of\_class,students) 10. plt.ylabel('Number of students') 11. plt.title('Subjects enrolled by students') 13. plt.show()   **Output:** |

The line 3 create a figure object whose options can be set. We use line 4 to set the size of the figure and the spacing between the subplots. The add\_axes (x0, y0, dx, dy) method takes a list of four values: x0, y0, dx, and dy for the subplot. The values x0 and y0 are the coordinates of the lower left corner of the subplot, and dx and dy are the width and height of the subplot, with all values specified in relative units: 0 represents left bottom corner and 1 represents top right corner). In line 9, we call the bar () function using the axis object ax to plot the bar chart.

To plot multiple variables on a bar chart, we may type the following Python script.

|  |
| --- |
| 1. **import** numpy as np 2. **import** matplotlib.pyplot as plt  5. scores\_Jack = ( 95 ,  85 ,  74 ,  75 ,  80 ) 6. scores\_John = ( 85 ,  82 ,  64 ,  70 ,  82 ) 8. # create plot 9. fig, ax = plt.subplots () 10. indexes = np.arange (len (scores\_Jack)) 12. bar\_width =  0.4 14. data1 = plt.bar (indexes, scores\_Jack, bar\_width, color = 'b' , label = 'Jack' ) 16. data2 = plt.bar (indexes + bar\_width, scores\_John, bar\_width, color = 'r' , label = 'John' ) 18. plt.ylabel ( 'Scores' ) 19. plt.title ( 'Scores by Students' ) 20. plt.xticks (indexes + bar\_width / 2 , ( 'Maths' ,  'Statistics' ,  'Python' ,  'Data Science' ,  'English' )) 21. plt.legend () 23. plt.tight\_layout () 24. plt.show ()   **Output:** |

In the bar chart given above, we plot the scores obtained by two students in 5 different subjects. We create a variable *indexes* that is used as an independent variable to keep track of location on the x-axis to plot the scores obtained in subjects. Note that in lines 16, we use *indexes + bar\_width* instead of *indexes* as used in line 14*,* to specify the location of the bars for the student John. This is done to separate bars of both students from each other. Line 20 shows the use of the method xticks () to specify the location of the subject names at the middle of both bars, i.e., *indexes + bar\_width/2.*

We can add titles, labels and legends to the generated plots. To add titles, labels and legend to a plot, we use the title, xlabel, ylabel and legend methods of the pyplot module, respectively. We pass string values to these methods, which appear on the plots as shown in the output.

# 5.3 Pie Charts

A pie chart is a circular statistical chart that is used to display the percentage distribution of **categorical variables**. Categorical variables are those variables which represent the categories such as gender, name of countries and type of pet. The area of the whole chart represents 100% or the whole data. The areas of the pies in the chart denote the percentage of shares the categories have in the data.

Pie charts are popular in business communications because they give a quick summary of business events such as sales and operations. Pie charts can be used, for example, to summarize results from surveys and usage of memory in a computer system.

To draw a pie chart, we use the function pie() in the pyplot module. The following Python code draws a pie chart showing the number of cars by types.

|  |
| --- |
| 1. # Import libraries 2. **from** matplotlib **import** pyplot as plt 3. **import** numpy as np 5. cars = ['FORD', 'TESLA', 'JAGUAR','AUDI', 'BMW',  'MERCEDES'] 7. numbers\_cars = [13, 26, 39, 13, 39, 78] 9. fig = plt.figure(figsize =(10, 7)) 10. plt.pie(numbers\_cars, labels=cars, autopct='%1.1f%%') 12. plt.show()   **Output:** |

The ***autopct***='%.1f%%' string formatting is used for the formatting of how the percentages appear on the pie chart.

|  |
| --- |
| **Further Readings-** **Matplotlib Plots** |
| To study more about Matplotlib plots, please check Matplotlib’s official documentation for plots.  <https://matplotlib.org/tutorials/introductory/pyplot.html#sphx-glr-tutorials-introductory-pyplot-py>  You can explore more features of Matplotlib by searching and reading this documentation. |

# 5.4 Line Plots for Continuous Data

Line plots are useful to convey the behavior of one or more variables that change over space or time. Line plots display the trend of data along a scale divided into equal intervals. Let us generate a simple line plot.

|  |
| --- |
| 1. **import** matplotlib.pyplot as plt 3. Year = [2000,2001,2002,2003,2004,2005,2006,2007,2008,2009] 4. inflation\_rate = [2.8, 3.2, 4, 3.7, 1.2, 6.9, 7, 6.5, 6.23, 4.5] 6. plt.plot(Year, inflation\_rate, color='red', marker='o') 7. plt.title('Inflation Rate Vs Year', fontsize=14) 8. plt.xlabel('Year', fontsize=14) 9. plt.ylabel('Inflation Rate', fontsize=14) 10. plt.grid(True) 11. plt.show()   **Output:** |

In this graph, we have plotted unemployment rate of adults belonging to an arbitrary location against years from 2000 to 2009. We use the function plot() from the pyplot module of Matplotlib, pass it the values for the values of years and unemployment rate as x and y axes to generate a line plot.

Multiple plots can be drawn on the same figure as shown in the Python script given below.

|  |
| --- |
| 1. **import** matplotlib.pyplot as plt 2. **import** numpy as np 3. **import** pandas as pd 5. df=pd.DataFrame( 6. {'x': range(1,21), 7. 'line1': np.random.randn(20), 8. 'line2': np.random.randn(20)+range(1,21), 9. 'line3': np.random.randn(20)+range(21,41) 10. }) 12. # multiple line plots 13. plt.plot( 'x', 'line1', data=df, marker='o', markerfacecolor='blue', markersize=12, color='r') 14. plt.plot( 'x', 'line2', data=df, marker='', color='g', linewidth=2) 15. plt.plot( 'x', 'line3', data=df, marker='', color='b', linewidth=2, linestyle='dashed') 16. plt.legend()   **Output:** |

Here, we plot 3 different data variables: line1, line2 and line3 against the variable x. We have used DataFrame from Pandas library to save all 4 variables. We have used different options inside plt.plot() function for distinguishing plots from each other and for better visualization. The options marker, markerfacecolor, color, linewidth and markersize are used to adjust the marker type, line color, line thickness and marker size, respectively.

# 5.5 Scatter Plot

A scatter plot is used to visualize the relationship between two variables in two-dimensions. It uses dots or marks to plot values of two variables, one along the x-axis and the other along the y-axis.

If an increase in one variable causes an increase in another variable and vice versa, we can conclude that there is a positive linear relationship between two variables. However, if increasing the first variable reveals a decrease in the second variable, we say that there is a negative linear relationship between both variables.

To plot a scatter plot, type the following piece of code

|  |
| --- |
| 1. **import** matplotlib.pyplot as plt 2. **import** statistics as st 4. month\_names = ['Jan', 'Feb', 'Mar', 'Apr', 'May', 'Jun', 'Jul', 'Aug', 'Sep', 'Oct', 'Nov', 'Dec'] 5. months = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12] 6. raindata = [2, 5, 4, 4, 0, 2, 7, 8, 8, 8, 1, 3] 7. fig, ax = plt.subplots(nrows=1, ncols =1) 9. ax.set\_title("Measures of Center") 10. ax.set\_xlabel("Month") 11. ax.set\_ylabel("Number of times it rained") 13. ax.scatter([1,2,3,4,5,6,7,8,9,10,11,12],raindata) 15. plt.xticks(np.arange(12)+1, month\_names, color = 'black') 17. # draw points for mean, median, mode 18. ax.plot([st.mean(raindata)], [st.mean(raindata)], color='r', marker="o", markersize=15) 19. ax.plot([st.median(raindata)], [st.median(raindata)], color='g', marker="o", markersize=15) 20. ax.plot([st.mode(raindata)], [st.mode(raindata)], color='k', marker="o", markersize=15) 22. # Annotation 23. plt.annotate("Mean",  (st.mean(raindata), st.mean(raindata)+0.3),color="r") 24. plt.annotate("Median", (st.median(raindata), st.median(raindata)-0.7),color="g") 25. plt.annotate("Mode", (st.mode(raindata), st.mode(raindata)-0.7),color="k") 27. plt.show()   **Output:** |

We plot measures of center of given data in this plot. After settings display options in lines 7 to 11, the function scatter () in line 13 plots the number of rainy days in 12 months of the year.

We plot the mean, the median and the mode of the given data as well using commands given in lines 18 to 20. Line 23 t0 25 are used to annotate the measures of center of the data.

# 5.6 Histogram

A histogram is a bar chart that shows the frequency distribution or shape of a numeric feature in the data. This allows us to discover the underlying distribution of the data by visual inspection. To plot a histogram, we pass a collection of numeric values to the method hist () of Matplotlib.pyplot package.

For example, the following code plots the distribution of values of a Normal random variable.

|  |
| --- |
| 1. **import** matplotlib.pyplot as plt 2. **import** numpy as np 4. #Creating a normal random variable 5. randomNumbers = np.random.normal(size=10000) 7. #Draw a histogram 8. plt.figure(figsize=[10,8]) 10. plt.hist(randomNumbers) 11. plt.title("Histogram") 12. plt.xlabel("Value") 13. plt.ylabel("Frequency") 14. plt.show()   **Output:** |

SciPy.Stats package can be used to generate random variables. However, here we have used NumPy’s random.normal() method to generate a Normally distributed data. The default settings of this method generate a random variable of zero mean and unit standard deviation.

The plot shown in the output of the program reveals that more than 2500 data points out of 10000, have a value around 0. A few values are less than -3 and greater than 3. By default, the method hist () uses 10 bins or groups to plot the distribution of the data. We can change the number of bins in line 10 of the code by using the option **bins**.

|  |
| --- |
| 1. plt.hist(randomNumbers, bins=100) 2. plt.show()   **Output:** |

This plot is smoother than the previous one which was generated using 10 bins. It is obvious from this plot that the generated data follows a Normal or a Gaussian distribution (bell curve).

It is also possible to generate multiple histograms on the same plot. The following example illustrates this concept.

|  |
| --- |
| 1. plt.figure(figsize=[10,8]) 3. # Creating random numbers using numpy 4. x = 0.75 \* np.random.randn(10000) 5. y = 1.5 \* np.random.randn(10000) + 5 7. plt.hist([x, y], bins=100, label=['Zero mean, 0.75 STD','Five mean, 1.5 STD']) 8. plt.xlabel('Value',fontsize=12) 9. plt.ylabel('Frequency',fontsize=12) 10. plt.title('Two Histograms Together',fontsize=12) 11. plt.legend() 13. plt.show()   **Output:** |

In line 1 of the code, we adjust the size of the figure. Lines 4 and 5 create two Normal random variables. The multiplying factors 0.75 and 1.5 specify the standard deviations of both variables x and y, respectively. The addition of 5 in line 5 shifts the center of y from 0 to 5. We specify labels in the function plt.hist () in line 7. The invocation of plt.legend() puts these labels on the generated plot.

# 5.7 Creating a Frequency Distribution

A frequency distribution shows the frequency of occurrence of various outcomes in the sample data. Sometimes, the frequency distribution is displayed as a plot or a graph. We can either use a bar chart or a histogram to plot the frequency distribution. Each entry of this distribution shows the frequency of occurrence of different values within specific groups. As an instance, the following table shows the frequency of people having weight in the specified range.

Table 5.1: Frequency of occurrence of people having weight in the specified range.

|  |  |
| --- | --- |
| **Weight range** | **Frequency** |
| less than 50 kg | 4 |
| 50–60 kg | 15 |
| 60–70 kg | 20 |
| 70–80 kg | 22 |
| 80–90 kg | 5 |
| 90–100 kg | 2 |

The following code utilizes a bar chart to plot the frequency distribution given in the Table 5.1.

|  |
| --- |
| 1. **import** numpy as np 2. **import** matplotlib.pyplot as plt 4. weight\_range = ['less than 50 kg', '50–60 kg', '60–70 kg', '70–80 kg', '80–90 kg', '90–100 kg'] 5. num\_students = [4, 15, 20, 22, 5, 2] 7. # plotting the frequency distribution 8. plt.figure(figsize=[10,8]) 10. plt.bar(weight\_range, num\_students) 11. plt.xlabel('Range of weights',fontsize=12) 12. plt.ylabel('Frequency',fontsize=12) 13. plt.title('Number of students in different ranges of weight', fontsize=12) 14. plt.show()   **Output:** |

The bar () method takes values of x and y axis and plots the values of y as vertical bars.

When we have information of both x and y axis, we use a bar chart to show the frequency distribution. However, there are cases, when we do have values for y axis but we do not know what values of x, they belong to. In this case, it is more convenient to use the histogram to plot the frequency distribution. The histogram splits the data into small equal-sized bins, and places the frequency of occurrence of y variables in the respective bins. We do have the option to change the number of bins for a better display of the data.

The following code plots the frequency distribution as a histogram.

|  |
| --- |
| 1. #Plotting the Frequency Distribution with Histogram 2. **import** numpy as np 3. **import** matplotlib.pyplot as plt 5. #Creating a normal random variable 6. randomNumbers = np.random.normal(size=1000) 8. plt.figure(figsize=[8,6]) 9. plt.hist(randomNumbers, width = 0.5, color='r',alpha=0.7) 10. plt.grid(axis='y', alpha=0.5) 11. plt.xlabel('Value',fontsize=12) 12. plt.ylabel('Frequency',fontsize=12) 13. plt.title('Normal Distribution Histogram',fontsize=12) 14. plt.show()   **Output:** |

In this example, we generate 1000 data points from the normal distribution in line 6. Since we do not have the information of the number of groups to divide our data into, we use the histogram instead of the simple bar chart. We draw the histogram using hist () function in line 9 of the code. The options width, color and alpha are used to adjust the width of the bars, their color and the color transparency, respectively.

# 5.8 Relation between PMF, PDF and Frequency Distribution

It is important to know that there is a close link between frequency distributions and the probability mass and density functions. If we normalize the frequency of occurrence given on the y-axis of a frequency distribution plot (either bar chart or a histogram), we get normalized or relative frequency. The sum of all the relative frequencies of occurrence of all the events or groups of data equates to 1.

We also know that the sum of probabilities of all the possible outcomes related to values of random variables is also 1. Thus, once we have a frequency distribution plot of a random variable, we normalize its y-axis, i.e., we get the relative frequency. In this way, we obtain the probability function of the random variable. Now, if the random variable is discrete, we get the probability mass function (PMF). For continuous random variables, we get the probability density function (PDF).

# 5.9 Cumulative Frequency Distribution and Cumulative Distribution Function (CDF)

A cumulative frequency distribution represents the sum of frequencies of occurrences of a group and all groups below it in a frequency distribution. This implies that we add up the frequencies of all the groups below a certain group to find the cumulative frequency of that group. We continue the example given in Table 5.1 to draw the cumulative frequency distribution.

Table 5.2: Cumulative frequency of occurrence of people having weight equal to or less than a particular range.

|  |  |  |
| --- | --- | --- |
| **Weight range** | **Frequency** | **Cumulative Frequency** |
| less than 50 kg | 4 | 4 |
| 50–60 kg | 15 | 19 |
| 60–70 kg | 20 | 39 |
| 70–80 kg | 22 | 61 |
| 80–90 kg | 5 | 66 |
| 90–100 kg | 2 | 68 |

If we have to find out the number of people who have their weights up to 70 kg, we have to add the frequency of people in the range less than 50 kg, 50-60 kg and 60-70 kg. In this case, we shall get a cumulative frequency of 39 given in the 3rd column of Table 5.2.

The following code plots the cumulative frequency distribution as a bar chart.

|  |
| --- |
| 1. **import** matplotlib.pyplot as plt 2. **import** numpy as np 4. weight\_range = ['less than 50 kg', 'up to 60 kg', 'up to 70 kg', 5. 'up to 80 kg', 'up to 90 kg', 'up to 100 kg'] 7. num\_students = [4, 15, 20, 22, 5, 2] 8. cum\_freq\_students = np.cumsum(num\_students) 10. # plotting the frequency distribution 11. plt.figure(figsize=[10,8]) 13. plt.bar(weight\_range, cum\_freq\_students) 14. plt.xlabel('Range of weights',fontsize=12) 15. plt.ylabel('Frequency',fontsize=12) 16. plt.title('Number of students up to a specific weight', fontsize=12) 17. plt.show()   **Output:** |

The output of the program shows that the cumulative frequency distribution is an increasing function because the frequency of occurrence is never negative.

For the sake of completeness, we plot the cumulative frequency distribution as a continuous line. Suppose, we want to know the number / percentage of people among a group who own at least a specific number of cars. We have a total of 600 people that have at least 1 car. We use Pandas to store the data and first compute its frequency distribution as follows

|  |
| --- |
| 1. **import** pandas as pd 2. **import** matplotlib.pyplot as plt 4. count\_people = 600 6. people\_car\_data = {'Number of cars': [1, 2, 3, 4, 5, 6, 7, 8, 9, 10], 7. 'People having number of cars': [300, 150, 100, 15, 10, 8, 6, 5, 4, 2]} 9. df = pd.DataFrame(data=people\_car\_data) 10. **print**(df) 12. df.plot(kind='bar', x='Number of cars', y='People having number of cars', 13. figsize=(8, 6), color='r'); 15. plt.grid(axis='y', alpha=1) 16. plt.title("Count of People for Number of cars they own", y=1.01, fontsize=12) 17. plt.ylabel("Count of People", fontsize=12) 18. plt.xlabel("Number of Cars", fontsize=12)   **Output:**  Number of cars People having number of cars  0 1 300  1 2 150  2 3 100  3 4 15  4 5 10  5 6 8  6 7 6  7 8 5  8 9 4  9 10 2  Text(0.5, 0, 'Number of Cars') |

From this frequency distribution, we compute and plot cumulative frequency distribution as follows.

|  |
| --- |
| 1. # Cummulative Frequency Graph 3. df['totalPeople'] = df['People having number of cars'].cumsum() 4. **print**(df) 6. df.plot(x='Number of cars', y='totalPeople', kind='line', 7. figsize=(8, 6)) 9. plt.axhline(y=count\_people, color='green', linestyle='--') 10. plt.title("Cummulative Frequency of People having a certain number of cars", fontsize=12) 11. plt.ylabel("Total of People having a certain number of cars", fontsize=12) 12. plt.xlabel("Number of Cars", fontsize=12)   **Output:**  Number of cars People having number of cars totalPeople  0 1 300 300  1 2 150 450  2 3 100 550  3 4 15 565  4 5 10 575  5 6 8 583  6 7 6 589  7 8 5 594  8 9 4 598  9 10 2 600  Text(0.5, 0, 'Number of Cars') |

A cumulative frequency distribution plot of a random variable with normalized y-axis, i.e., relative frequency gives us the cumulative distribution function (CDF). Dividing the right side of the command given in line3 of the previous program, df['totalPeople'] = df['People having number of cars'].cumsum(), results in the normalized y-axis. Hence, we get the cumulative distribution function (CDF). Mathematically,



where *F(x)* is the CDF and the right-hand side of the equation says that the probability of the random variable *X* having any value equal to or less than value *x.*

# 5.10 The Quantile Function

A quantile is a cut point that divides the range of a probability distribution or sample observations into equal sized intervals having equal probabilities. A famous example of a quantile is the median of the data or a probability distribution. The median is the point such that half of the data have values less than the median and the remaining half values are greater than the median. The median is also referred to as 2-quantile.

The division of a distribution into four equal parts constitutes four ***quartiles***, whereas the division into 100 equal parts makes up 100 ***percentiles***. When the distribution is divided into 10 equal parts, we get 10 ***deciles***.

The **quantile function** also known as **inverse CDF** or the **percent-point function** (**PPF**) is associated with the distribution of random variables. While a CDF tells us the probability of random variable *X* to have a value equal to or less than a specific value *x*, a quantile function tells us the value of the random variable such that the probability of the variable being less than or equal to that value equals the given probability. Mathematically, the quantile function *Q(P)* is given as



or

,

where min on the right side of the equation means the quantile function returns the minimum value of *x* from all those values such that their distribution *F*(*x*) equals or exceeds probability *p,* and ∀*p* means all probability values lie in 0 to 1 range. The value *x* returned by *Q(P)* obeys the CDF equation



The PPF or the quantile function can be used to get the values / samples of the variable *X* from the given distribution. If *F*(*x*) is the distribution function, we can use the quantile function to generate the random variable that has *F*(x) as its distributions function.

**Example:** Suppose a random variable *X* has the following probability mass *P(X)* and the probability distribution *F(X)*

*X*=[−2 0 1 3]

*P(X)*=[0.2 0.1 0.3 0.4]

*F(X)*=[0.2 0.3 0.6 1]

We plot both F(X) and the quantile function using the following Python script.

|  |
| --- |
| 1. ## Quantile function 3. **import** numpy as np 4. **import** matplotlib.pyplot as plt 6. x =  [-2,  0,  1,  3] 7. cdf\_func = [0.2, 0.3, 0.6, 1] 9. ## Plot of the cumulative distribution  function 10. plt.step(x,cdf\_func) 11. plt.xlabel('Values of RV X') 12. plt.ylabel('Probability') 13. plt.title('Cumulative Distribution Function') 14. plt.show() 16. ## Plot of the quantile function 17. plt.step(cdf\_func,x, color='r') 18. plt.xlabel('Probability') 19. plt.ylabel('Values of RV X') 20. plt.title('Quantile Function') 21. plt.show()   **Output:** |

It is obvious from the outputs that the quantile function is obtained by reflecting the graph of the CDF about the horizontal axis and rotating the resulting graph in the counter clockwise direction. A value of the RV *X,* for example*,* 1in the CDF graph gives us 0.6 value of the probability.

In a similar way, getting any value of *X* less than or equal to 1 has a corresponding probability value of 0.6 in the quantile plot. Since the horizontal axis is a probability, it goes from zero to one. The vertical axis goes from the smallest to the largest value of the cumulative distribution function of the random variable.

For a normal RV, we plot its PDF, CDF and the quantile function using the Python script given below.

|  |
| --- |
| 1. **from** scipy.stats **import** norm 2. **import** numpy as np 3. **import** matplotlib.pyplot as plt 5. # Generating a range of values from -4 to 4 because a standard Normal RV has most values between -3 to 3 6. x= np.arange(-4,4,0.01) 8. # Plot of PDF 9. plt.plot(x,norm.pdf(x)) 10. plt.xlabel('Values of RV X') 11. plt.ylabel('Probability') 12. plt.title('Probability Density Function of a Normal RV') 13. plt.show() 15. # Plot of CDF 16. plt.plot(x,norm.cdf(x)) 17. plt.xlabel('Values of RV X') 18. plt.ylabel('Probability') 19. plt.title('Cumulative Distribution Function of a Normal RV') 20. plt.show() 22. # Plot of Inverse CDF (or PPF or Quantile fucntion) 23. plt.plot(x, norm.ppf(x)) 24. plt.xlabel('Probability') 25. plt.ylabel('Values of RV X') 26. plt.title('Quantile Function of a Normal RV') 27. plt.show()   **Output:** |

# 5.11 The Empirical Distribution Function

The empirical distribution function (EDF) or simply empirical distribution is used to describe a sample of observations of a variable. The value of this distribution at a given point equals the proportion of observations from the sample that are less than or equal to the point.

EDF is a cumulative distribution associated with a sample. It increases by 1/*n* at each of the *n* observations. Its value at any specified value of the measured variable is the fraction of observations of the measured variable that are less than or equal to the specified value.

Suppose a sample of size *n* has the following observations: *S = [x1, x2, …, xn].* The empirical distribution function of the whole sample is given as



The value of the empirical distribution at a specific point *x* can be calculated by counting the number of observations that are less than or equal to x. Finally, divide the counted number by the total number of observations. Thus, we obtain the proportion of observations less than or equal to *x*.

We compute the empirical distribution function for the following sample:

*S = [0.3 0.4 0.3 0.0 0.5 0.6 0.8 -0.5]*

We sort elements of S as follows

*S = [-0.5 0.0 0.3 0.3 0.4 0.5 0.6 0.8]*

The EDF of this sample is given as

*Fn(X) = [1/8 2/8 3/8 4/8 5/8 6/8 7/8 1 ]*

The EDF gives us an estimate of the cumulative distribution function from which the points in the sample are generated.

A Python script to estimate EDF is given below.

|  |
| --- |
| 1. **from** matplotlib **import** pyplot 2. **from** numpy.random **import** normal 3. **from** statsmodels.distributions.empirical\_distribution **import** ECDF 4. **import** numpy as np 6. # generate a sample 7. sample1 = normal(loc=40, scale=5, size=700) 8. sample2 = normal(loc=20, scale=5, size=1400) 9. sample = np.concatenate((sample1, sample2)) 11. # plot the histogram 12. pyplot.hist(sample, bins=50) 13. pyplot.show() 15. # fit a edf 16. ecdf = ECDF(sample) 18. # get cumulative probability for values 19. **print**('P(x<25): %.3f' % ecdf(25)) 20. **print**('P(x<50): %.3f' % ecdf(50)) 21. **print**('P(x<75): %.3f' % ecdf(75)) 23. # plot the edf 24. pyplot.plot(ecdf.x, ecdf.y) 25. pyplot.show()   **Output:**    P(x<25): 0.569  P(x<50): 0.993  P(x<75): 1.000 |

The output of the program first shows the histogram of the generated sample. This sample consist of two Normal distributions. We show the cumulative probability for values of *x* = 25, 50 and 75 in the output. It can be seen that more than 99% of the samples have a value of *x* less than or equal to 50. The final plot shows the estimated empirical distribution function that converges to 1.

|  |
| --- |
| **Hands-on Time – Exercise** |
| **To check your understanding of data plotting and visualization for exploratory analysis, complete the following exercise questions. The answers to the questions are given at the end of the book.** |

# 5.12 Exercise Questions

**Question 1:**

we generate a \_\_\_\_\_\_\_\_ to plot the frequency distribution of a data variable,

A. Bar plot

B. Pie plot

C. Histogram

D. Any of the above

**Question 2:**

When we decrease the number of bins in a histogram, the plot becomes

A. Expanded

B. Contracted

C. Smooth

D. rough

**Question 3:**

Matplotlib’s function plt.plot() is used to creates a

A. Scatter plot

B. Line plot

C. Pie plot

D. Any of the above

**Question 4:**

The range of the values plotted on the y-axis of a cumulative distribution plot is

A. 0 - 1

B. -3 - 3

C. 0 - infinity

D. Depends upon the values of the random variable

**Question 5:**

The range of the values plotted on the y-axis of a quantile plot is

A. 0 - 1

B. -3 - 3

C. 0 - infinity

D. Depends upon the values of the random variable

**Question 6:**

The pie chart is used when we have \_\_\_\_\_\_\_\_\_ data.

A. Continuous

B. Discrete

C. Either continuous or discrete, one type at a time.

D. Both continuous and discrete together

**Question 7:**

Matplotlib’s function plt.plot () can plot \_\_\_\_\_\_\_\_\_\_\_\_

A. time varying data

B. space varying data

C. time and space varying data

D. any two variables together where one depends upon other

**Question 8:**

The \_\_\_\_\_\_\_\_\_\_\_\_ plot with the normalized values on the y-axis gives us the probability density or mass function

A. Line

B. Bar

C. Histogram

D. All of the above

Chapter 6: Statistical Inference

# 6.1 Basics of Statistical Inference and How it Works?

In most real-world situations, we have sample data but we do not have access to the whole population we are interested in. For instance, we want to calculate the average marks of all the students of a city who appeared in a particular exam. Usually, it is not easy to collect the marks of all the students. In this case, we measure / take sample of a small group of students which represent the whole population of the students of the city who appeared in that particular exam.

Descriptive statistics provides us the information about the sample data. For instance, we sample marks of 100 students in a particular exam. We calculate the properties of the sample, such as the mean and the standard deviation to get valuable information about these 100 students. These properties are called the **statistics**. Chapter 4 deals with calculating statistics from sample data.

The properties of a population are called the **parameters** of the population. **Statistical inference** (or the inferential statistics) comprises of the methods and the techniques which permit us to use the information from the samples of a population to make decisions about the populations (generalizations). Thus, it is important to have sample that represent the population with fairly large accuracy.

Techniques of the statistical inference mostly deal with the

1. parameter(s) estimation (learning) and
2. hypothesis testing.

In parameter estimation, we assume that the sample data comes from a statistical model or a particular probability distribution. The sample is analyzed to estimate the parameters of the assumed model or the probability distribution. For example, if we assume a Normal distribution, we have to estimate the mean and the standard deviation of the Normal destitution.

In hypothesis testing, we have to check certain assumptions about the population under consideration.

For instance, in medical research, based upon the experimental data and evidence, the researchers may have to decide whether there is any impact of a particular food item or a drug on the disease. Thus, it is hypothesized that the food or drug has a significant impact on the disease. The hypothesis or the assumption may or may not be true. It has to be tested for truth. Hypothesis testing is used to accept or reject these assumptions.

# 6.2 Statistical Models and Learning

The methods of statistical inference make reasonable assumptions about the available data. Statistical models are set of assumptions concerning the generation of the observed data.

For example, a company spends money on advertising its products to increase sales at different stores. The relationship between dollars spent on advertisement and sales in dollars for this company is given in Figure 6.1. Therefore, a model for the aforementioned problem can be a linear relationship or a line between advertisement and sales. A good model, which makes accurate assumptions about the data, is necessary for statistical inference.

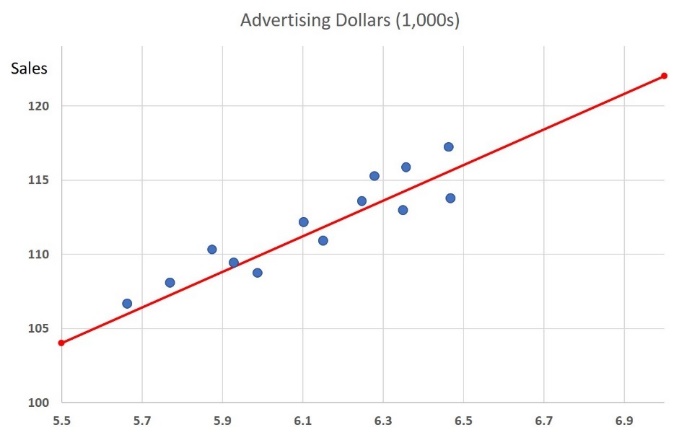


Figure 6.1: Relationship between dollars spent on advertisement and sales in dollars. Every point on the graph shows the data from one store. The line captures the overall trend of the data.

A statistical model is built from the observed data, sometimes referred to as the **training data**. Once a model is created, it is used to make inference or predictions on the future data (or the **test data**). The process of inferring the parameters of the model, for example slope and intercept of a simple linear model, is sometimes referred to as **learning** (or learning the parameters of a model).

The **regression** is a statistical method to find the relationship between input and output variables so that this relation can be used to predict most probable value of the output variable for a given input value. The regression assumes that the output variable is continuous, in contrary to the **classification**, that works with discrete output variables.

The objective of a linear regression model is to find a relationship between one or more independent input features and a continuous target variable that is dependent upon the input features. When there is only one feature it is called **univariate or simple linear regression**.

Ordinary Least Squares (OLS) is one of many mathematical techniques to find the solution of the mathematical equations resulting from the regression model. The result of the solution is the unknown parameters of the regression model.

Suppose we have only one input variable, ***x***, such as the dollar spend on the advertisement as in Figure 6.1. We assume the linear regression model. Then this model can be mathematically described by the equation of a line.

**

The parameter *m* is the slope of the line and the parameter *c* is the intercept on the vertical axis. *f(x)* is the function to be estimated that approximates the output variable such as the sales in dollars. The parameters *m* and *c* of the linear model have to be learnt to find the optimal line that passes through the data points such that the error between the line and the data points is minimum.

Consider the case, when we have multiple input features *x*1, *x*2, *x*3 … These features can be different mediums of the advertisement: TV, news, social media etc. for the example given in Figure 6.1. Suppose all of input features have a linear relationship with the target variable *y*, a linear model can still be assumed as follows:

**

In this case, the parameters to be learnt are *c*, *m*1, *m*2, *m*3 and so on. In this case, there are multiple features; thus, it is a multivariate parameter learning problem. In this case, the regression is known as **multiple linear regression**.

# 6.3 Fundamentals Concepts in Inference

## 6.3.1 Point Estimation

The process of point estimation makes use of the observed data to calculate a point or a single value related to an unknown population. The point is generally a parameter, for example, the mean or the standard deviation of the population.

In the following example, we estimate population mean from the sample mean.

|  |
| --- |
| 1. **import** numpy as np 2. **import** pandas as pd 3. **import** matplotlib.pyplot as plt 4. **import** scipy.stats as stats 6. np.random.seed(12345) 7. population = stats.poisson.rvs(loc=12, mu=24, size=10000) 8. **print**('The population mean is', population.mean()) 9. pd.Series(population).hist(density=True, zorder = 1, alpha=1, label = 'Population Histogram') 11. # We estimate mean by taking a sample out of original population 12. np.random.seed(12345) 13. sample = np.random.choice(a= population, size=500)  # Sample 500 values 14. **print** ('The sample mean is', sample.mean()) 15. pd.Series(sample).hist(density=True, zorder = 2,  alpha=0.5, label = 'Sample Histogram') 16. plt.legend() 18. # We check the difference between two means 19. **print**("Difference of the means is " ,population.mean() - sample.mean() )  # difference between means   **Output:**  The population mean is 35.9784  The sample mean is 35.544  Difference of the means is 0.43440000000000367 |

Lines 6 and 12 of the code use a seed value of 12345 to ensure similar results every time we run the code. We generate a Poisson random variable of 10000 samples having an expected (average) rate of occurrence of 24 and the starting point is 12 as specified in line 7 of the code.

In line 13 of the code, we take 500 samples from the generated Poisson distribution using random.choice () function of NumPy library. It can be observed from the output that sample mean provides a very good approximation of the population mean because the difference between means is very small. If our sample size is reduced, we may not get a good estimate of the population mean.

In a similar fashion, the point estimate for the variance or standard deviation of the population can be calculated from the sample variance or sample standard deviation.

## 6.3.2 Interval Estimation

Interval estimation, in contrast to the point estimation, aims to find a range of values of interest of an unknown population.

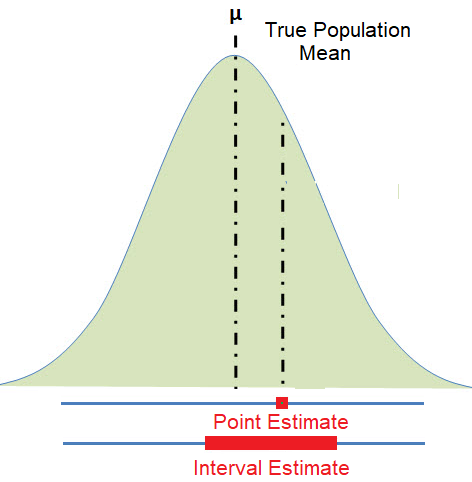


Figure 6.2: The point and interval estimates of a Normally distributed population whose true mean, μ, is given in the center of the distribution.

The accuracy of the estimation generally increases with large samples. However, it is very rare that the point estimate from a given sample exactly corresponds to the true population mean. Thus, in many cases, it is preferred to calculate an interval within which we expect our parameter of interest to fall. The estimation of such an interval is called an interval estimate.

For instance, a random sample of scores for students in an exam may give us an interval from 65 to 75, within which we expect the true average of all scores. The endpoint values 65 and 75 depend on the samples and the computed sample mean. As the sample size increases and we take numerous samples, the variability between computed means for different samples decrease. Thus, the estimated mean, parameter of the population μ, is likely to be closer to the true mean of the population of all students who appeared in that particular exam.

Let θ be the parameter to be estimated. It can be mean, standard deviation or any other point. Let θL and θU be the lower and upper limits of the interval. The difference θU -θL gives us the range within which we expect true parameter of the population with a certain probability. The interval estimation techniques try to find this difference θU -θL. Interval estimates are either

* confidence intervals (frequentist inference) or
* credible intervals (Bayesian inference).

We discuss these in Chapter 7 and 8, respectively.

# 6.4 Hypothesis Testing

Sometimes statisticians have to check certain assumptions, also known as **statistical hypotheses**, about the population under consideration. For instance, while analyzing data sampled from patients, a researcher may have to study the origin of a certain disease.

Based upon the experimental data and evidence, the researcher may have to decide, for example, whether COVID19 jumped to humans via pangolin. In this case, it is hypothesized that COVID19 is spread in humans via pangolin. This hypothesis or the assumption may or may not be true. Thus, it has to be tested for truth. The process of **hypothesis testing,** a method of statistical inference, is used by statisticians to accept or reject statistical hypotheses.

To study the relationship between a certain food and the disease, the data of the patients have to be collected. For instance, a statistical hypothesis can be “*consuming too much caffeine increases the risk of cancer*”. Now this hypothesis may or may not be true. Based on the analysis of data, we have to decide the truth of the said hypothesis.

To check if a hypothesis is true, we have to study the entire population. Since we do not usually have the access to the data of the population, we analyze a random sample from the population. If the observed data is found inconsistent with the hypothesis, the hypothesis is rejected.

## 6.4.1 Null and Alternative Hypotheses

Hypothesis testing requires a statistical model to explain the data. In frequentist inference, the parameter to be estimated is assumed to be Normally distributed. Now the observed data may be consistent or contradictory to the assumed data distribution. Based upon the analysis of the data, we define two different statistical hypotheses:

1. **The null hypothesis** denoted by Ho, implies that the observed data is consistent with the assumed distribution. Null hypothesis usually describes that the chance alone is responsible for the results. It means we have to check for the consistency of the data with our assumption. The null hypothesis is assumed true unless the observed data / evidence shows differently. If the observed data is consistent with the null hypothesis, then it is accepted.
2. **The alternative hypothesis** denoted by H1, suggests that the observed data contradicts our assumptions. In this case, we reject the null hypothesis and accept the alternative hypothesis.

In a coin toss experiment, for example, we want to determine whether a coin is fair. A null hypothesis would be that both Heads and Tails would occur equal number of times when this coin is flipped numerous times. The alternative hypothesis would be that the number of Heads and Tails would be different. We can express these hypotheses mathematically as

Null Hypothesis = Ho: P = 0.5

Alternative Hypothesis = H1: P ≠ 0.5

Now if the coin is flipped 100 times, resulting in 70 Tails and 30 Heads. From this experimental data, we tend to reject the null hypothesis. Thus, based on the evidence from the observed data, we may decide that the coin is not fair.

Moreover, in the legal principle,*presumption of innocence*, a suspect is assumed to be innocent until proven guilty. In this case, the null and the alternative hypotheses would be

Null Hypothesis = Ho: Suspect is innocent,

Alternative Hypothesis = H1: Suspect is guilty.

If the evidence is in the favor of the suspect, he is declared innocent (null hypothesis is not rejected). On the other hand, the suspect is convicted based on evidence against them (null is rejected, alternative hypothesis is selected).

## 6.4.2 Procedure for Hypothesis Testing

In **hypothesis testing,** a procedure is followed either to reject or accept a null hypothesis.

1. Form the null and alternative hypotheses such that if one hypothesis is true, the other must be false.
2. Express the plan to use the observed data for the evaluation of the null hypothesis. This plan usually uses a single test statistic such as the mean of the sample data.
3. Examine the observed data to compute the value of the test statistic such as the mean.
4. Infer from the results whether to accept or reject the null hypothesis by applying the decision rules. An unlikely value of the test statistic from the sample data may result in the rejection of the null hypothesis.

# 6.5 Important Terms used in Hypothesis Testing

## 6.5.1 Sampling Distribution

Let us draw all possible samples of a specific size from a population of interest and compute a statistic such as the sample mean or the standard deviation for each drawn sample. Naturally, the computed statistic will vary from one sample to other. If we plot the probability distribution of this statistic, we get a distribution called a **sampling distribution** of the statistic.

An important theorem in statistics is the **central limit theorem** that is concerned with the sampling distributions. Suppose we take sufficiently large random samples from a population of interest. Every time we have to take a sample; we replace the previous sample in the population. This is called as sampling with replacement. The central limit theorem states that the resulting sampling distribution of the computed means of the individual samples will be approximately Normally distributed even though the original population may or may not be Normally distributed.

## 6.5.2 Errors in Hypothesis Testing

Performing a hypothesis test may result in either of two types of errors.

1. **Type I error** occurs when we reject a null hypothesis despite it being true. The probability of getting this error is known as the **significance level**, denoted by Alpha α. The value of α is set by the statistician according to the problem at hand before even investigating the data. Usually it is set to 0.005, 0.01 or 0.05.
2. **Type II error** arises when we fail to reject a null hypothesis when it is false. The probability of getting a Type II error is denoted by Beta β. The probability of not committing a Type II error or correctly rejecting the null hypothesis, is called the **power of the test.**

Table 6.1: Summary of hypothesis testing.

|  |  |  |
| --- | --- | --- |
| Decision | Null Hypothesis Ho is True | Null Hypothesis Ho is False |
| Accept Ho | (1- α)  Confidence level | β (Type II error) |
| Reject Ho | α (Type I error) | (1- β)  Power of the test |

## 6.5.3 Tests for Statistical Hypotheses

**Two types of tests are common in statistical hypothesis testing. These are given as follows:**

**One-tailed test** has rejection region on only one side of the sampling distribution. For instance, if the null hypothesis is that the mean is greater than or equal to 2, the alternative hypothesis is that the mean is lesser than 2. The rejection region is the range of numbers on the left side of 2, i.e., less than 2, in the sampling distribution.

**Two-tailed test** has rejection region on both sides of the sampling distribution. For instance, the null hypothesis is that the mean equals 2. The alternative hypothesis is that the mean is either less than or greater than 2. The rejection region is range of numbers on both sides of the sampling distribution.

If we have sufficiently large samples available, we assume a Normal sampling distribution. In this case, we perform testing using z-scores. However, when we do not have access to large sample sizes, more than 30 samples, we resort to t-distribution for testing purposes.

The t-distribution, also known as the Student's t-distribution is similar to the Normal distribution but with tails heavier than the Normal distribution. It implies that a t-distribution has a greater chance for observing extreme values than a Normal distribution because it has heavier tails. When our sample size is small and the variance of the population is unknown, we perform t-tests, instead of z-tests for hypothesis testing.

## **6.5.4 z-value** (z-score)

**z-value** also known as z-score is a measure of standard deviations. How many standard deviations the observed value is away from the mean in a Normal distribution. For example, z-value = 2 means that the observed value is 2 standard deviations away from the mean. Below is the formula to calculate z value:



where x, μ and σ are data points on the curve, mean and the standard deviation, respectively. The z-score represents the area under the Normal distribution up-to the value of z. Recall from Section 3.6.3 on the Normal distribution that the area under the curve from – σ to +σ is 68.3% of the overall area. Furthermore, the area under the curve from – 2σ to +2σ is 95.5% of the overall area.

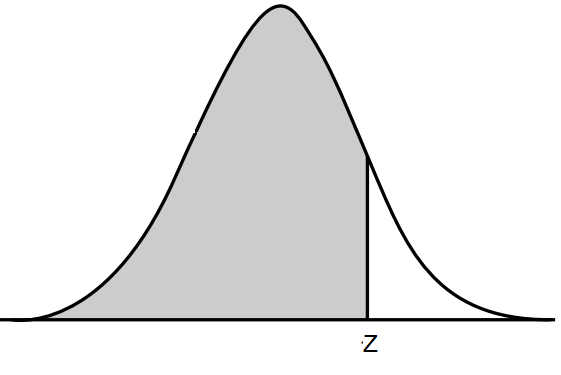


Figure 6.3: z-score from a Normal distribution.

The value of z is first computed by subtracting the mean μ of the distribution from the data point *x*. This operation centers the distribution around 0. Second, we divide the difference between x and μ by the standard deviation σ to make a standard Normal distribution having a unit standard deviation. The z-score is than calculated by computing the area under the Normal curve up-to the value of z.

A z-score equal to, less than and greater than 0 represent an element equal to, less than and greater than the mean, respectively. A z-score equal to -2 / 2 represent a data point that is 2 standard deviations less than / greater than the mean, respectively.

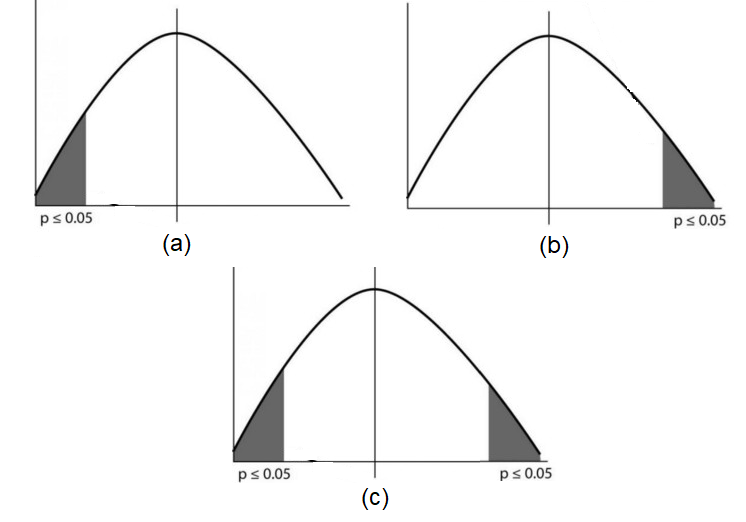
When the number of sample data points is large, about 68% of the elements have a z-score between -1 and 1; about 95% have a z-score between -2 and 2; and about 99% have a z-score between -3 and 3.

## 6.5.5 p-value

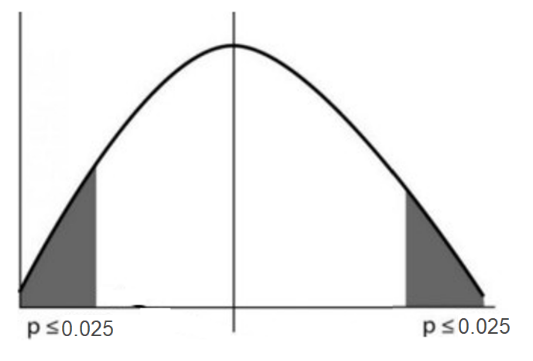
The examination of the observed data makes use of decision rules for rejecting or accepting the null hypothesis. The decision rules are described by using a probability value known as the p-value.

To understand p-value, we first describe some important terminology.

1. **Region of acceptance** describes a range of values. If the test statistic falls within this range, the null hypothesis is not rejected. The region of acceptance is chosen in such a way that the probability of making a Type I error is equal to the significance level.
2. **The critical region** or the **region of rejection** comprises of the set of values outside the region of acceptance. If the test statistic falls within the region of rejection, the null hypothesis is rejected at the α level of significance.
3. **The significance level** is the probability of rejecting the null hypothesis when it is true. The significance level α is used in hypothesis testing to find out the hypothesis that the data support. For example, a significance level of 0.05 indicates a 5% probability that an actual difference between the sample and the population represented by our null hypothesis exists when there is no actual difference. A lower significance level means a stronger evidence will be required to reject the null hypothesis.



(a) (b)



(c)

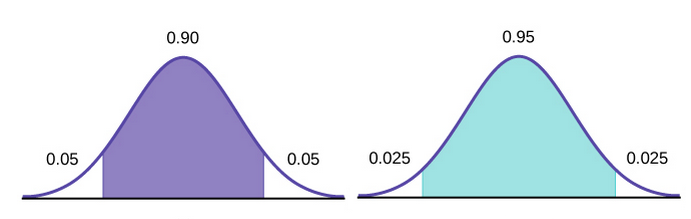
Figure 6.4: For a 95% confidence interval, regions of acceptance (unshaded) and rejection (shaded) for (a) one-tailed (left-tailed), (b) one-tailed (right-tailed) and (c) a two-tailed test. If p-value falls in shaded regions, it is considered significant to reject the null hypothesis.

**p-value** is the probability of obtaining test results at least as extreme as the results actually observed, assuming a correct null hypothesis. It measures the strength of evidence in support of a null hypothesis. If the p-value is less than the significance level, we reject the null hypothesis.

A very small p-value means that such an extreme observed outcome would be very unlikely under the null hypothesis. A p-value is compared against the significance level, α. If the p-value is less than α, we have very unlikely observation. Thus, we say that the results are statistically significant because the sample data is giving us this evidence. In this case, we reject the null hypothesis because there is very less chance of observing the data consistent with the sampling distribution of the test statistic under the null hypothesis.

In the tails of the Normal distribution, we get high magnitude of z-values that correspond to small p-values. Getting these values is an indication that it is very unlikely that the observed sample comes from a pattern represented by our null hypothesis, i.e., we reject the null hypothesis.

As an example, suppose the population mean is 10 and the range of means is from 9.5 to 10.5. If we find the sample average is outside the given range, the null hypothesis is rejected. Else, the difference is supposed to be justifiable by chance alone.

****

(a) (b)

Figure 6.5: (a) A confidence level of 90% corresponding to α =1-0.90 = 0.1, α/2 = 0.1/2 = 0.05 area of rejection is on either side, (b) A confidence level of 95%, corresponding to α =1-0.95 = 0.05, α/2 = 0.05/2 = 0.025 area of rejection is on either side.

Let us use a 95% confidence level, the associated significance level α would be 0.05 (5%). The z-score corresponding to 0.025 (2.5%), 0.05 (5%), 0.95 (95%) and 0.975 (97.5%) would be -1.96, -1.64, 1.64 and +1.96, respectively. ‎

Table 6.1: z-scores for a confidence level of 95% (significance level α of 5%).

|  |  |
| --- | --- |
| Test type | Range of z-scores in the region of acceptance |
| Left-tailed | -∞ (infinity) ‎to +1.64 |
| Right-tailed | -1.64 to ∞ |
| Two-tailed | -1.96 to +1.96 |

For 95% confidence interval in a two-tailed test, if a z-score is between -1.96 and +1.96, the p-value will be larger than 0.025, we do not reject the null hypothesis. When the z-score is outside -1.96 – 1.96 range, e.g., 2.8, the corresponding p-value will be smaller than 0.025. In this case, we can reject the null hypothesis.

Note that both z-value and p-value are associated with the standard Normal distribution. These methods do not work with other distributions. Thus, we assume our sampling distribution to be a Normal distribution due to the central limit theorem.

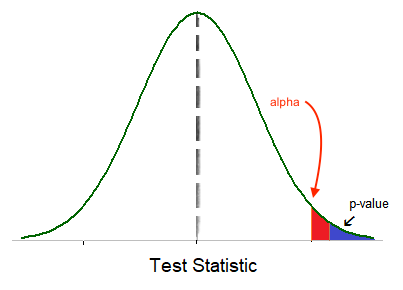


Figure 6.4: Comparison of p-value and α for hypothesis testing in the sampling distribution of the test statistic such as mean. The p-value is the area under the curve past the observed data point.

Suppose we have score of 500 students with an average score of 60. We would like to know what is the probability of getting a score such as 85. Let us plot the student score as a histogram.

|  |
| --- |
| 1. np.random.seed(123) 2. student\_score = np.random.normal(60, 10, 500).round() 3. plt.hist(student\_score, bins = 10, density=True) 4. plt.show() 5. **print**('The mean student score is', student\_score.mean()) 6. **print**('The mean student score is', student\_score.mean())   **Output:**    The mean student score is 59.626 |

Line 1 of the code uses a random seed to reproduce the results. Line 2 generates 500 Normally distributed random numbers rounded to integer by the use of round () function. The mean value of these numbers is set to 60 whereas a standard deviation of 10 is used.

The output shows an average student score of 59.626, and the histogram shows an approximate Normal distribution of the scores. The score of students can be normalized by using scipy.stats function zscore () to get a standard Normal distribution with zero mean and unit standard deviation. Here, we use the formula



to get the z-value corresponding to a particular value. For example, we have been given a class of students whose average marks are 85. We want to find out the probability of getting 85 marks given we have another class of 500 students whose mean marks are found to be 60. First, we compute z-value corresponding to 85 marks.

|  |
| --- |
| 1. zscore = ( 85 - student\_score.mean() ) / student\_score.std() 2. zscore   **Output:**  2.5215872335107994 |

Since area under the probability distribution is 1, a probability of 0.95, let us say, corresponds to 95% of the area under the distribution. Thus, in a quantile function also known as inverse cumulative distribution function or percent point function, we specify the value of the probability to get the percentage of points.

In a standard Normal distribution, 95% of points correspond to a z-value of 1.645 by using the flowing command

The Python code to find this z-value from the probability or percentage of points is given as follows:

|  |
| --- |
| 1. stats.norm.ppf(0.95)   **Output:**  1.6448536269514722 |

If we have to find out, for instance, marks above which top 5% students lie, we type the following code:

|  |
| --- |
| 1. stats.norm.ppf(0.95)\*student\_score.std()+student\_score.mean()   **Output:**  76.17768434215024 |

This code converts a z-value to the corresponding x value in the Normal distribution using the following formula that comes directly from the formula of calculating the z-value.



The output of the code implies that if a student has marks above 76.178, they lie in top 5% marks.

We use the following Python script to find the p-value from z-score corresponding to 85 mean marks of our second class.

|  |
| --- |
| 1. marks\_to\_check = 85 2. zscore = ( marks\_to\_check - student\_score.mean() ) / student\_score.std()   # getting z-score 3. p\_val = 1 - stats.norm.cdf(zscore)        # getting the p-value 4. **print**(f'The z-score = {zscore:0.3f} and the p-value = {p\_val:0.3f}')   **Output:**  The z-score = 2.522 and the p-value = 0.006 |

Line 2 converts the x value to corresponding z-score, whereas line 3 computes the p-value. stats.norm.cdf(zscore) calculates the area under the Normal curve to the left of z-score. We subtract this area from 1 to get the area under the curve to the right of z-score. Line 4 uses f-string format, and 0.3f displays the floating-point numbers to 3 decimal values. A positive z-score of 2.522 means that 85 marks are about 2.5 standard deviations away from the mean. Furthermore, a p-value of 0.006 implies that there is about 0.6% chance of getting these marks from a sample of 500 students having an average of 60 marks and a standard deviation of 10 marks.

Now if we set a significance level of 5%, we can compare it against the computed p-value of 0.6%. If we hypothesize that getting 85 marks are common, we can reject our hypothesis because 0.6% is less than 5% significance level.

We make use of z-values and p-values in Chapter 7 for hypothesis testing.

|  |
| --- |
| **Further Readings** |
| More information on the point and interval estimates can be found at:  <http://www.cqeacademy.com/cqe-body-of-knowledge/quantitative-methods-tools/point-estimates-and-confidence-intervals/>  For more information about hypothesis testing, visit:  <https://www.analyticsvidhya.com/blog/2015/09/hypothesis-testing-explained/> |

# 6.6 Exercise Questions

**Question 1:**

Which of the following testing is used to make decisions from the observed data?

A. Probability

B. Hypothesis

C. Statistics

D. None of the mentioned

**Question 2:**

Which of the values is mostly used to measure statistical significance?

A. p

B. μ

C. σ

D. All of the mentioned

**Question 3:**

Use of samples to estimate population parameters is called

A. Statistical interference

B. Statistical inference

C. Statistical application

D. None of the mentioned

**Question 4:**

A large positive z-score, for example, 3, implies that the value under consideration is \_\_\_\_\_\_\_\_\_\_\_, and the corresponding p-value would be \_\_\_\_\_\_\_\_\_\_\_.

A. Highly likely, small

B. Highly likely, large

C. Less likely, small

D. Less likely, large

**Question 5:**

A small positive z-score, for example, 0. 5, implies that the value under consideration is \_\_\_\_\_\_\_\_\_\_\_, and the corresponding p-value would be \_\_\_\_\_\_\_\_\_\_\_.

A. Highly likely, small

B. Highly likely, large

C. Less likely, small

D. Less likely, large

**Question 6:**

In a one-tailed test, the confidence level is set to 90%. If the p-value is less than \_\_\_\_\_\_\_\_\_\_, we reject the null hypothesis.

A. 0.01

B. 0.5

C. 0.05

D. 0.1

**Question 7:**

In a two-tailed test, the confidence level is set to 90%. If the p-value is less than \_\_\_\_\_\_\_\_\_\_, we reject the null hypothesis.

A. 0.05

B. 0.5

C. 0.025

D. 0.25

Chapter 7: Frequentist Inference

It is pointed out in Chapter 6 that most techniques of the statistical inference are either

1. parameter(s) estimation (learning) or
2. hypothesis testing.

In parameter estimation, we have to estimate the parameters of a statistical model or a distribution. In hypothesis testing, we have to check certain assumptions about the population under consideration.

These assumptions have to be tested for truth. Methods of hypothesis testing are used to accept or reject these assumptions. In the following sections, we present parametric and non-parametric estimation methods as well as methods for hypothesis testing.

# 7.1 Parametric Inference

**Parametric models** belong to a class of statistical models through which we can represent the population using a **finite set** of fixed parameters. A parametric model can also be defined in terms of probability distributions which can be represented by a finite number of parameters.

A linear model can be described by the parameters of the line: slope and intercept. To estimate a target variable corresponding to the unseen future test data, we need just the parameters of the model.

Furthermore, if a population is assumed to be Normally distributed, it can be defined in terms of two parameters of the Normal distribution: mean and standard deviation. Thus, the model that assumes the Normal distribution is said to be a parametric model. The examples of learning algorithms that utilize parametric models include:

* Linear **regression**
* Logistic regression (**classification**) and
* Naïve Bayes classification.

Linear regression uses input variables to estimate output target variable when it is continuous, whereas the logistic regression tries to estimate the discrete output variables. The problems where we estimate discrete output labels or classes is called as classificationproblems.

To implement linear regression, a parametric model, in Python, we use the following program.

|  |
| --- |
| 1. **from** pandas **import** DataFrame 2. **import** statsmodels.api as sm 3. **import** seaborn  as sns 4. **import** matplotlib.pyplot as plt 6. StockMarketData = { 7. 'Year': [2001,2002,2003,2004,2005,2006,2007,2008,2009,2010,2011,2012,2013,2014,2015,2016,2017,2018,2019,2020,2021], 8. 'InterestRate': [2, 2.15, 2.45, 2.75, 2.3, 2.65, 3.5, 3.15,3.25,4.15,4.5,3.45,3.75,5.25,5.75,5.5,3.05,6,6.2,6.05,6.3], 9. 'UnemploymentRate': [5.1,5.1,5.3,5.2, 5.7, 4.9, 6, 4.9, 4.8, 4.1, 3.2 ,3.1, 4.1, 4.1, 3.9, 3.2, 3.2, 4.1,4.2,4.4,4.6], 10. 'StockPrice': [30000,30010,30500,32104,27098,28459,33512,29565,30931,34958,33211,34293,36384,38866,38776,40822,35704,36719,40000,40500,42300] 11. } 13. df = DataFrame(StockMarketData,columns=['Year','InterestRate','UnemploymentRate','StockPrice']) 14. **print**(df) 16. # here we have 2 variables for the multiple linear regression. 17. #If you just want to use one variable for simple linear regression, 18. #then use X = df['Interest\_Rate'] or X = df['UnemploymentRate'] 19. X = df[['InterestRate', 'UnemploymentRate'] ] 20. Y = df['StockPrice'] 22. sns.regplot(x=X['InterestRate'],y=Y) 23. plt.show() 24. sns.regplot(x=X['UnemploymentRate'],y=Y,color='r') 25. plt.show() 27. X = sm.add\_constant(X) # adding a constant for y-intercept 29. model = sm.OLS(Y, X).fit() 31. predictions = model.predict(X) 32. **print**("Predictions:\n",predictions) 33. print\_model = model.summary() 34. **print**(print\_model)   **Output:**  Year InterestRate UnemploymentRate StockPrice  0 2001 2.00 5.1 30000  1 2002 2.15 5.1 30010  2 2003 2.45 5.3 30500  3 2004 2.75 5.2 32104  4 2005 2.30 5.7 27098  5 2006 2.65 4.9 28459  6 2007 3.50 6.0 33512  7 2008 3.15 4.9 29565  8 2009 3.25 4.8 30931  9 2010 4.15 4.1 34958  10 2011 4.50 3.2 33211  11 2012 3.45 3.1 34293  12 2013 3.75 4.1 36384  13 2014 5.25 4.1 38866  14 2015 5.75 3.9 38776  15 2016 5.50 3.2 40822  16 2017 3.05 3.2 35704  17 2018 6.00 4.1 36719  18 2019 6.20 4.2 40000  19 2020 6.05 4.4 40500  20 2021 6.30 4.6 42300      Predictions:  0 28900.344332  1 29278.508818  2 29868.786739  3 30708.141239  4 29158.520145  5 30705.108162  6 31934.759459  7 31965.656451  8 32300.791636  9 35150.957245  10 36780.570789  11 34216.444907  12 34142.518613  13 37924.163482  14 39350.762825  15 39301.667368  16 33124.980749  17 39814.985916  18 40236.179705  19 39691.964165  20 40156.187256  dtype: float64  OLS Regression Results  ==============================================================================  Dep. Variable: StockPrice R-squared: 0.837  Model: OLS Adj. R-squared: 0.819  Method: Least Squares F-statistic: 46.28  Date: Tue, 29 Sep 2020 Prob (F-statistic): 8.04e-08  Time: 12:28:34 Log-Likelihood: -186.95  No. Observations: 21 AIC: 379.9  Df Residuals: 18 BIC: 383.0  Df Model: 2  Covariance Type: nonrobust  ====================================================================================  coef std err t P>|t| [0.025 0.975]  ------------------------------------------------------------------------------------  const 2.809e+04 3439.149 8.168 0.000 2.09e+04 3.53e+04  InterestRate 2521.0966 327.644 7.695 0.000 1832.742 3209.451  UnemploymentRate -830.2553 583.165 -1.424 0.172 -2055.439 394.929  ==============================================================================  Omnibus: 2.076 Durbin-Watson: 1.924  Prob(Omnibus): 0.354 Jarque-Bera (JB): 1.594  Skew: -0.509 Prob(JB): 0.451  Kurtosis: 2.114 Cond. No. 51.0  ==============================================================================  Warnings:  [1] Standard Errors assume that the covariance matrix of the errors is correctly specified. |

In this program, we want to predict the StockPrice based upon two independent variables InterestRate and UnemploymentRate. First, we import Pandas, Statsmodels.api, Seaborn and Matplotlib libraries. We save our data in a dictionary in lines 6 to 11. Next, we construct a Pandas DataFrame from the saved dictionary in line 13.

We display our complete data using line 14 of the code that prints the DataFrame df. There are 4 columns in the output: Year, InterestRate, UnemploymentRate and StockPrice.

The X and the Y variables for the linear regression are constructed in line 19 and 20, respectively. Note that the variable X contains data for both independent variables InterestRate and UnemploymentRate. Since we use multiple (2) input variables to estimate the output variable StockPrice, this becomes a **multiple linear regression** problem.

Lines 22 to 25 plot the data as regression plots of the Seaborn library to find the general trend of the dependent variable against independent variables. The output plots are used to find the general trend of the data visually. For example, the trend of the first plot shows a positive relationship between InterestRate and StockPrince, whereas the second plot shows a negative relationship between UnemploymentRate and StockPrice.

Line 27 is used to add a constant column to the variable X. This constant is required by statsmodel.api module to find the y-intercept term. Finally, line 29 fits the data using Ordinary Least Squares (OLS), a mathematical algorithm, to find the parameters (coefficients) of the multiple linear regression model.

The ordinary least squares (OLS) regression results show a lot of statistics and useful information about the learned model. The parameters of the model are given as the coef:

const = 2.809e+04,

InterestRate = 2521.0966 and

UnemploymentRate = -830.2553.

Note that a positive parameter (slope) for the InterestRate indicate that the dependent / target variable Stockprice has a positive relationship with this independent variable, whereas the negative value -830.2553 indicates that the UnemploymentRate is inversely proportional to the Stockprice. This is also evident from the plots generated by the program.

Parametric models are simpler and easier to interpret. Due to limited number of fixed parameters, they are usually faster than nonparametric models. A less amount of data is required to learn parameters of these models. On the down side, they are generally applicable to the problems in which the structure of the underlying data is not very complex.

# 7.2 Confidence Intervals

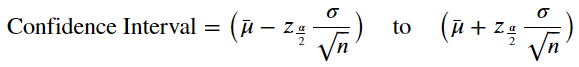
Interval estimates are formed by specifying a value. A value of 0.95 indicates that if the experiment is run, sampling distributions of the sample statistic is drawn, then 95% of the time, these distributions would capture the true parameter within the interval of interest. Since this value gives us a kind of surety about the true parameter, we call this value a **confidence level.** Since we deal with the confidence level, we refer an interval of interest as **confidence interval.** Preferably, we select a short interval with high confidence level or degree of confidence. It is better to be 95% confident that a certain electronic equipment has an average life of 4 to 5 years than to be 99% confident that its average life is 1 to 10 years.

Since we are assuming the repetition of the sampling process and drawing the sampling distributions accordingly, we are interpreting the probability as done in the **frequentist statistics**.

The Python implementation for confidence interval is given below.

|  |
| --- |
| 1. **import** numpy as np 2. **import** scipy.stats as stats 4. N=1000      # sample size 5. gamma=0.95  # gamma = 1-alpha (also known as confidence level) 6. alpha = 1 - gamma 8. # mean and standard diviation of the population 9. mu=5 10. sigma=3 12. # Normally distributed sample data of size N 13. x=np.random.randn(N)\*sigma+mu 15. # Calculation of mean and standard deviation of the sample data 16. mu\_sample=np.mean(x) 17. sigma\_sample=np.std(x, ddof=1)   # delta degree of freedom ddof=1 means divide by N-1 instead of N for the sample STD. 19. **print**('sample mean: mu\_sample                                     : %f' % mu\_sample) 20. **print**('sample standard deviation: sigma\_sample                    : %f' % sigma\_sample)  23. # calculations using nornmal distribuiton for 95% confidence level 24. l1=stats.norm.ppf(0.025)    # lower percentile 25. u1=stats.norm.ppf(0.975)  # upper percentile 26. **print**('confidence interval of mu\_sample using normal distribution : (%f, %f)' % 27. (mu\_sample+l1\*sigma\_sample/np.sqrt(N), mu\_sample+u1\*sigma\_sample/np.sqrt(N)))   **Output:**  sample mean: mu\_sample : 3.940637  sample standard deviation: sigma\_sample : 2.758312  confidence interval of mu\_sample using normal distribution : (2.859398, 5.021875) |

We specify 1000 sample points and a confidence level of 0.95. The data is sampled in line 13 of the code. This data comes from a normal distribution having mean 5 and standard deviation 3 as specified in lines 9 and 10. The sample means and standard deviations are printed using lines 19 and 20 of the code. Since the percent point function or the quantile function is used to get the values of the random variables when the probability is given as the input to the function. Thus, we use stats.norm.ppf and specify lower point α/2 = (1-.95)/2 = 0.05/2 = 0.025 or 2.5% and upper point 1-α/2 = 1- (1-.95)/2 = 1- 0.05/2 = 1-0.025 =0.975 or 97.5% on the normal curve to this function. In return, we get -1.96 and 1.96 as z-scores corresponding to 2.5% and 97.5%, respectively. This is done in lines 24 and 25 of the code. Finally, we use the formula in line 27 of the code to print the confidence interval.

where represents the point estimate of the mean, zα/2 is the z-score at the junction between region of acceptance and rejection, and σ/√n is the standard deviation of the sampling distribution of the mean which is also referred to as standard error (SE).

# 7.3 Nonparametric Inference

In **nonparametric models,** the structure of the model is not defined in advance, rather it depends upon the data. As more and more data are gathered, the number of parameters of the model vary to fit the data accordingly. It is not the case that the nonparametric models do not have any parameters. The number the parameters is not fixed instead.

The examples of learning algorithm that utilize nonparametric models include:

* Histogram
* Kernel density estimation (KDE)
* Nonparametric regression and
* K-nearest neighbors (KNN).

Both histograms and the kernel density estimation (KDE) methods provide us the estimates of the probability density function (PDF) of a random variable. In nonparametric regression, the parameter size varies depending upon the available data. A KNN looks *K* points in the available data that are nearest to the test data point for the estimation purposes. It can be used for both regression and classification problems.

Nonparametric methods such as KDE make inferences about the population from a finite data sample. These methods make use of one of many kernels that are non-negative symmetric mathematical functions. Examples of kernel functions include uniform, triangle, Gaussian and cosine functions.

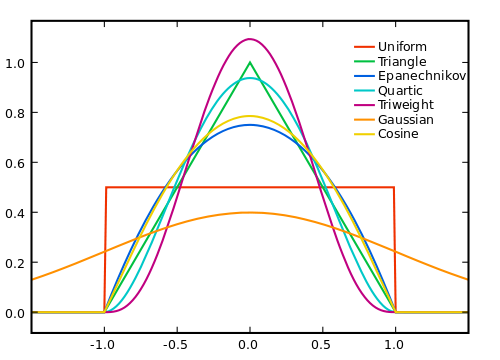
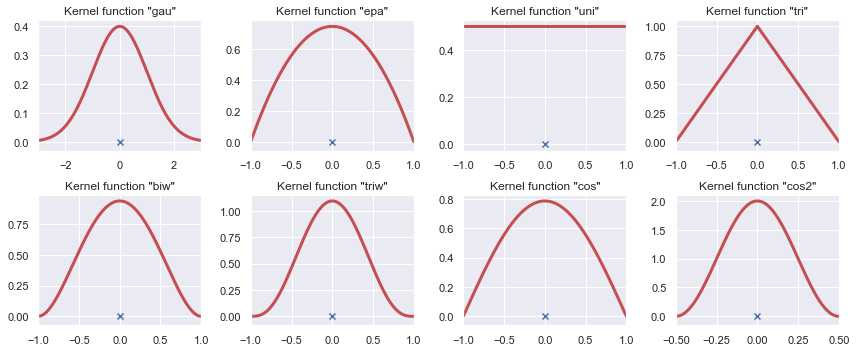


Figure 7.1: Examples of kernel functions.

A histogram counts the number of data points in different regions to estimate PDF, whereas KDE is a function defined as the sum of a kernel function on every data point. KDE gives a better estimate of the PDF as compared to a histogram.

Figure 7.2: Kernel functions available in Statsmodels library.

To estimate the PDF using KDE for univariate case, we use **sm.nonparametric.KDEUnivariate**.

To implement nonparametric kernel density estimation in Python, we first import necessary packages.

|  |
| --- |
| 1. %matplotlib inline 2. **import** numpy as np 3. **from** scipy **import** stats 4. **import** statsmodels.api as sm 5. **import** matplotlib.pyplot as plt 6. **from** statsmodels.distributions.mixture\_rvs **import** mixture\_rvs 8. # Seed the random number generator for reproducible results 9. np.random.seed(12345) |

We use the function **%matplotlib inline** that renders the figures such that they become part of the notebook.

When we mention seed() with a particular number as input say 0 or 12345, we make sure to generate same set of random numbers always. Thus, it is used to reproduce results.

We sample from known distributions as follows.

|  |
| --- |
| 1. # Location (center), scale (spread) and weight for the two distributions 2. pdf1\_loc, pdf1\_scale, pdf1\_weight = -1 , .5, .25 3. pdf2\_loc, pdf2\_scale, pdf2\_weight = 1 , .5, .75 5. # Sample from a mixture of distributions 6. sample\_dist = mixture\_rvs(prob=[pdf1\_weight, pdf2\_weight], size=250, 7. dist=[stats.norm, stats.norm], 8. kwargs = (dict(loc=pdf1\_loc, scale=pdf1\_scale), dict(loc=pdf2\_loc, scale=pdf2\_scale))) |

First, we specify the centers, spread and probability weight for the two distributions in lines 2 and 3. A weight of .25 indicates that we take 25% of the samples from first PDF. To get samples from a mixture of distributions, we use the function **mixture\_rvs** that take probability weights, size and types of distributions as the input in lines 6 to 8 of the code. We specify Normal distributions for both cases and take 250 samples as specified in line 6. The option kwargs (keyworded arguments), like the option args, allows us to pass variable number of arguments to a function as input. Usually, we use a dictionary object with kwargs.

Next, we plot the samples and their histograms by the following piece of code.

|  |
| --- |
| 1. fig = plt.figure(figsize=(12, 5)) 2. ax = fig.add\_subplot(111) 4. # Scatter plot of data samples and histogram 5. ax.scatter(sample\_dist, np.abs(np.random.randn(sample\_dist.size)), 6. zorder=2, color='g', marker='+', alpha=0.5, label='Samples') 8. lines = ax.hist(sample\_dist, bins=20, color = 'r', edgecolor='k', label='Histogram', zorder=1) 10. ax.legend(loc='best') 11. plt.show()   **Output:** |

The first line of the program adjusts the size of the figures, whereas the second line specifies how many subplots do we need. We have specified 111 in line 2, the first two digits 11 indicate a matrix of subplots having 1 row and 1 column, whereas the last digit 1 means the subplot number 1. Lines 5 and 6 are used to plot the samples of distributions as green markers +, while the histogram is drawn by counting the number of samples corresponding to each bin in line 8. It can be seen that approximately 25% and 75% of the samples belong to the first and the second distribution, respectively.

|  |
| --- |
| 1. kde = sm.nonparametric.KDEUnivariate(sample\_dist) 2. kde.fit() # Estimate the densities |

The above-mentioned two lines of code are used to estimate the PDFs of a mixture of two distributions. Finally, we plot the results as follows:

|  |
| --- |
| 1. fig = plt.figure(figsize=(12, 5)) 2. ax = fig.add\_subplot(111) 4. # Plot the histogram of samples 5. ax.hist(sample\_dist, bins=20, density=True, label='Histogram from samples', 6. zorder=1, color = 'r', edgecolor='k', alpha=0.8) 8. # Plot the KDE as fitted using the default arguments 9. ax.plot(kde.support, kde.density, lw=3, label='KDE from samples', zorder=2)  12. # Plot the true distribution 13. true\_values = (stats.norm.pdf(loc=pdf1\_loc, scale=pdf1\_scale, x=kde.support)\*pdf1\_weight 14. + stats.norm.pdf(loc=pdf2\_loc, scale=pdf2\_scale, x=kde.support)\*pdf2\_weight) 15. ax.plot(kde.support, true\_values, lw=3, label='True distribution', zorder=3) 17. # Plot the samples 18. ax.scatter(sample\_dist, np.abs(np.random.randn(sample\_dist.size))/40, 19. marker='+', color='g', zorder=4, label='Samples', alpha=0.9) 21. ax.legend(loc='best') 22. ax.grid(True)   **Output:** |

The output of this program shows the actual samples (green ‘+’ markers), the histogram (red bars), estimated KDE from the samples (blue) and the true distribution (orange).

The option density = True normalizes the histogram in line 5 of the code.

The option zorder in all four plots defines the order of appearance of the plots. For example, a plot having a greater number of zorder appears in front of the plot that have a smaller number of zorder.

The option kde.support provides the values of x-axis against which the estimated density kde.density is plotted in line 9 of the code.

To plot the true distribution that is a mixture of two normal distributions of weights 25% and 75%, we mix both true distributions together in line 13 and 14 of the code. Note there is a slight difference between the true distributions and the estimated densities from KDE. This is partly because we use a limited number of observations for kernel density estimation.

Benefits of nonparametric models include their flexibility to learn very complex forms of relationships between the input and the output data because they do not assume the form of function that maps input to the output. The negative aspects of these models include the requirement of a lot of training data to estimate the mapping function. Furthermore, these models are slower to learn because of the presence of a lot of parameters.

|  |
| --- |
| **Further Readings** |
| For the official documentation of the stable release of the Statsmodel package and the kernel density estimation, visit the following webpage.  <https://www.statsmodels.org/stable/index.html>  <https://www.statsmodels.org/stable/examples/notebooks/generated/kernel_density.html#The-available-kernel-functions> |

# 7.4 Hypothesis Testing using z Tests

As mentioned in Chapter 6, when we have a sample size greater than 30 observations, and the standard deviation of the population is known, we perform z tests for hypothesis testing. Otherwise, we perform t tests. In this section, we present one-tailed and two-tailed z tests.

## 7.4.1 One-tailed z Test

Suppose the hypotheses to be tested are as follows:

Null Hypothesis : H0: sample\_mean < 19

Alternate Hypothesis : H1:sample\_mean > 19

In this case, the alternative hypothesis is on only one side of the null hypothesis, i.e., the mean of the sample is greater than 19. The test that can be performed to test these hypotheses is called as one-tailed z test.

We assume a confidence interval of 95%. The corresponding z-value is computed. The p-value is compared against the significance level α, 0.05 (5%). If the z-value is found greater than the critical z-value that corresponds to the z-value at the boundary of the region of acceptance and the region of rejection, we accept the null hypothesis, otherwise we accept the alternative hypothesis.

To implement one-tailed z test, type the following Python script.

|  |
| --- |
| 1. **import** numpy as np 2. **from** numpy **import** random 3. **import** math 4. **import** scipy.stats as st  7. population = np.array([20,12,22,32,52,1,22,30,40,50,6,12,32,52,1,22,3,7,12,32,52,62,12,32,52,11,22,3]) 8. sample\_size = 12 9. sample = random.choice(population, sample\_size) 11. population\_mean = population.mean() 12. **print**("Population Mean: ", population\_mean) 14. sample\_mean = sample.mean() 15. **print**("Sample Mean: ", sample\_mean) 17. # Null Hypothesis 18. # sample\_mean < 19 19. # Alternate Hypothesis 20. # sample\_mean > 19 22. pop\_stdev = population.std() 23. **print**("Population Standard Deviation: ", pop\_stdev) 24. z\_test = (sample\_mean - population\_mean)/ (pop\_stdev/math.sqrt(sample\_size)) 25. **print**("Z test value: ",z\_test) 27. confidence\_level = 0.95 28. z\_critical\_val = st.norm.ppf(confidence\_level) 29. **print**("Z critical value: ", z\_critical\_val) 31. **if**(z\_test > z\_critical\_val): 32. **print**("Null Hypothesis is rejected.") 33. **else**: 34. **print**("Null Hypothesis is accepted.")   **Output:**  Population Mean: 25.214285714285715  Sample Mean: 24.083333333333332  Population Standard Deviation: 18.020538169498916  Z test value: -0.21740382738025502  Z critical value: 1.6448536269514722  Null Hypothesis is accepted. |

In line 9, a sample of size 12 is taken from the population defined on line 7 of the code. The sample mean is compared against the population (true) mean to get the z-value in line 24 of the code. The critical value of z, that corresponds to a particular p-value is computed using SciPy.stats function norm.ppf ().

We reject the null hypothesis if the z critical value is less than the z test value. Since z test value, -0.217 is less than z critical value, 1.645, we accept the null hypothesis.

## 7.4.2 Two-tailed z Test

Suppose the hypotheses to be tested are as follows:

Null Hypothesis : H0: sample\_mean = 23

Alternate Hypothesis : H1:sample\_mean !=23

In this case, the alternative hypothesis is on both sides of the null hypothesis, i.e., the mean of the sample is not equal to 23. The test that can be performed to test these hypotheses is called as two-tailed z test.

To implement two-tailed z test, type the following Python script.

|  |
| --- |
| 1. **import** numpy as np 2. **from** numpy **import** random 3. **import** math 4. **import** scipy.stats as st 6. population = np.array([20,12,22,32,52,1,22,30,40,50,6,12,32,52,1,22,3,7,12,32,52,62,12,32,52,11,22,3]) 7. sample\_size = 12 8. sample = random.choice(population,12) 10. population\_mean = population.mean() 11. **print**("Population Mean: ", population\_mean) 13. sample\_mean = sample.mean() 14. **print**('Sample Mean:' , sample\_mean) 16. # Null Hypothesis 17. # sample\_mean = 23.5 18. # Alternate Hypothesis 19. # sample\_mean != 23.5 21. pop\_stdev = population.std() 22. **print**("Population Standard Deviation: ", pop\_stdev) 23. z\_test = (sample\_mean - population\_mean)/ (pop\_stdev/math.sqrt(sample\_size)) 24. **print**('Z test value:', z\_test) 26. # calculation of p-value 27. **if** (z\_test>0): 28. p\_val = 1 - st.norm.cdf(z\_test) 29. **else**: 30. p\_val = st.norm.cdf(z\_test) 31. **print**('p-value:' ,p\_val) 33. # Right Tail 34. confidence\_level = 0.95 35. alpha = 1-confidence\_level 36. z\_critical\_val1 = st.norm.ppf(confidence\_level+alpha/2) 38. # Left Tail 39. z\_critical\_val2 = st.norm.ppf(alpha/2) 41. **print**("Z critical value 1: ", z\_critical\_val1) 42. **print**("Z critical value 2: ", z\_critical\_val2) 44. #if(z\_test > z\_critical\_val1 or z\_test < z\_critical\_val2):     either use this line or the line following it 45. **if**(p\_val < alpha/2): 46. **print**("Null Hypothesis is rejected.") 47. **else**: 48. **print**("Null Hypothesis is accepted.")   **Output:**  Population Mean: 25.214285714285715  Sample Mean: 29.75  Population Standard Deviation: 18.020538169498916  Z test value: 0.871903770861863  p-value: 0.19163043818841108  Z critical value 1: 1.959963984540054  Z critical value 2: -1.959963984540054  Null Hypothesis is accepted. |

In line 8, a sample of size 12 is taken from the population defined on line 6 of the code. The sample mean is compared against the population (true) mean to get the z-value in line 23 of the code. A p-value is computed in lines 27 to 30 by using if-else conditions. This is because if z-value is positive, it has to be compared to the p-value on the right side of the sampling distribution. However, a negative z-value should be compared to the p-value on the left side of the distribution. Since it is a two-tailed test, two critical values of z are computed using SciPy.stats function norm.ppf () in lines 36 and 39 of the code. Finally, we can either test our hypothesis using z\_test or p\_val. Here, in line 45, we test if the p-value is less than half of the significance level, we reject the null hypothesis.

Since p-value, 0.1916 is greater than α/2, we accept the null hypothesis.

# 7.5 Exercise Questions

**Question 1:**

The probability of rejecting the null hypothesis when it is false corresponds to

A. α

B. β

C. Type I error

D. Type II error

**Question 2:**

Since α corresponds to the probability of Type I error, then 1−α corresponds to

A. Probability of rejecting H0 when H0 is true

B. Probability of accepting H0 when H0 is true

C. Probability of accepting H0 when H1 is true

D. Probability of rejecting H0 when H1 is true

**Question 3:**

In a hypothesis testing, if β is type II error, and 1−β is the power of the test, then which statement corresponds to 1- β

A. probability of rejecting H0 when H1 is true

B. probability of failing to reject H0 when H1 is true

C. probability of failing to reject H0 when H0 is true

D. probability of rejecting H0 when H0 is true.

**Question 4:**

In a hypothesis, what is the effect on the region of rejection when the level of significance α is reduced?

A. The rejection region is reduced in size

B. The rejection region is increased in size

C. The rejection region is unaltered

D. The answer depends on the alternative hypothesis

**Question 5:**

Which statement (s) is true?

A. A very small p-value indicates that the actual data differs from the expected under the null hypothesis

B. p-value measures probability that hypothesis is true

C. p-value measures probability of Type II error

D. A large p-value indicates that the data is consistent with the alternative hypothesis

**Question 6:**

The average growth of a specific type of trees is 5.3 inches in a year. A researcher hypothesizes that a new variety of that tree should have a greater yearly growth. A random sample of 100 new trees results in an average yearly growth of 5.9 inches and a standard deviation of 1.5 inches. The appropriate null and alternative hypotheses to test the hypothesis are:

A. H0: μ=5.9 against H1: μ>5.9

B. H0: μ=5.9 against H1: μ≠5.9

C. H0: μ=5.3 against H1: μ>5.3

D. H0: μ=5.3 against H1: μ≠5.3

Chapter 8: Bayesian Inference

The Bayesian statistics, in contrast to the frequentist statistics, interprets the probability as a degree of belief as the prior knowledge. The use of priors about happening of events makes this a subjectiveview of the probability because the prior knowledge may vary from one expert to another.

The prior knowledge is also used to associate probability with the parameters to be estimated or the hypotheses to be tested. Our degree of belief changes as new evidence / data appears. The belief can be defined as a probability distribution. For instance, the belief about average heights of European males can be expressed as, "there is 80% probability that the average height is between 175 to 185 cm". Bayes' theorem is employed by Bayesian inference to update the probability of a hypothesis based on the evidence or the availability of data.

Bayesian statistics mainly finds its application when we have to update some parameters based on dynamic data or a sequence of data. In the subsequent sections, we revise the Bayes’ rule and present methods based upon Bayesian inference.

# 8.1 Conditional Probability

The events occurring around us can be independent such as tossing of a single coin. However, many events are dependent upon other events in such a way that they are affected by previous events. Conditional probability is a way to describe the dependency of the events. The probability of an event that is based upon / conditional to another event is called a conditional probability.

For instance, suppose we have 5 balls in a bag, out of which 2 are blue and 3 are red. We define the following events:

1. Event A: Getting a blue ball,

Chances of getting a blue ball are 2 in 5:

P(A) = 2/5

1. Event B: Getting a red ball

Chances of getting a red ball are 3 in 5:

P(B) = 3/5.

What happens when we draw a ball from the bag, and then draw another ball. The second draw is now depending upon (conditional to) the previous draw; thus, it is a dependent event. Suppose we get a blue ball in the first draw, i.e., P(A) = 2/5, and a red ball in the second draw. The probability of getting the second red ball is not 3/5 anymore. It will be 3/4 because we do not replace the first ball. The total number of balls present in the bag are 4 for the second draw.

If we have to compute the probability of getting the first blue ball and the second red ball, we have to combine the probabilities of both events happening together. It is known as the **joint probability** of A and B, and denoted as P(A∩B):

P(A∩B) = 2/5x3/4 =6/20 = 3/10.

The symbol ⋂ is for the intersection of the events. The expression for P(A∩B) combines the probability of event A, P(A), and the probability of event B given A has occurred before, P(B|A).

P(A∩B) = P(A). P(B|A)

P(B|A)= P(A∩B) / P(A).

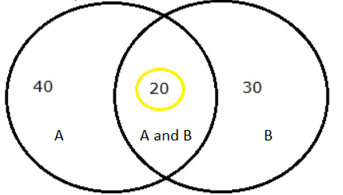


Figure 8.1 Explanation of the joint probability P(A∩B).

Thus, the conditional probability can be defined as the likelihood of occurrence of an event based on the occurrence of a previous event. Conditional probability is calculated by multiplying the probability of the preceding event by the updated probability of the conditional event. As another example:

* Event A is that it is raining outside, and it has a 40% chance of raining today. The probability of event A is P(A) = 0.4.
* Event B is that a person needs to go outside, and it has a chance of 30%, i.e., P(B) = 0.3.

Let the probability that both events happen together is P(A⋂B) = 0.2 or 20%.

Now we are interested to know the probability or chances of occurrence of rain given the person has come out. The probability of rain given the person went out is the conditional probability P(A|B) that can be given as,

*P(A|B) = P(A⋂B)/P(B) = 0.2/0.3 = 0.66= 66.6%.*

# 8.2 Bayes’ Theorem and the Bayesian Philosophy

In many situations, the events or experiments are not repeatable. For example, find the probability of winning of candidates in elections to be held next month? Obviously, the event of election will happen only once next month, it is not repeatable. The frequentist approach fails in such scenarios. The Bayesian approach will make use of prior knowledge about the candidates such as popularity of the candidates, the result of previous elections etc. to make inferences from the available data.

In many cases of scientific experiments, typically some prior knowledge of the experiment is available. Discarding this prior information may affect the results of the inference. The Bayesian statistics makes use of this already available information about the process to make decisions. This prior information is combined with the present information using Bayes’ theorem.

Frequentist inference works with the probability of the data given the hypothesis *P(D|H)* is true. Bayesian inference, contrary to the frequentist approach, concentrates on *P(H|D)*, i.e., the probability of the hypothesis given the data. This implies that the data is treated as fixed, not a random variable. However, hypotheses are considered as random variables; thus, probabilities are associated with hypotheses to be tested.

The Bayesian probability is interpreted as a **degree of belief**. Suppose, in a rainy season, it rains most of the days of the month in some geographical area. The natives of that area believe that the chances of having a rainy-day is 80% or 0.8. This becomes the prior probability that is based on the degree of belief of the natives. We write

*P*(rainy-day = true) = 0.8,

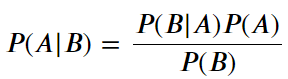
where a degree of belief of 80% that a randomly chosen day receives rain is the prior probability of having a rainy-day in the absence of any other evidence. It is important to point out that the degree of belief denotes the probability of happening of a particular event before we make actual observation of the event.

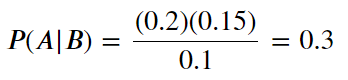
Obviously, the priors of the events can change when we observe the actual outcomes or events. In other words, the presence of an evidence may cause our degree of belief of the event to change.

As a practical example, we might want to calculate the probability that a patient has a heart disease given they are obese. We define event *A* as “patient has a heart disease”. From previous experience and the data collected from different hospitals, it is known as a **prior** belief that 15% of patients have a heart disease, i.e., *P*(*A*) = 0.15. Furthermore, we define event *B* as “patient is obese”. From the past collected data, 10% of the patients are obese, i.e., *P*(*B*) = 0.1.

Now suppose, we know from the hospital tests data that 20% of the patients diagnosed with a heart disease are obese, i.e., *P*(*B|A*) = 0.2. The probability that a patient is obese given that they have a heart disease is 20%. *P*(*B|A*) is referred to as a **likelihood** function. Now we are interested to find out the probability that a patient has a heart disease if they are obese, i.e., *P*(*A|B*). This new conditional probability in the presence of **evidence**, event B: obesity, is called as **posterior** probability.

Bayes’ theorem computes posterior from the likelihood, evidence and prior as follows:





This implies that if a patient is obese, their chances of having a heart disease is 0.3 or 30% in contrast to 15% chances in the absence of the evidence as suggested by the past data. Thus, the presence of evidence of one event alters the posterior probability of the other event.

In terms of hypothesis testing, some terminology related to Bayes’ theorem is given as follows.

* **P(A):** the probability of hypothesis A being true, regardless of the data. This is known as the **prior** probability of A or the unconditional probability.
* **P(B):** the probability of the data, regardless of the hypothesis. This is known as the **evidence**.
* **P(B|A):** the probability of data B given that the hypothesis A is true. This is known as the **likelihood** of data B conditional on the hypothesis A.
* **P(A|B):** the probability of hypothesis A given the data B. This is known as **posterior** probability.

# 8.3 Computations in Bayesian Inference

Suppose we want to estimate the average height of adults. We assume that height has a Normal distribution. The frequentist approach to estimate adult height could be as follows.

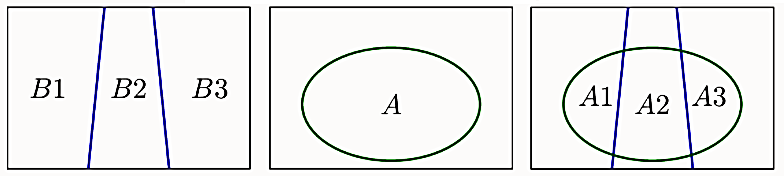
The height is assumed to be a fixed, not a random, number. Thus, we cannot assign probabilities to the average height being equal to a specific value. Next, we shall collect sample of the population consisting of adults. The population mean is then estimated as the sample mean that is consistent with the data. The most likely / consistent value of the average height is obtained by a method called as **maximum likelihood estimate**. The maximum likelihood estimate of the population mean is usually equal to the sample mean in frequentist statistics.

The Bayesian approach to estimate adult height could be as follows. The average or the mean, a fixed value, is described as having a probability distribution over the possible values of the average heights. The sample data is obtained from the population. This data is used to update this distribution. The updated distribution of the parameter becomes narrower as new sample data is used by Bayes rule to update the estimate of the average height of adults.

## 8.3.1 Computing Evidence: Total Probability

The computation of the posterior probability in the Bayes theorem involves the computation of the prior, likelihood and the evidence. The evidence is usually calculated by the law of total probability.

Suppose, we have a sample space represented as a rectangle in Figure 8.2 (a). Since three mutually exclusive events *B*1, *B*2 and *B*3 cover the whole sample space, these are exhaustive. Now any event *A* can be considered as the intersection of the event with all 3 mutually exclusive exhaustive events.



(a) (b) (c)

Figure 8.2: The law of total probability. To compute the probability of an event A (given as an oval) in the sample space (rectangular), we have to compute the probability of event A with respect to mutually exclusive and exhaustive events *B*1, *B*2 and *B*3.

To find the probability of *A,* we can compute and add the probabilities of mutually exclusive parts of event *A*: *A*1, *A*2 and *A*3 as follows:



where



Thus,



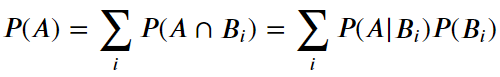
Now from the definition of conditional probability,



The probability of event *A* in terms of probabilities conditional to the mutually exclusive events is now given as:



This can be compactly written as



The last equation is known as “**the law of total probability**” in the sense that the total probability of any event *A* can be computed by its parts *A*1, *A*2 and *A*3, that in turn can be computed from the conditional probabilities. This equation demonstrations that the computation of the evidence requires computations comparable to the number of partitions of the sample space. This amounts to a lot of computations when the partitions become large.

In case of a continuous random variable *B,* the summation is replaced by its continuous counterpart, the integral. Most Bayesian calculations of the posterior become intractable due to the large computational overhead due to the calculation of the evidence in the denominator. Therefore, instead of computing the exact sum (discrete case) or integral (continuous case), we take samples from the posterior in such a way that its good approximation is obtained. Monte Carlo methods, discussed in Section 8.4, are used to sample posterior.

## 8.3.2 Steps to Follow for Bayesian Inference

We have to compute the posterior from the prior, evidence and the likelihood functions. We follow these steps to estimate posterior in the Bayesian inference:

* Establish a belief about the prior before observing the data. Furthermore, assume a likelihood function as well. This is equivalent to assuming some probability distributions for the prior and the likelihood.
* Use the data to update our belief about the model. This corresponds to computing the posterior from the available data.
* If data is available sequentially, we keep on updating our belief based upon new evidence.

# 8.4 Monte Carlo Methods

Monte Carlo methods are algorithms which depend on repeated random sampling to obtain approximate results. The basic concept behind Monte Carlo sampling is to employ randomness to approximate solution to the problems for which an exact solution is difficult to compute. These methods are widely used to find the approximate (numerical) integration and to generate random draws from a probability distribution.

Monte Carlo sampling is particularly useful to compute approximate solution to the posterior in a reasonable time that is hard to compute otherwise. Monte Carlo methods can be used to predict the expected outcome of an experiment by calculating the outcome multiple times with different random inputs.

Monte Carlo methods rely on randomness and the *law of large numbers* that can be explained as follows. *T*he sample statistic such as mean for a sample size *n* converges to the population mean as *n* approaches to infinity. In other words, there would be very high probability that sample mean is very close to population mean when *n* is very large.

Suppose we want to find the probability of tails in a coin flip experiment. We call this probability *p.* Initially, we do not have any idea or any prior information about this number *p*. We start to flip a coin, and record the outcomes in each flip. This becomes our observed data. Our inference of the probability *p* might change when we repeat the coin flip experiment again and again. To implement this in Python, type the following script.

|  |
| --- |
| 1. #Import required libraries 2. **import** random 3. **import** matplotlib.pyplot as plt 5. #Let Heads = 0 and Tails = 1 6. #Definition of function that randomly gives us either 0 or 1 as the output. 7. **def** coin\_flip(): 8. **return** random.randint(0,1) 10. #Check the return value of coin\_flip() 11. coin\_flip() 13. #Monte Carlo Simulation 14. #Empty list to store the probability values. 15. list1 = []  18. **def** monte\_carlo(n): 19. results = 0 20. **for** i **in** range(n): 21. flip\_result = coin\_flip() 22. results = results + flip\_result 24. #Calculating probability value: 25. prob\_value = results/(i+1) 27. #Append the probability values to the list: 28. list1.append(prob\_value) 30. #Plot the results: 31. plt.axhline(y=0.5, color='r', linestyle='-') 32. plt.xlabel("Iterations") 33. plt.ylabel("Probability") 34. plt.plot(list1) 36. **return** results/n 38. #Calling the function: 40. answer = monte\_carlo(100) 41. **print**("Final value :",answer)   **Output:**  The flipped coin value is 1  Final value : 0.49 |

This code imports libraries random and Matplotlib for generating random numbers and for plotting the results, respectively. We define a function coin\_flip () at line 7 of the code. This function uses another function random.randint () to generate a random integer either 0 or 1.

Next, to save the outcomes of each coin flip, we create an empty list in line 15 of the code. This list is updated in another function monte\_carlo (*n*) that takes the number of repetitions *n* of the experiment as its input. We use a for loop that iterates *n* number of times, each time the function coin\_flip () is called, and its random outcome, either 0 or 1, is appended to the list. Thus, the size of the list grows until it reaches equal to the number of repetitions of the experiment.

The value of the probability of getting the Tails is calculated in line 25 of the code. Note that we divide results, that holds the sum of 1’s (Tails) by (*i*+1) instead of *i.* This is because the for loop start from 0 and goes to *n*-1 (a total of *n* times).

Next, we plot the results using lines 31 to 34 of the code. Finally, the function returns the final value of the probability after *n* trials of the experiment in line 36 of the code.

The designed function monte\_carlo (*n*) is called in line 40 of the code for an input of 100. The output shows that the initial outcome of the coin\_flip was 1. This is depicted in the output plot. As more and more flips ae made, the computed probability approaches to 0.5 as per our expectation.

# 8.5 Maximum a Posteriori (MAP) Estimation

The maximum a posteriori (MAP) estimation of a model is the mode of the posterior distribution, where the mode is the value of the random variable at which the probability mass (or density) function takes its maximum value.

The mode of a distribution is found by numerical optimization methods. PyMC3 allows us to compute the MAP of a distribution with the find\_MAP () function. The MAP is returned as a parameter point, which is always represented by a Python dictionary of variable names: NumPy arrays of parameter values as key:value pairs.

In the following code, we find the MAP estimate of our model.

|  |
| --- |
| 1. **import** pymc3 as pm 2. **import** numpy as np 4. # True parameter values 5. alpha, sigma = 1, 1 6. beta = [1, 2.5] 8. # Size of dataset 9. size = 100 11. # Predictor variable 12. X1 = np.random.randn(size) 13. X2 = np.random.randn(size) \* 0.2 15. # Simulate outcome variable 16. Y = alpha + beta[0] \* X1 + beta[1] \* X2 + np.random.randn(size) \* sigma 18. # Initialize a PyMC model 19. basic\_model = pm.Model() 21. # Define model parameters 22. with basic\_model: 24. # Priors for unknown model parameters, create Normal variables 25. # These are stochastic variables 26. alpha = pm.Normal("alpha", mu=0, sigma=10) 27. beta = pm.Normal("beta", mu=0, sigma=10, shape=2) 28. sigma = pm.HalfNormal("sigma", sigma=1) 30. # Expected value of outcome, completely deterministic variable 31. mu = alpha + beta[0] \* X1 + beta[1] \* X2 33. # Likelihood of observations in the model 34. Y\_obs = pm.Normal("Y\_obs", mu=mu, sigma=sigma, observed=Y)  37. # Use find\_MAP to find maximum a posteriori from a pymc model 38. map\_estimate = pm.find\_MAP(model=basic\_model) 39. **print**(map\_estimate)   **Output:**   100.00% [19/19 00:00<00:00 logp = -163.64, ||grad|| = 11.014]  {'alpha': array(1.03540327), 'beta': array([0.85459263, 2.29026671]), 'sigma\_log\_\_': array(0.0619924), 'sigma': array(1.06395426)} |

The output shows the estimated values of parameters alpha, beta and sigma. It can be observed that the estimated MAP values are closer to the actual values defined in lines 5 and 6 of the code. We generate input (predictor) variables X1 and X2 in lines 12 and 13 of the code. The output is assumed to be a linear combination of the input variables with some noise as defined in line 16. The basic PyMC model is initialized using pm.Model() function. Line 22 uses the keyword “with” to specify the model parameters.

We define parameters alpha and beta to be Normally distributed whereas the parameter sigma to be half Normal. The half Normal distribution has just half of the Normal distribution. For example, if any parameter such as the standard deviation assumes positive values only and follows a Gaussian distribution, we can model it as a half Normal. The likelihood of the observations are also modelled as a Normal distribution in line 34. Finally, function find\_MAP() in line 38 finds the MAP estimate of the parameters.

Sometimes the MAP estimate of the model is not acceptable, particularly when the either the distribution is multimodal (having multiple modes that are meaningfully different), or the mode of the distribution is at an extreme.

PyMC3’s function find\_MAP() is used less common in many situations. If we wish a point estimate such as the mode, we usually get it from the posterior using Monte Carlo sampling methods.

# 8.6 Credible Interval Estimation

The credible interval is the Bayesian counterpart of the confidence interval for the frequentist approach to the interval estimates.

Remember in the frequentist statistics, we defined the probability by frequent runs of the experiment. It is assumed that the population parameters such as average height and the standard deviation of the height are fixed. This parameter, for example, a sample mean is computed from the sample, and its sampling distribution is used for inference of population mean. Since it is often difficult to conduct many trials of the experiment, we resort to the "central limit theorem" that tells us that taking large random samples from the population with replacement results in a Normal distribution for the sample means. The frequentist approach usually chooses an interval in which the population parameter such as the mean of the distribution lies 95% of the time.

In the Bayesian inference of the credible interval, sampling distributions are not used. The degree of belief about the population parameter is modelled as a posterior distribution. For instance, in the coin toss experiment presented in Section 8.4, our degree of belief or the probability of getting a tail or a head is continuously updated as more and more flips of the coin are presented to us.

For instance, we want to estimate the posterior probability of getting heads in a coin toss experiment using Bayesian inference. Recall from Chapter 3, this type of experiment is called as a binomial experiment.

## 8.6.1 Beta Distribution as a Prior

In Bayesian statistics, we have to assume a prior distribution for the parameters to be estimated. The uniform distribution can be used as a prior (flat prior) when the probability of occurrence of every possible outcome is equally likely. In case the coin is fair, the probability of getting heads equals the probability of getting tails and a uniform distribution can be assumed for both heads and tails. However, it may not be case especially when the occurrence of some events is more likely than other events. In this case, the **Beta distribution** is usually used as a conjugate prior for the Bernoulli trials and the binomial model. The word conjugate means that both prior and posterior would result in a similar type of distribution, i.e., a beta prior results in a beta posterior.

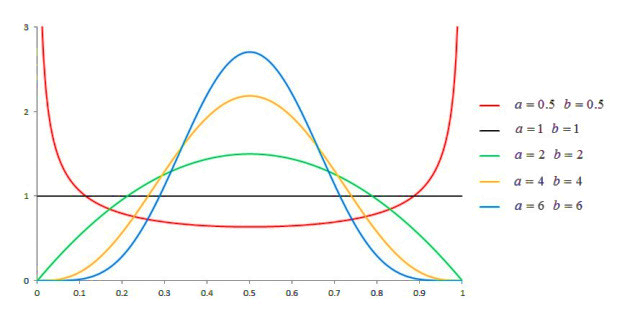
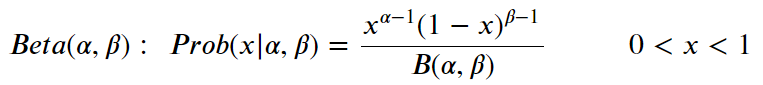


Figure 8.3: Beta distribution for different values of α and β.

Mathematically, the Beta distribution is given as,



where *B* is the beta function that normalizes the Beta distribution to make it a valid probability distribution. It can be observed from the aforementioned equation and Figure 8.3 that, for varying values of α and β, the shape of the Beta distribution varies. If both α and β are set to 1 in the Beta distribution, we get a uniform distribution that is a special case of the Beta distribution. The greater the difference between α and β, the more *skew*ed the resulting Beta distribution is.

Thus, the Beta distribution is able to capture the probability of x successes in repeated trials of a binomial experiment even when the outcomes have different probabilities.

Suppose our initial prior belief about the flipping of a coin is that both heads and tails are equally likely. Thus, we can assume that priors for both parameters α and β are 1. However, when we flipped the coin 100 times, we observed that heads occurred more than the tails. The following Python code shows the simulation of the coin flip experiment.

|  |
| --- |
| 1. ### Estimating the posterior probability in a coin flip experiment done multiple times 2. **import** numpy as np 3. **from** scipy.stats **import** beta, t, norm 4. **from** scipy.special **import** btdtri 5. **import** matplotlib.pyplot as plt 7. p = 0.7 8. n = 100 9. np.random.seed(5)  # to reproduce results 10. num\_heads = np.random.binomial(p=p, n=n) 11. num\_tails = n - num\_heads 12. **print**("successes (heads) = %i, failures (tails) = %i"%(num\_heads, num\_tails))   **Output:**  successes (heads) = 72, failures (tails) = 28 |

In this code, we have assumed that success corresponds to the heads and the failure corresponds to the tails. We have modelled occurring of the heads as *p* =0.7 in line 7 of the code. When binomial experiment is run for *n=*100 times, we observed 72 heads and 28 tails. Line 9 uses np.random.seed (5) to ensure same outcome in each run of the code to reproduce results.

Our initial belief (prior) about a fair coin is updated. Since Beta distribution is used as a prior for binomial model, the following Python code shows the updating of our belief as the posterior distribution.

|  |
| --- |
| 1. ## initially assumed priors for heads and tails before the experiment 2. prior\_a = 1 3. prior\_b = 1 5. a = prior\_a + num\_heads 6. b = prior\_b + num\_tails 7. rv = beta(a, b) 9. x = np.linspace(0, 1, 100) 10. plt.plot(x, rv.pdf(x)) 11. plt.title("Posterior after 100 Throws of a Fair Coin (%i heads, %i tails)" %(num\_heads,num\_tails)) 12. plt.show()   **Output:** |

Lines 2 and 3 of the code, show our initial belief before the run of the experiment. We update our belief in lines 5 and 6 of the code by simply adding number of heads to α and number of tails to β. Line 9 to 12 are used to plot the posterior distribution. It can be seen that the distribution is skewed towards right because the value of α is greater than β.

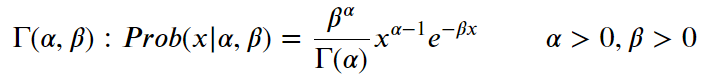
To find the credible interval, we type the following code.

|  |
| --- |
| 1. # The p-th quantile of the beta distribution. 2. b\_up = btdtri(a, b, 0.975) 3. b\_lo = btdtri(a, b, 0.025) 5. plt.plot(x, rv.pdf(x)) 7. right\_line = plt.axvline(b\_up, lw=2, color='blue') 8. left\_line = plt.axvline(b\_lo, lw=2, color='blue') 9. fill = plt.axvspan(b\_lo, b\_up, alpha=0.1, color='green') 11. plt.title("95%% credible interval: [%.3f, %.3f]"%(b\_lo, b\_up)) 12. plt.show()   **Output:** |

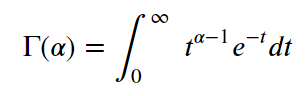
Lines 2 and 3 of the code uses btdtri () function from the SciPy.special package. This function computes the quantiles of the Beta distribution specified by the inputs a and b (corresponding to α and β). It means that it uses inverse cumulative distribution function (the quantile function) of the Beta distribution. Details of the quantile function are given in Chapter 5. For example, 0.025 and 0.975 values in these lines compute the points on the Beta distribution that corresponds to the 97.5 percentile and 2.5 percentile of the distribution. The difference 97.5-2.5 = 95 gives the 95% credible interval. The 95% credible interval means that there is 95% probability that our parameter (probability of success or heads) falls within the range 0.625 and 0.799.

## 8.6.2 Gamma Distribution as a Prior

A Gamma distribution Γ(α, β) with a positive shape parameter α and a positive rate parameter β can be given as:



The Gamma distribution is defined for positive values of the random variable *x*. The rate parameter β can be considered as the inverse of the scale parameter θ, i.e., θ = 1/β. Γ(α) is called the Gamma function, that is given as:



The Gamma function computes the factorial of the positive real numbers. Remember factorial is only defined for integers. However, the integral given in the Gamma function interpolates the factorial for positive non-integers as well. For example,

5! = 5x4x3x2x1 = 120.

The factorial of floating-point (non-integers) such as 5.2! is undefined. However, Γ(5.2) is defined due to the Gamma function that computes the integration.

The following Python code plots a Gamma distribution for shape or alpha parameter of 5 and the rate or beta parameter of 2.5.

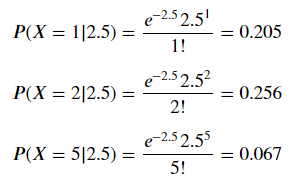
|  |
| --- |
| 1. **import** scipy.stats as stats 2. # Parameters of the prior gamma distribution. 3. a = 5 # shape or alpha 4. b = 2.5 # rate = 1/scale or beta 5. x = np.linspace(start=0, stop=10, num=100) 6. plt.figure(figsize=(8, 6)) 7. plt.plot(x, stats.gamma.pdf(x,a=a,scale=1/b), 'r-') 8. plt.title('Gamma Density Function for a={} and b={}'.format(a,b))   **Output:** |

The presence of an exponential function, shape and rate parameters enable a Gamma distribution to serve as a conjugate prior in Bayesian statistics for the exponential family of distributions such as a **Poisson distribution**.

Suppose it is believed that average number of goals in a football match are 2.5. We want to find out the probability of exact *k* goals in a match. This can be modelled as a Poisson distribution which can be given as:



where λ represents the rate, e is the Euler number (e=2.71828...) and *k* represents the number of occurrences of the event. For example, to find out exactly 1, 2 and 5 goals in a match, we can perform calculations as follows:



Now suppose we observe results of 100 football matches, and print the average number of goals occurred in all 100 matches. The following Python script simulates 100 samples.

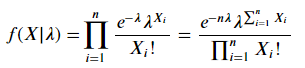
|  |
| --- |
| 1. **import** numpy as np 2. **import** scipy.stats as stats 4. np.random.seed(5)       # using seed to reproduce the results 5. n = 100                 # number of samples. 6. actual\_lambda = 2.5     # true parameter. 7. # sample array. 8. y = np.random.poisson(lam=actual\_lambda, size=n) 9. **print**('The generated Poisson samples are:', y) 10. **print**('\nThe mean of samples is %0.3f' %y.mean())   **Output:**  The generated Poisson samples are: [2 5 1 2 3 3 1 1 3 0 3 1 4 2 4 2 1 4 5 1 2 1 2 5 2 3 0 2 4 4 2 4 2 8 2 1 2  3 1 2 4 6 3 0 3 5 3 3 2 2 1 4 5 3 1 1 1 2 2 5 4 4 2 1 3 5 3 2 2 3 3 3 3 6 3 1 2 1 3 0 1 0 3 5 3 2 2 2 0 1 1 6 7 1 2 4 5 2 3 4]  The mean of samples is 2.640 |

We use np.random.seed(5) to reproduce the results. The average number of goals from 100 matches equals 2.64 that is quite close to the actual\_lambda, 2.5, of the Poisson distribution. We plot the histogram of the 100 samples as follows.

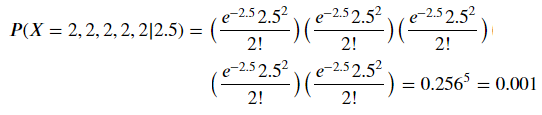
|  |
| --- |
| 1. **import** matplotlib.pyplot as plt 2. %matplotlib inline 3. # Histogram of the sample data 4. plt.figure(figsize=(7, 5)) 5. plt.hist(y, bins=8, color='b') 6. plt.title('Histogram of the Generated Data') 7. plt.show()   **Output:** |

A peak can be observed between 2 and 3 in the histogram, that indicates 2 to 3 goals in more than 25 matches.

Since each match is independent of the other match, the observations or the number of goals scored in each match are independent of each other. Thus, the likelihood function given the λ parameter of the Poisson model is given as:



where the symbol Π means product of individual probabilities. For instance, if we want to find the probability of the event of observing 2 goals in first 5 matches, the aforementioned equation becomes



Thus, the chances of observing exactly 2 goals in 5 matches is very low 0.001. If we have to find the probability of observing 2 goals in all 100 matches, we would have a very small number 0.256100 ~ 0. Due to this reason, mostly we use **log likelihood** instead of simple likelihood due to very small probabilities. The log function amplifies small numbers. Thus, we get rid of this problem of dealing with very small numbers.

The computation of the probabilities in a Bayesian model become enormous when we have a lot of observations. Furthermore, the computation of the evidence, the denominator, is usually not easy. Thus, instead of computing the posterior directly form the evidence, likelihood and the prior, we construct the posterior by taking its samples using **Monte Carlo techniques**.

We assume a Gamma distribution as the prior and the likelihood of the aforementioned Poisson process related to average number of goals in a football match.

The following code shows how to perform this using Python’s PyMC3 package.

|  |
| --- |
| 1. **import** pymc3 as pm 2. model = pm.Model() 3. with model: 5. # Define the prior of the parameter lambda. 6. lam = pm.Gamma('lambda', alpha=a, beta=b) 7. # Define the likelihood function. 8. y\_obs = pm.Poisson('y\_obs', mu=lam, observed=y) 9. # Consider 1000 draws and 2 chains. 10. trace = pm.sample(draws=1000, chains=2)   **Output:**  Auto-assigning NUTS sampler...  Initializing NUTS using jitter+adapt\_diag...  Multiprocess sampling (2 chains in 4 jobs)  NUTS: [lambda]  100.00% [4000/4000 00:02<00:00 Sampling 2 chains, 0 divergences]  Sampling 2 chains for 1\_000 tune and 1\_000 draw iterations (2\_000 + 2\_000 draws total) took 12 seconds. |

Line 2 of the code initiates a PyMC model, whereas the parameters of the Bayesian model are specified using keyword “with” with the model name. We define the Gamma prior for our process, and the Poisson likelihood since the observed data is assumed to be coming from a Poisson distribution. The parameters of the Gamma distribution in line 6 of the code are specified by variables a and b, whereas the parameter mu of the Poisson distribution corresponds to the λ, and is assumed to be Gamma distributed because in Bayesian inference the parameter is considered a random variable. This is in contrast to the frequentist inference where the parameter of the model is considered fixed and is not assigned any probability.

The PyMC function sample () in line 10 takes the samples of the posterior based upon defined prior and the likelihood. The number of samples to draw are specified by the option draws, whereas the option chains specifies the number of Markov chains to take samples from. These samples are referred to as trace in PyMC. Markov chains is a process usually employed by Monte Carlo methods to get samples from the posterior. Since number of chains are 2, in the output of the code, we see 2000 draws, of which 1000 good draws are returned to us.

To plot the output trace and the posterior, we may type the following commands.

|  |
| --- |
| 1. pm.traceplot(trace) 3. pm.plot\_posterior(trace,  hdi\_prob=.95)   **Output:** |

Line 1 of the code plots the posterior of the lambda parameter which is assumed to be Gamma distributed in PyMC model. The option hdi\_prob plots **Highest Density Interval (HDI)** of the posterior for the chosen percentage of density. HDI refers to the region in which posterior has high density. In our case, we plot 95% HDI that corresponds to the 0.95 credible interval. It can be observed that the mean posterior lambda is 2.6, and the 0.95 credible interval lies between 2.3 and 2.9.

# 8.7 Naïve Bayes Classification

The classification is the problem of estimating the output target variable when it is discrete. The difference between regression and classification is that in the former the output variable is continuous whereas in the latter the output variable is discrete that represents the classes or categories.

Naive Bayes is one of the simplest classification algorithms that is based on Bayes Theorem of probability. A basic assumption that Naive Bayes classifier uses is the independence of input variables / features. This assumption is considered as naive which simplifies computations. In terms of probability, this assumption is called class conditional independence.

Suppose based upon weather conditions, we want to predict whether to play or not on a particular day. We have access to some previous data along with the output label corresponding to whether the game was played or not. We use the Naïve Bayes’ algorithm to predict /classify the output variable.

To implement the Naïve Bayes’ algorithm in Python, we may write the following script.

|  |
| --- |
| 1. #Import Gaussian Naive Bayes model 2. **from** sklearn.naive\_bayes **import** GaussianNB 4. **from** sklearn **import** preprocessing 6. # Assigning features and label variables 7. weather=['Sunny','Sunny','Overcast','Rainy','Rainy','Rainy','Overcast','Sunny','Sunny', 8. 'Rainy','Sunny','Overcast','Overcast','Rainy'] 9. temp=['Hot','Hot','Hot','Mild','Cool','Cool','Cool','Mild','Cool','Mild','Mild','Mild','Hot','Mild'] 11. play=['No','No','Yes','Yes','Yes','No','Yes','No','Yes','Yes','Yes','Yes','Yes','No'] 13. #creating label Encoder 14. le = preprocessing.LabelEncoder() 15. # Converting string labels into numbers. 16. weather\_encoded=le.fit\_transform(weather) 17. **print** ("Weather:",weather\_encoded) 19. # Encode temp and play columns to convert string labels into numbers 20. temp\_encoded=le.fit\_transform(temp) 21. label=le.fit\_transform(play) 22. **print** ("Temp:",temp\_encoded) 23. **print** ("Play:",label) 25. #Combining features weather and temp in a single variable (list of tuples). 27. features=np.column\_stack((weather\_encoded,temp\_encoded)) 28. **print** ("Combined feature:",features) 30. # Generate a model using naive bayes classifier in the following steps: 31. # 1. Create naive bayes classifier 32. # 2. Fit the dataset on classifier 33. # 3. Perform prediction 35. #Create a Gaussian Classifier 36. model = GaussianNB() 38. # Train the model using the training sets 39. model.fit(features,label) 41. #Predict Output for input 0:Overcast, 2:Mild 43. predicted= model.predict([[0,2]]) 44. **print** ("Predicted Value:", predicted)   **Output:**  Weather: [2 2 0 1 1 1 0 2 2 1 2 0 0 1]  Temp: [1 1 1 2 0 0 0 2 0 2 2 2 1 2]  Play: [0 0 1 1 1 0 1 0 1 1 1 1 1 0]  Combined feature: [[2 1]  [2 1]  [0 1]  [1 2]  [1 0]  [1 0]  [0 0]  [2 2]  [2 0]  [1 2]  [2 2]  [0 2]  [0 1]  [1 2]]  Predicted Value: [1] |

This program uses sci-kit learn library that contains numerous machine learning algorithms. Lines 7 to 11 are used to enter the input and the output variables. Since strings are difficult to work with, we convert string feature values and output labels into integers using label encoding method preprocessing.LabelEncoder ().The functionfit\_transform ()in lines 16, 20 and 21 converts string labels into numbers.

We create a Gaussian Naïve Bayes’ classifier model in line 36, and train this model using the available observations / training data using model.fit () in line 39. To predict a new test point corresponding to the input 0: overcast weather and 2:mild temperature, we use predict () function that results in a predicted value of 1: play the game.

Naïve Bayes is easy to implement and interpret. It performs better compared to other similar models when the input features are independent of each other. It requires a small amount of training data to estimate the test data.

The main limitation of Naïve Bayes is the assumption of independence between the independent variables. If features are dependent, this algorithm cannot be applied. Dimensionality reduction techniques can be used to transform the features into a set of independent features before applying the Naïve Bayes classifier.

# 8.8 Comparison of Frequentist and Bayesian Inferences

The frequentist inference assumes that the sample data is random and incomplete. It has come from an unknown population whose parameters have to be estimated. The sample data is used to make inference about unknown population parameters. The frequentist inference assumes that there is a single fixed true value of the unknown parameter.

The frequentist inference uses confidence statements instead of direct probability about the parameters. Parameters are usually specified in terms of the confidence level we have about their true range of values. It is important to realize that a confidence level of say 0.95 or 95% does not mean a probability of 0.95.

The main strength of the frequentist inference is that it does not need any prior knowledge of the process or experiment from which the inference has to be made about the population.

The main weakness of the frequentist approach lies in its interpretation of the probability, the frequency of occurrence of a particular event, in a long-run of trials.

In the frequentist statistics, we cannot assign probabilities to those events which cannot be repeated. However, it is normal to assign probabilities to non-repeatable events in the Bayesian statistics.

The Bayesian inference employs a single tool, Bayes’ theorem, in contrast to the frequentist inference that has to use many different tools such as z-value, p-value and critical regions etc. to infer from the data.

In Bayesian statistics, it is easy to get rid of difficult parameters by marginalized them out of the joint posterior distribution. Furthermore, Bayesian statistics provides us the means to determine the distribution of future observations. This is not an easy task if we do the things in a frequentist way.

The main disadvantage of the Bayesian inference is the subjective view of the probability. The prior about an event or a process may vary from one expert to another which would result in different estimates of the posteriors.

# 8.9 Exercise Questions

**Question 1:**

Which distribution is usually used as a prior for Bernoulli trials and binomial experiments?

A. Normal distribution

B. Poisson distribution

C. Beta distribution

D. Gamma distribution

**Question 2:**

Which distribution is usually used as a prior for the distributions involving a parameter related to average rate of occurrence of a certain event?

A. Normal distribution

B. Poisson distribution

C. Beta distribution

D. Gamma distribution

**Question 3:**

Which one of the following credible intervals for a specific parameter of a distribution would have minimum width?

A. 99%

B. 90%

C. 95%

D. 100%

**Question 4:**

Suppose we have been given the following credible intervals. Which one would be better?

A. 95% credible interval with the range [2, 4]

B. 90% credible interval with the range [2, 4]

C. 95% credible interval with the range [3, 3.5]

D. 90% credible interval with the range [3, 3.5]

**Question 5:**

The classification is the problem of estimating the \_\_\_\_\_\_\_\_\_\_\_ variable when it is \_\_\_\_\_\_\_\_\_\_\_.

A. output target, discrete.

B. output target, continuous.

C. input target, discrete.

D. input target, continuous.

**Question 6:**

Log likelihood is preferred instead of simple likelihood because of?

A. Avoiding very high values of the probability

B. Avoiding very small values of the probability

C. Avoiding the computation of the evidence

D. Sampling of the posterior probability

**Question 7:**

Maximum Likelihood Estimation (MLE) is used for \_\_\_\_\_\_\_\_\_\_\_\_\_ whereas Maximum a Posteriori (MAP) estimation is used for \_\_\_\_\_\_\_\_\_\_\_ inference?

A. Bayesian, Frequentist

B. Frequentist, Bayesian

C. Prior, Posterior

D. Posterior, Prior

**Question 8:**

Monte Carlo methods are used to \_\_\_\_\_\_\_\_\_\_\_\_ the \_\_\_\_\_\_\_\_\_\_ distribution?

A. Randomize, Likelihood

B. Randomize, Posterior

C. Sample, Posterior

D. Sample, Likelihood

**Question 9:**

Suppose we have 10 students, out of which 7 are female and 3 are male. We define the following events:

1. Event A: Selecting a female student for a sports event;
2. Event B: Selecting a male student for a sports event.

What is the probability of selecting a female and a male student together?

**Hint:** find probability of happening of event A and B together.

A. 21/90

B. 70/90

C. 7/10

D. 21/100

**Question 10:**

Suppose we have 10 students, out of which 7 are female and 3 are male. We define the following events:

1. Event A: Selecting a female student for a sports event;
2. Event B: Selecting a male student for a sports event.

What is the probability of selecting a female student, if we have already selected a male student?

**Hint:** find probability of event A, given B has already occurred?

A. 21/90

B. 70/90

C. 7/10

D. 3/9

Chapter 9: Hands-on Projects

This chapter presents two projects to give the reader a better understanding of the concepts introduced in previous chapters.

The first project performs A/B testing which is a statistical experiment where we test two or more alternative choices against each other to decide the one that performs better than other. It is a classical hypothesis testing problem where we state the null and the alternative hypothesis. Confidence intervals are analyzed to reject or accept the null hypothesis in favor of or against the alternative hypothesis, respectively.

The second project deals with linear regression using both frequentist and Bayesian methods. For frequentist inference of linear regression parameters, we use ordinary least squares (OLS), whereas, for Bayesian inference, we make use of Monte Carlo simulation to sample posterior probabilities, and use credible intervals to make decisions. We give details of these projects in the following sections.

# 9.1 Project 1: A/B Testing Hypothesis – Frequentist Inference

A/B testing is used to test changes in features of a product or its new features. We split the product users in two categories:

* **experiment or test group**, that consists of those users which are introduced to the new features of the product;
* **control group,** that uses the product without new features.

We conduct a comparison between these two groups to decide whether new features of the product are better than the original old features.

A/B testing allows us to select the better option based upon the statistical tests. A/B testing may not be appropriate to test major changes such as completely new products. To design an A/B test, we may need to look at the external historical data to get insights about the similar experiments.

Suitable metrics should be chosen for A/B testing. These metrics include sums and counts; e.g., how many users visit a particular webpage daily. Other metrics include probability or ratio of probabilities, mean, median and quartiles etc. For instance, what are average or mean number of users of a particular product or its features. Another example may be the percentage of a web page visitors who follow a links to other specific web sites.

In the first step, we decide on a particular metric, for example, the average number of active users who visit an online product or technology. Here, active may be defined as a user who visits the web page at least twice a week. The next step is to decide on the minimum number of observations to conduct the A/B testing. The following test parameters should be kept in mind to enable the calculation of a suitable sample size:

* **Baseline conversion rate** is the current conversion rate for the online web page we are testing. The conversion rate can be defined as the number of conversions (to premium content, for example) divided by the total number of visitors. This rate corresponds to the time before any change is made in the product or web page.
* **Significance level** is the minimum change to the baseline rate, for example, an increase in the conversion rate of 2% might be good for the business.
* **Confidence level,** a range of reasonable values in which we expect to have the true population parameter.

The baseline conversion rate is estimated from the historical data. The significance level depends upon the needs of the business, whereas the confidence level is commonly set at 95%.

Once we finalize the aforementioned steps, it is time to implement A/B testing in Python. We download a publicly available dataset from *Kaggle* that is used to test the conversion rates of control and treatment (test) groups related to the old and the new web pages, respectively. The dataset can be downloaded from <https://www.kaggle.com/zhangluyuan/ab-testing>.

This dataset contains 294478 rows of observations. We define the null and the alternative hypotheses as follows:



Where *p*0 and *p* are the conversion rates of the old and the new designs, respectively. The null hypothesis *H*0 can be interpreted as the probabilities of conversion in the control and the test groups are equal. The alternative hypothesis *H*a states that the probabilities of conversion in the control and the test groups are not equal.

We set a confidence level of 95%, i.e.,

𝛼=(1-0.95)=0.05.

The user defined threshold 𝛼 implies that if the p-value is lower than 𝛼, we reject the null hypothesis.

In other words, the conversion rate we observe for the test group should be statistically different from the conversion rate of the control group in such a way that our confidence is 95%. If it is the case, we decide to reject the null hypothesis 𝐻0, i.e., we accept the new design.

**Effect size** is a measure to evaluate the strength of a statistical claim. It usually refers to a statistic calculated from sample data such as the correlation between two variables and the mean difference. Effect sizes are used in statistical hypothesis testing to calculate the power of a statistical test. The [standard deviation](https://en.wikipedia.org/wiki/Standard_deviation) of the effect size indicates the amount of uncertainty in the measurement.

The effect size is directly related to the difference we expect in conversion rates between the control and the treatment groups. In this project, we set the effect size to 2.5%. Thus, we compute the effect size using baseline conversion rate of, for example, 13% and expected conversion rate of 15.5% in the treatment group (15.5-13 = 2.5%).

The minimum sample size required for the A/B testing is estimated using **the power of the test**. Recall from Section 6.5.2 that the power of the test is defined as (1−𝛽). This corresponds to the probability of discovering a statistical difference between the control and the treatment groups when the difference actually exists. A typical value of this is generally set at 0.8. The

value of Alpha 𝛼 is set earlier at 0.05 from 95% confidence interval.

The following Python code, after importing necessary packages and libraries, computes the effect size and then the sample size required using the power of the test.

|  |
| --- |
| 1. # Importing Packages and Libraries 2. **import** numpy as np 3. **import** pandas as pd 4. **import** scipy.stats as stats 5. **import** statsmodels.stats.api as sms 6. **import** matplotlib.pyplot as plt 7. **import** seaborn as sns 8. %matplotlib inline 10. # Calculating effect size based on our expected rates 11. effect\_size = sms.proportion\_effectsize(0.13, 0.155) 12. # Calculation of the required sample size 13. required\_sample\_size = sms.NormalIndPower().solve\_power(effect\_size, alpha=0.05, power=0.8, ratio=1) 14. required\_sample\_size = np.ceil(required\_sample\_size) 15. **print**(required\_sample\_size)   **Output:**  3064.0 |

The function proportion\_effectsize () from the Statsmodel.stats.api specified in line 11 of the code takes two conversion rates as the input and computes the effect size to be used in power of the test. The function NormalIndPower().solve\_power () takes any 3 of the following parameters as its input and computes the fourth parameter:

* **Effect\_size**isrelated to the difference we expect in conversion rates between the control and the treatment groups.
* **Alpha (α)** is the probability of a type I error, that is wrong rejections if the Null Hypothesis is true.
* **Nobs1** number of observations of sample.
* **Power of the test (1-β)** is one minus the probability of a type II error. It is the probability that the test correctly rejects the null hypothesis if the alternative hypothesis is true.
* **Ratio** of number of observations in sample 2 relative to sample 1. It is usually set to 1.

Here, we intend to find number of observations of sample 1. The output of the program indicates that at least 3064 observations of each group are required.

The aforementioned settings of the parameters specify that, with a power parameter set to 0.8, if there is an actual difference in two conversion rates, i.e., 2.5% (15.5%-13%), we have about 80% chance to detect it as statistically significant in our test with the calculated sample size.

We load our downloaded dataset as a Pandas DataFrame as follows.

|  |
| --- |
| 1. df = pd.read\_csv('ab\_data.csv') 2. df.info() 3. df.head(10)   **Output:**  <class 'pandas.core.frame.DataFrame'>  RangeIndex: 294478 entries, 0 to 294477  Data columns (total 5 columns):  # Column Non-Null Count Dtype  --- ------ -------------- -----  0 user\_id 294478 non-null int64  1 timestamp 294478 non-null object  2 group 294478 non-null object  3 landing\_page 294478 non-null object  4 converted 294478 non-null int64  dtypes: int64(2), object(3)  memory usage: 11.2+ MB |

The first line reads our dataset which is saved as a comma separated value file (.csv extension). We check the information of the loaded dataset in the second line. Finally, third line of the code shows first 10 row entries (each row is one observation) of the dataset. It can be observed that there is a total of 294478 observations, each having 5 columns or feature variables. The columns **user\_id** and the **timestamp** show the user ID of each session and the time of the session, respectively.

The column **group** shows two different types of user categories: the user assigned to the control or the treatment group. The **landing\_page** column shows which design of the web page, old or new, did the user land to. The column named converted shows the status of the users whether a conversion is made or not where 0=not converted and 1=converted.

We check the cross tabulation of the control and the treatment groups by Pandas crosstab () function.

|  |
| --- |
| 1. # Computing cross tabulation or frequency table of groups. 2. pd.crosstab(df['group'], df['landing\_page'])   **Output:** |

It can be observed that some users in the control group are incorrectly exposed to the new\_page, and the users of the treatment group are incorrectly exposed to the old\_page,

We check if some users appear multiple times to check duplicate entries in the dataset.

|  |
| --- |
| 1. # Checking users who appear multiple times in the dataset. 2. num\_sessions = df['user\_id'].value\_counts() 3. user\_mul\_times = num\_sessions[num\_sessions > 1].count() 5. **print**('There are %s users that appear multiple times in the dataset' %user\_mul\_times)   **Output:**  There are 3894 users that appear multiple times in the dataset |

We get rid of these duplicate entries to avoid sampling of the same user multiple times.

|  |
| --- |
| 1. remove\_users = num\_sessions[num\_sessions > 1].index 3. df = df[~df['user\_id'].isin(remove\_users)] 4. **print**(f'''''The updated dataset has {df.shape[0]} observations 5. after we have removed the users who appear multiple times.''')   **Output:**  The updated dataset has 286690 observations  after we have removed the users who appear multiple times. |

The first line gets the indices of the users who appear in multiple sessions. These indices are used in isin () function that returns the values in df['user\_id'] which are in the given list, and the ~ at the beginning is a not operator.

df['user\_id'].isin(remove\_users) returns those indices which corresponds to the IDs to be removed. However,

~ df['user\_id'].isin(remove\_users) is used to find those indices which corresponds to the IDs to keep. Thus, we get 286690 observations after we have removed the users that appear multiple times in the dataset.

Since we have already calculated the required sample size to be used for A/B testing, we do not need to work with all the observations of the dataset. We sample both the control and the treatment groups for the required sample size in the following Python script.

|  |
| --- |
| 1. control\_sample = df[df['group'] == 'control'].sample(n=int(required\_sample\_size), random\_state=5) 2. treatment\_sample = df[df['group'] == 'treatment'].sample(n=int(required\_sample\_size), random\_state=5) 4. ab\_test = pd.concat([control\_sample, treatment\_sample], axis=0) 5. ab\_test.reset\_index(drop=True, inplace=True)  8. ab\_test.info() 9. **print**('\n \n') 10. ab\_test['group'].value\_counts()   **Output:**  <class 'pandas.core.frame.DataFrame'>  RangeIndex: 6128 entries, 0 to 6127  Data columns (total 5 columns):  # Column Non-Null Count Dtype  --- ------ -------------- -----  0 user\_id 6128 non-null int64  1 timestamp 6128 non-null object  2 group 6128 non-null object  3 landing\_page 6128 non-null object  4 converted 6128 non-null int64  dtypes: int64(2), object(3)  memory usage: 239.5+ KB  treatment 3064  control 3064  Name: group, dtype: int64 |

In lines 2 and 3, we select the observations corresponding to the control and the treatment groups, respectively. The function sample () is used to take a random sample equal to the size of the variable required\_sample\_size. Note that we have converted this variable to an integer because the sample () requires an integer input rather than a float.

In lines 4 and 5, we first concatenate both groups as a single DataFrame namely ab\_test, then the indices of the DataFrame are reset. This is done inplace to update the DataFrame without creating a new dummy object. The output shows that there is a total of 6128 entries out of which half entries are for the control and the remaining half are for the treatment group.

Once we are done with the sampling, we visualize the results, i.e., the conversion rates for both groups.

|  |
| --- |
| 1. conversion\_rates = ab\_test.groupby('group')['converted'] 2. # Std. deviation of the proportion 3. std\_p = **lambda** x: np.std(x, ddof=0) 4. # Std. error of the proportion 5. se\_p = **lambda** x: stats.sem(x, ddof=0) 6. conversion\_rates = conversion\_rates.agg([np.mean, std\_p, se\_p]) 7. conversion\_rates.columns = ['conversion\_rate', 'std\_deviation', 'std\_error'] 9. conversion\_rates.style.format('{:.4f}')   **Output:** |

We compute the standard deviation and the standard error [σ/*√n*] of both groups. Furthermore, these results are aggregated based upon the mean, standard deviation and the standard error in line 7 of the code.

These results show that two designs of the web pages perform quite similar 12.37% and 12.7% conversion rates for the control and the treatment groups, respectively. We plot these results.

|  |
| --- |
| 1. # plotting the results 2. plt.figure(figsize=(6,6)) 3. sns.barplot(x=ab\_test['group'], y=ab\_test['converted']) 5. plt.ylim(0, 0.15) 6. plt.title('Conversion Rate of Control and Treatment Groups') 7. plt.xlabel('Group') 8. plt.ylabel('Converted (proportion)')   **Output:** |

The black vertical line in both bars represent the 95% confidence interval. The treatment group has a slightly greater conversion rate than the control group. We check if this small increment is statistically significant.

Finally, we test our hypothesis. We use a Normal approximation to compute p-value in a z-test. We import statsmodels.stats.proportion module to get the p-value and confidence intervals. We also find the number of conversions in both control and the treatment groups as follows.

|  |
| --- |
| 1. **from** statsmodels.stats.proportion **import** proportions\_ztest, proportion\_confint 2. converted\_control = ab\_test[ab\_test['group'] == 'control']['converted'] 3. converted\_treatment = ab\_test[ab\_test['group'] == 'treatment']['converted']  6. n\_control = converted\_control.count() 7. n\_treatment = converted\_treatment.count() 8. successes = [converted\_control.sum(), converted\_treatment.sum()] 9. nobs = [n\_control, n\_treatment] 11. z\_stat, pval = proportions\_ztest(successes, nobs=nobs) 12. (lower\_con, lower\_treat), (upper\_con, upper\_treat) = proportion\_confint(successes, nobs=nobs, alpha=0.05) 14. **print**(f'z statistic: {z\_stat:.2f}') 15. **print**(f'p-value: {pval:.3f}') 16. **print**(f'95% confidence interval for control group: [{lower\_con:.3f}, {upper\_con:.3f}]') 17. **print**(f'95% confidence interval for treatment group: [{lower\_treat:.3f}, {upper\_treat:.3f}]')   **Output:**  z statistic: -0.39  p-value: 0.700  95% confidence interval for control group: [0.112, 0.135]  95% confidence interval for treatment group: [0.115, 0.139] |

In lines 2 and 3, we separate those control and treatment observations which result in conversion from the DataFrame ab\_test. Lines 6 and 7 of the code compute the number of conversions for both groups. Line 11 of the code computes the z-statistic and the p-value from the successes. Line 12 uses function proportion\_confint () to get confidence intervals for a binomial proportion.

The results show that the p-value=0.700 is greater than the set significance level 𝛼 =0.05. This implies that the probability of observing extreme results is small. Thus, we shall not reject the null hypothesis 𝐻0. In conclusion, the new web page (new design) does not perform significantly better than the old design.

The limits in 95% confidence interval for the treatment group ([0.115, 0.139] contains the baseline 13% conversion rate; however, it does not include 15.5% target. Thus, the new design is unable to meet our expectations.

# 9.2 Project 2: Linear Regression using Frequentist and Bayesian Approaches

There are mainly two types of supervised learning algorithms: classification and regression. If the output labels have a continuous range of values, it is a regression problem. For example, the prediction of house prices from a given dataset is a regression problem.

If the relationship between the input features and the output target variable is assumed linear, the regression would be linear. Otherwise, it would be non-linear. Here, we discuss linear regression that is more prevalent than its non-linear counterpart.

The objective of a linear regression model is to find a relationship between one or more independent input features and a continuous target variable which is dependent upon the input features. When there is only one feature it is called univariate or simple linear regression problem, whereas the case of multiple input features is known as **multiple linear regression**. The linear regression model can be represented by the following equation.

where is the predicted value, is the bias term, are model parameters, are (*n+1)* input features, and represents the noise in the measurements. This regression model can be compactly represented as

where = is the vector that contains all the parameters of the model and  is the vector of features. The learned function serves as an estimate of the output target variable . The solution to the linear regression problem can be given as

This solution is obtained using a mathematical technique known as Ordinary Least Squares (OLS) that gives us the maximum likelihood estimate of the parameter vector

If we have one feature, the parameters correspond to the y-intercept and the slope of the line. However, in case of more than one input feature as in the aforementioned model, the concept of a line is extended to a plane or a hyper-plane in more than 2 dimensions.

To implement the linear regression in Python, we first load our dataset in a Pandas DataFrame.

|  |
| --- |
| 1. # Importing packages 2. **import** pandas as pd 3. **import** numpy as np 4. **import** matplotlib.pyplot as plt 5. %matplotlib inline 6. **import** seaborn as sns 7. **import** scipy          # Scipy for statistics 8. # PyMC3 for Bayesian Inference 9. **import** pymc3 as pm 10. # Loading and displaying datasets 11. exercise = pd.read\_csv('exercise.csv')    # give path of the dataset files 12. calories = pd.read\_csv('calories.csv') 13. df = pd.merge(exercise, calories, on = 'User\_ID') 14. df = df[df['Calories'] < 300] 15. df = df.reset\_index() 16. df['Intercept'] = 1 17. df.head(10)   **Output:** |

After importing required packages, we load the already downloaded datasets **exercise.csv** and **calories.csv**. These two datasets can be downloaded from <https://www.kaggle.com/fmendes/exercise-and-calories>

The **exercise** dataset has the following 8 columns: User\_ID, Gender, Age, Height, Weight, Duration, Heart\_Rate and Body\_Temp, whereas the **calories** dataset contains only 2 columns: User\_ID and Calories. We merge these two datasets together in line 14 of the code to find the relationship between the duration of the exercise and the calories burnt.

The following code plots the calories burnt against the time spent in exercise.

|  |
| --- |
| 1. plt.figure(figsize=(8, 8)) 3. plt.plot(df['Duration'], df['Calories'], 'rx'); 4. plt.xlabel('Duration (min)', size = 15); plt.ylabel('Calories', size = 15); 5. plt.title('Calories burned vs Duration of Exercise', size = 15);   **Output:** |

Each red color x mark on this graph shows one data point (observation) in the combined dataset. The time is measured in integer values of minutes; therefore, we do not see a continuous plot here. Instead, we observe discrete points on the plot corresponding to integer values of duration of exercise in minutes.

## 9.2.1 Frequentist Approach

We create X features and y output target variable as follows.

|  |
| --- |
| 1. # Create the features and response 2. X = df.loc[:, ['Intercept', 'Duration']] 3. y = df.loc[:, 'Calories'] 4. X.head(8)   **Output:** |

Note that an intercept =1 is required in X because of the presence of the term . The intercept corresponds to in our model.

We find the OLS solution to the linear regression model between feature duration and the response calories burnt as follows.

|  |
| --- |
| 1. # Ordinary Least Squares calculations 2. ols\_coefs = np.matmul(np.matmul(          np.linalg.inv(X.T.dot(X)) , X.T), y) 3. **print**(f'Intercept calculated: {ols\_coefs [0]}') 4. **print**(f'Slope calculated: {ols\_coefs[1]}')   **Output:**  Intercept calculated: -21.828102526050735  Slope calculated: 7.16978334958786 |

X.T in line 2 of the code computes the transpose of the matrix, X.T.dot(X) computes the term XTX, the NumPy linear algebra function np.linalg.inv () computes the matrix inverse, and np.matmul () performs matrix multiplication. The output shows two estimated parameters: the intercept () and the slope ().

We plot the estimated parameters along with the data points as follows.

|  |
| --- |
| 1. xs = np.linspace(4, 30, 1000) 2. ys = ols\_coefs[0] + ols\_coefs[1] \* xs 4. plt.figure(figsize=(8, 8)) 6. plt.plot(df['Duration'], df['Calories'], 'rx',label = 'observations', alpha = 0.8) 7. plt.xlabel('Duration (min)', size = 15); plt.ylabel('Calories', size = 15) 8. plt.plot(xs, ys, 'b--', label = 'OLS Fit', linewidth = 3) 9. plt.legend(prop={'size': 14}) 10. plt.title('Calories burned vs Duration of Exercise', size = 16);   **Output:** |

The blue color line that passes almost in the middle through the observed data points is the OLS fit to our data. Note that a line in a 2-dimensional space is described by 2 parameters as in the simple linear regression model. Had we used multiple input features; we would have to estimate more than 2 parameters of the linear regression model in higher dimensions.

Now to check the estimated output (calories burnt) against a specific input point (duration), we type the following code.

|  |
| --- |
| 1. #specifying a point against which the OLS estimate is to be calculated. 2. specific\_point = 15 4. OLS\_estimate = ols\_coefs[0] + ols\_coefs[1] \* specific\_point 6. **print**('Exercising for {:.0f} minutes will burn an estimated {:.2f} calories.'. 7. format(specific\_point, OLS\_estimate))   **Output:**  Exercising for 15 minutes will burn an estimated 85.72 calories. |

Line 4 of the code, uses a specific\_point as input to the estimated model. The OLS estimated against 20minute duration is found to be 121.57 calories. This is the way how we perform testing once we have learnt the parameters of our model. Every future test point is passed through an equation given in line 4 of the code to find its estimated output target variable.

## 9.2.2 Bayesian Approach

The aforementioned linear regression model is computed using the **frequentist** approach. The OLS gave us the maximum likelihood estimate (MLE) of the model parameters. To find the Bayesian solution, we have to specify a prior along with the likelihood function.

We resort to the PyMC module for specifying parameters of a Bayesian model. Suppose, we have access to only a few observations. Let the number of observations be 1000. The following code specifies a Bayesian linear regression model with 1000 observations using PyMC.

|  |
| --- |
| 1. with pm.Model() as linear\_model: 2. # Intercept modeled as Normally distributed 3. intercept = pm.Normal('Intercept', mu = 0, sd = 10) 4. # Slope modeled as Normally distributed 5. slope = pm.Normal('slope', mu = 0, sd = 10) 6. # Standard deviation modeled as half Normally distributed 7. sigma = pm.HalfNormal('sigma', sd = 10) 9. # Estimate of mean 10. mean = intercept + slope \* X.loc[:, 'Duration'] 12. # Observed values 13. Y\_obs = pm.Normal('Y\_obs', mu = mean, sd = sigma, observed = y.values) 15. # Sampler 16. step = pm.NUTS() 18. # Posterior distribution 19. linear\_trace = pm.sample(1000, step)   **Output:**  Multiprocess sampling (2 chains in 2 jobs)  NUTS: [sigma, slope, Intercept]  100.00% [4000/4000 00:35<00:00 Sampling 2 chains, 0 divergences]  Sampling 2 chains for 1\_000 tune and 1\_000 draw iterations (2\_000 + 2\_000 draws total) took 80 seconds.  The acceptance probability does not match the target. It is 0.9031750942338022, but should be close to 0.8. Try to increase the number of tuning steps.  The acceptance probability does not match the target. It is 0.8877011100124582, but should be close to 0.8. Try to increase the number of tuning steps. |

In Bayesian inference, the parameters of the model are not considered fixed; thus, we model both parameters intercept and the slope as Normally distributed with a zero mean and standard deviation 10. The standard deviation can only be positive; thus, it is modeled as a half Normal having only positive values. Line 10 estimates the mean value of the target variable from the linear regression model using the intercept and the slope defined in lines 3 and 5, respectively.

Line 13 of the code models the observed variable as a Normal with the mean estimated in line 10, and the standard deviation modeled as half Normal in line 7 of the code. It uses 500 observed values of the output variable.

Line 19 of the code takes 1000 samples of the posterior distribution using a built-in No U-Turn Sampler (NUTS) that is specified as an option to the function sample ().

The sample posterior is known as trace in PyMC. We plot the trace as follows.

|  |
| --- |
| 1. pm.traceplot(linear\_trace, figsize = (10, 10))   **Output:** |

Three plots in the output correspond to the intercept, slope and the standard deviation. The right-hand side of the figures shows samples, whereas the left side shows the histogram of these samples. It can be seen in the output plots given on left side of the figure that all three posteriors are Normally distributed. Furthermore, the peaks of these distributions correspond to the mode of the distribution, i.e., the Maximum A Posteriori (MAP) estimates of the parameters of the model. For instance, the slope is peaked between 7.1 and 7.2.

To get a better idea about the posteriors, we plot the posterior distributions as follows.

|  |
| --- |
| 1. pm.plot\_posterior(linear\_trace, figsize = (10, 8))   **Output:** |

The three plots show the mean values of the estimated posterior distributions along with the default 94% credible interval.

We plot these estimates along the frequentist estimates on the plot of the original dataset.

|  |
| --- |
| 1. plt.figure(figsize = (8, 8)) 2. pm.plot\_posterior\_predictive\_glm(linear\_trace, samples = 100, eval=np.linspace(2, 30, 100), linewidth = 1, 3. color = 'blue', alpha = 0.8, label = 'Bayesian Posterior Fits', 4. lm = **lambda** x, sample: sample['Intercept'] + sample['slope'] \* x) 5. plt.scatter(X['Duration'][:500], y.values[:500], s = 12, alpha = 0.8, c = 'red', label = 'Observations') 6. plt.plot(X['Duration'], ols\_coefs[0] + X['Duration'] \* ols\_coefs[1], 'k--', label = 'OLS Fit', linewidth = 1.4) 7. plt.title('Posterior Predictions with Limited Observations', size = 15); plt.xlabel('Duration (min)', size = 15) 8. plt.ylabel('Calories', size = 15) 9. plt.legend(prop={'size': 12})   **Output:** |

To evaluate the Bayesian posterior fit, we plot posterior predictive regression lines by taking regression parameters from the posterior distribution and plotting a regression line for each. The function plot\_posterior\_predictive\_glm () plots the predicted posterior lines of a Generalized Linear Model (GLM).

The black line corresponds to the OLS fit, whereas the blue lines correspond to the Bayesian posterior fit lines.

It can be seen that the Bayesian estimate of the parameters correctly corresponds to the frequentist estimates.

To check the posterior distribution of the target variable, calories, against a specified input point, say 20-minute duration, we use the following Python script.

|  |
| --- |
| 1. specific\_point = 15   # this corresponds to the value in terms of minutes exercised 2. bayes\_prediction = linear\_trace['Intercept'] + linear\_trace['slope'] \* specific\_point  5. # plotting the results 6. plt.figure(figsize = (8, 8)) 7. plt.style.use('fivethirtyeight') 8. sns.kdeplot(bayes\_prediction, label = 'Bayes Posterior Prediction') 9. plt.vlines(x = ols\_coefs[0] + ols\_coefs[1] \* specific\_point, 10. ymin = 0, ymax = 2.5, 11. label = 'OLS Prediction', 12. colors = 'red', linestyles='--') 13. plt.legend(); 14. plt.xlabel('Calories Burned', size = 15), plt.ylabel('Probability Density', size = 15); 15. plt.title(f'Posterior Prediction for {specific\_point} Minutes', size = 16)   **Output:** |

The output plot shows the Bayesian posterior prediction as a Normal curve along with the frequentist estimate for comparison. The peak of the Bayesian prediction is quite close to the frequentist estimate. However, the posterior distribution by the Bayesian inference reports the spread (standard deviation) of the calories burnt to indicate the variability of our estimate. This is a feature not offered by the frequentist estimates because the estimated mean is considered fixed and reported as a single point in the frequentist inference.

**Answers to Exercise Questions**

**Chapter 1**

Question 1: A

Question 2: C

Question 3: B

Question 4: A

Question 5: B

Question 6: C

Question 7: B

Question 8: C

Question 9: C

Question 10: C

**Chapter 2**

Question 1: B

Question 2: A

Question 3: C

Question 4: C

Question 5: C

Question 6: D

Question 7: B

Question 8: C

Question 9: D

Question 10: D

**Chapter 3**

Question 1: C

Question 2: A

Question 3: B

Question 4: B

Question 5: C

Question 6: C

Question 7: A

Question 8: C

Question 9: B

Question 10: B

Question 11: B

Question 12: B

**Chapter 4**

Question 1: D

Question 2: B

Question 3: B

Question 4: C

Question 5: C

Question 6: D

Question 7: C

Question 8: A

**Chapter 5**

Question 1: C

Question 2: D

Question 3: B

Question 4: A

Question 5: D

Question 6: B

Question 7: D

Question 8: C

**Chapter 6**

Question 1: B

Question 2: A

Question 3: B

Question 4: C

Question 5: B

Question 6: D

Question 7: A

**Chapter 7**

Question 1: A

Question 2: B

Question 3: A

Question 4: A

Question 5: A

Question 6: C

**Chapter 8**

Question 1: C

Question 2: D

Question 3: B

Question 4: C

Question 5: A

Question 6: B

Question 7: B

Question 8: C

Question 9: A

Question 10: B